

Modeling and Optimization of High Frequency Magnetic Components

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Outline

- Basic concepts and classical design
- High frequency effects
- Modeling review
- Advanced design and optimization process
- Application to converters
- Summary of design guidelines

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***Basic concepts
and
classical design***

Basic concepts

➤ Main applications of Magnetic components:

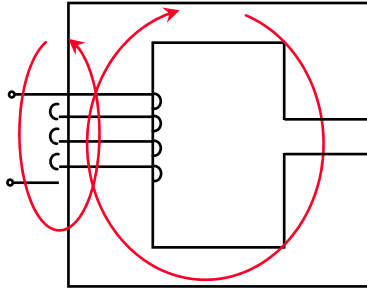
- ✓ Galvanic isolation
- ✓ Adjust voltage levels
- ✓ Filters
- ✓ Resonant inductors
- ✓ Measurement for feedback and protections
- ✓ Pulse transformers
- ✓ ...

... but basically, they produce:

- ENERGY TRANSFER
- ENERGY STORAGE

... and unfortunately, also LOSSES

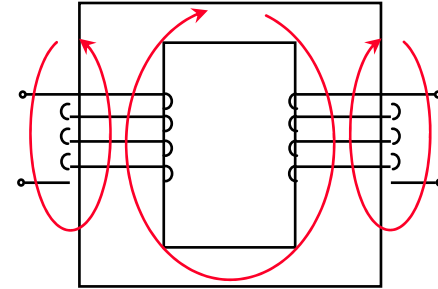
Inductor



➤ Core:

- ✓ **Flux: Energy link**
- ✓ **Non-linearity and hysteresis**
- ✓ **Losses:**
 - × Hysteresis
 - × eddy currents
 - × residual

Transformer

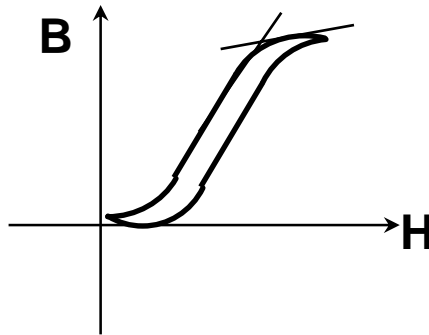


➤ Windings:

- ✓ **Electrical terminals**
- ✓ **Losses**
 - × DC losses
 - × AC losses
- ✓ **Winding strategy affects strongly to performance**

PERMEABILITY

$$B = \mu H$$

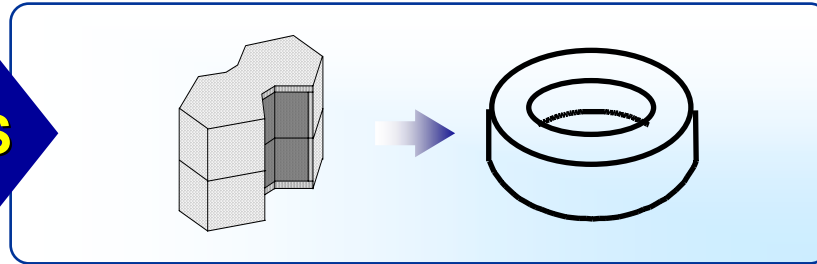


Permeability = Slope
NOT LINEAR

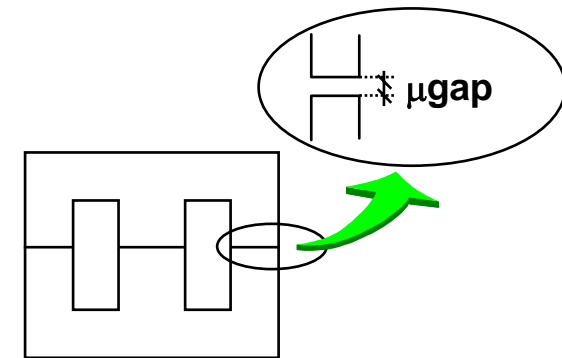
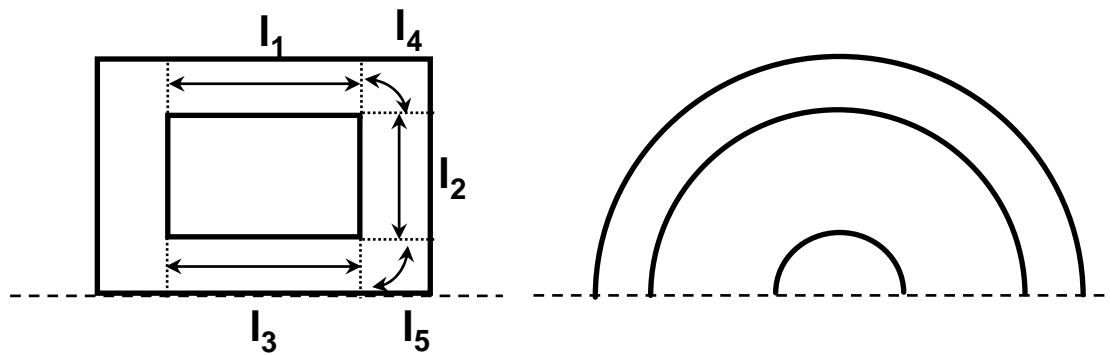
RELUCTANCE

$$\mathfrak{R} = \frac{1}{\mu} \cdot \frac{\text{length}}{\text{Area}}$$

EFFECTIVE VALUES



EXAMPLE: POT CORE

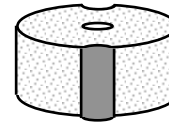
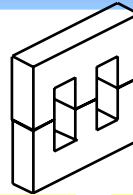
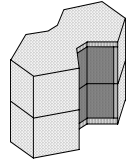


$$A_e = \frac{C_1}{C_2}; \quad V_e = \frac{C_1^3}{C_2^2}; \quad l_e = \frac{C_1^2}{C_2}$$

$$C_1 = \sum_1^5 \frac{l_i}{A_i} mm^{-1} \quad C_2 = \sum_1^5 \frac{l_i}{A_i^2} mm^{-3}$$

μ_e depends on the "microgap" (2.5 μm) due to the mechanization procedure

CORES



Shapes

RM, POT, EE, EI, PQ, TOROID...

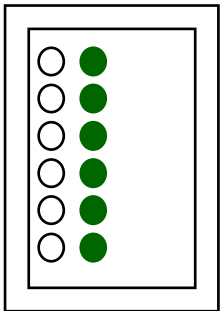
- ✓ Effective values
- ✓ Magnetic coupling
- ✓ Thermal management

Materials

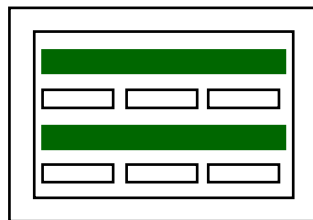
3F3, 3C85, 3C90, N67, N47...

- ✓ Core losses
- ✓ Reluctance and conductivity
- ✓ Maximum flux density

WINDINGS

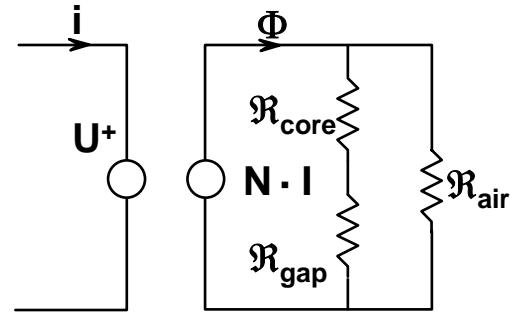
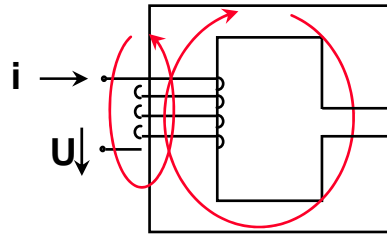


Concentric



Top down

Interleaving techniques can be applied
in both strategies



Some flux “leaks”, that affects to EMI , not to L

Duality principle

Electric	Magnetic
U	NI
I	Φ
R	ℜ
ρ	1/μ

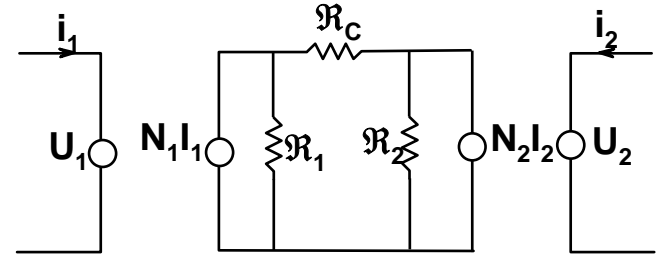
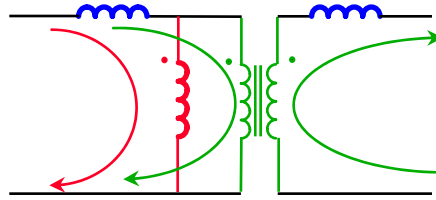
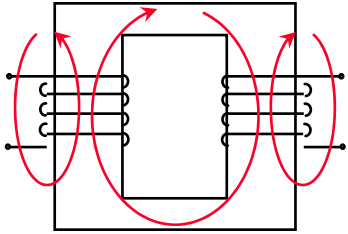
Main relationships

$$U = L \frac{\Delta i}{\Delta t} = N \frac{\Delta \Phi}{\Delta t}$$

$$L = N^2 A_L$$

Basic concepts

Transformer



➤ Ideal Transformer:

$$\frac{d\phi}{dt} = \frac{u_1}{n_1} = \frac{u_2}{n_2} = \dots = \frac{u_p}{n_p}$$
$$n_1 \cdot i_1 = n_2 \cdot i_2$$

No Energy Storage !!
No Losses !!

➤ Real Transformer:

✓ Common Energy:

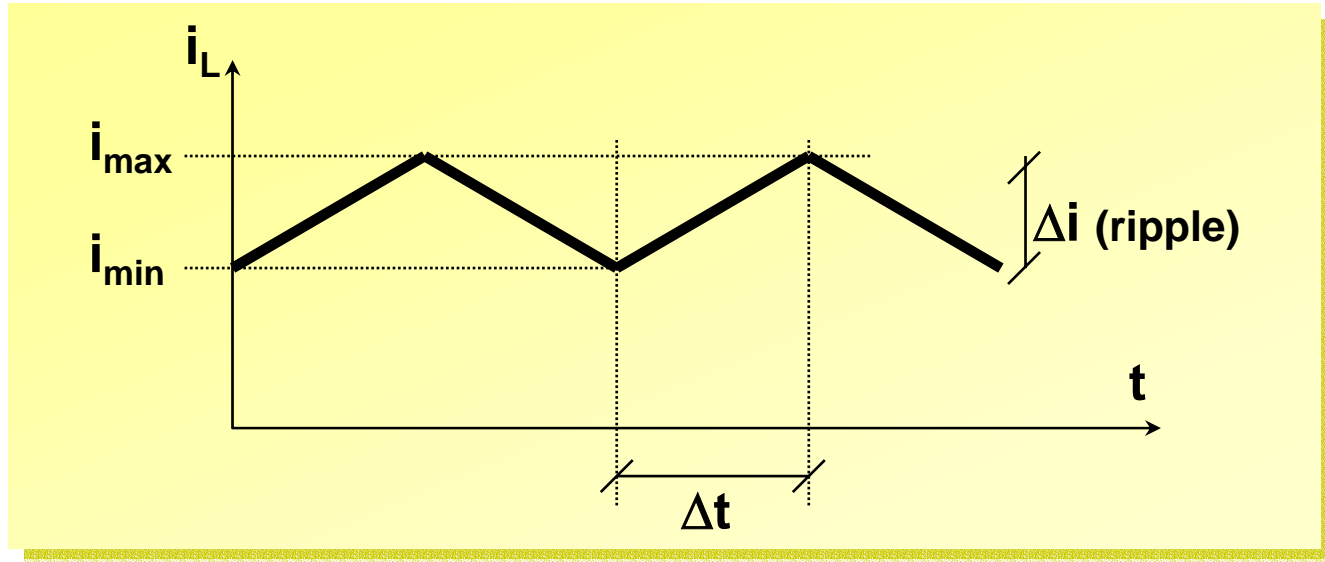
$$L_{mag, i} = \frac{n_i^2}{\mathcal{R}}$$
$$\sum ni = \Phi \cdot \mathcal{R}$$

in any winding

✓ Self energy

✓ Conductor losses

Note difference between
"transferred energy" and "stored energy"



$$U = L \frac{\Delta i}{\Delta t}$$



$$L = \frac{U \cdot \Delta t}{\Delta i}$$

U = Voltage applied to the inductor during Δt

1.

CORE SHAPE

Depends on the application (see data books)

2.

CORE SIZE

Depends on the power (see data books)

3.

CORE MATERIAL

Depends on the frequency (see data books)

4.

CONDUCTOR TYPE

Depends on the frequency (skin depth)

Solid wire: low frequency

Litz wire and foils: high frequency

5.

CONDUCTOR AREA

Depends on the required copper losses.
The maximum current density should be fixed with the conductor area

The number of turns should be calculated in order to keep flux density under the saturation value

$$L \frac{\Delta i}{\Delta t} = N \frac{\Delta \Phi}{\Delta t} \Rightarrow L \Delta i = N \cdot A_e \cdot \Delta B \Rightarrow$$

$$\Rightarrow L \cdot i_{max} = N \cdot A_e \cdot B_{max} \Rightarrow$$

$$N = \frac{L \cdot i_{max}}{A_e \cdot B_{max}}$$

This procedure guarantees that the inductor will not be saturated

$$L = \frac{N^2}{\mathfrak{R}_T} = N^2 \cdot A_L$$

$$\mathfrak{R}_T = \frac{N^2}{L}$$

$$A_L = \frac{1}{\mathfrak{R}_T}$$

- \mathfrak{R}_T is the total reluctance of the magnetic circuit.
- This reluctance should be achieved using:
 - ✓ Ferrite core + air gap
 - ✓ A material with distributed gap (low permeability) like iron powder

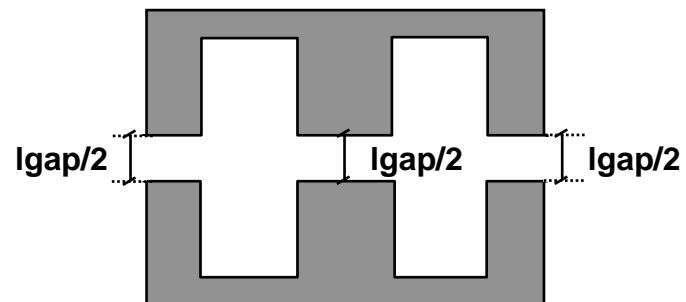
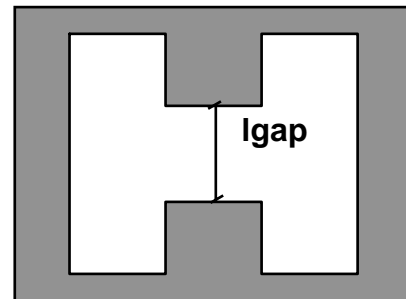
$$\mathfrak{R}_T = \mathfrak{R}_{ferrite} + \mathfrak{R}_{air} = \underbrace{\frac{1}{\mu_o \mu_e} \cdot \frac{l_e}{A_e}}_{1/A_L} + \frac{1}{\mu_o} \cdot \frac{l_{gap}}{A_e}$$

(ferrite without gap)

$$\mathfrak{R}_T = \frac{1}{A_L} + \frac{1}{\mu_o} \cdot \frac{l_{gap}}{A_e}$$

$$\frac{1}{A_{L_T}} = \frac{1}{A_L} + \frac{l_{gap}}{\mu_o \times A_e}$$

$$l_{gap} = \mu_o A_e \left[\frac{1}{A_{L_T}} - \frac{1}{A_L} \right]$$



1. **CORE SHAPE** Depends on the application (see data books)

2. **CORE SIZE** Depends on the power (see data books)

3. **CORE MATERIAL** Depends on the frequency (see data books)

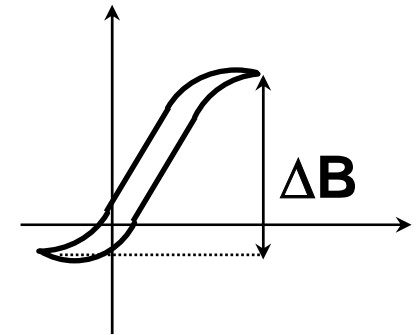
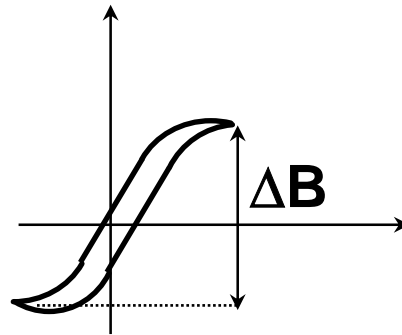
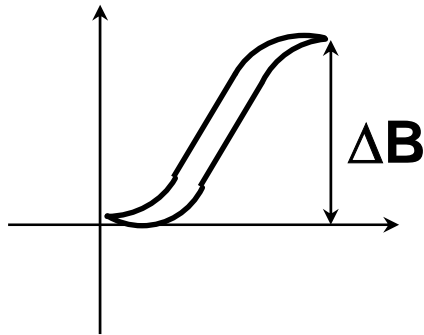
4. **CONDUCTOR TYPE** Depends on the frequency (skin depth)

Solid wire: low frequency

Litz or foils wire: high frequency

5. **CONDUCTOR AREA** In transformers:
Copper losses = Core losses

Number of turns calculated to keep maximum flux density or core losses under an appropriate value



$$U_1 = N_1 \cdot \frac{\Delta \Phi}{\Delta t} = N_1 \cdot A_e \cdot \frac{\Delta B}{\Delta t}$$



$$N_1 = \frac{U_1 \Delta t}{A_e \Delta B}$$

$$a = \frac{N_1}{N_2} \Rightarrow N_2 = \frac{N_1}{a}$$

Magnetizing inductance

$$L_{m1} = \frac{N_1^2}{\mathfrak{R}} = N_1^2 \cdot A_L \rightarrow \begin{matrix} \uparrow L_m \\ \downarrow i_{mag} \end{matrix}$$

Losses

CORE

Data book abacus

COPPER

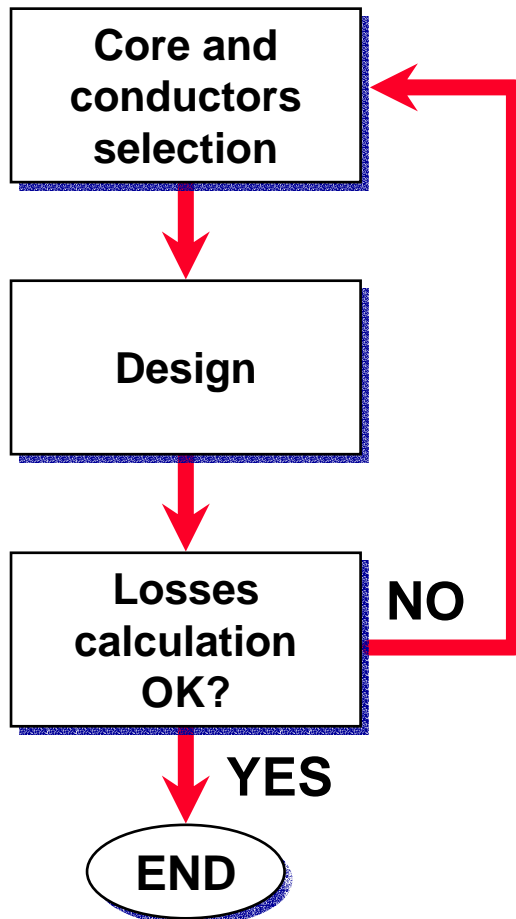
$$P = R \cdot I^2$$

$$R = \rho \frac{l}{S}$$

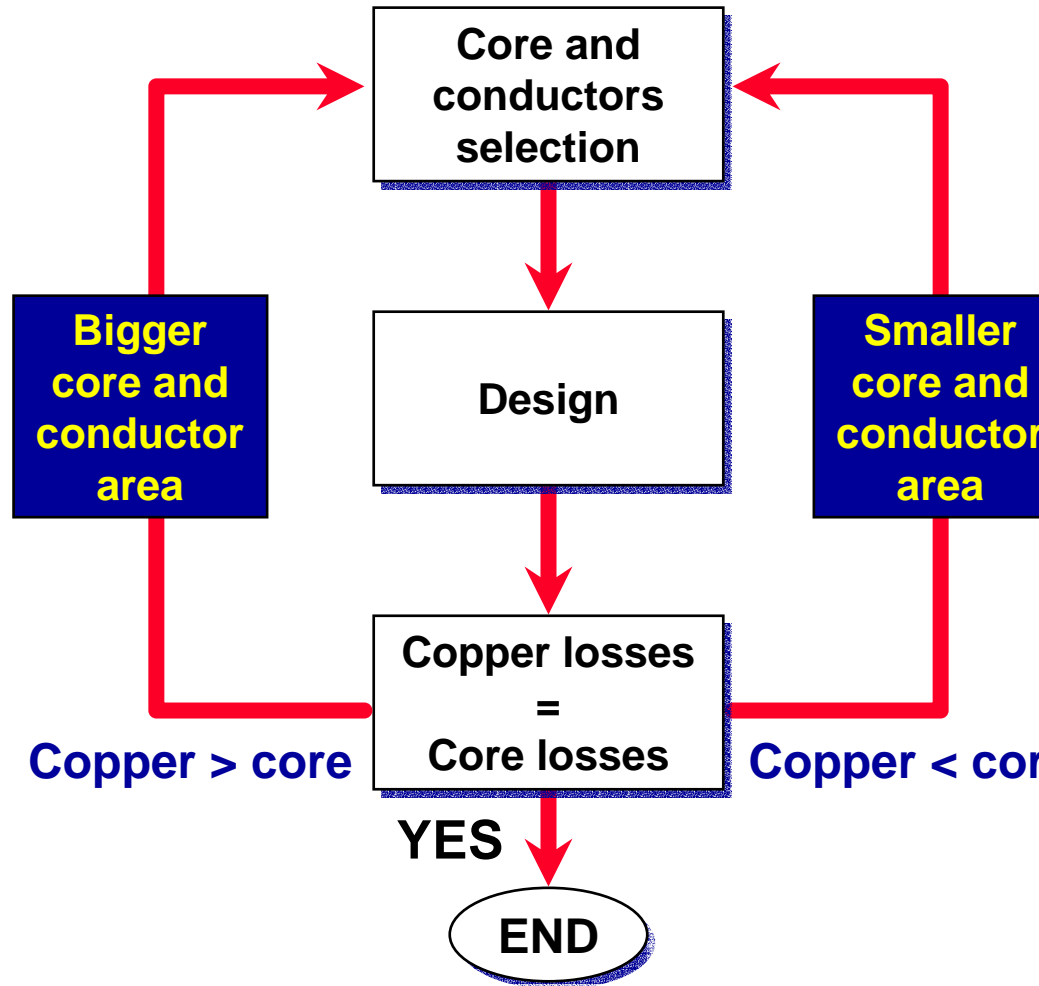
Losses in core and copper should be equal

Design procedure

Inductors



Transformers



Inductor

Transformer

Keeping L constant

**Increasing
Core Size**

- ↓ Number of turns
- ↓ Air gap
- ↓ Copper losses
- ↑ Core losses

Keeping n_1/n_2 constant

**Increasing
Core Size**

- ↓ Number of turns
- ↓ Copper losses
- ↓ L_{mag}
- ↑ Core losses

2

High Frequency effects

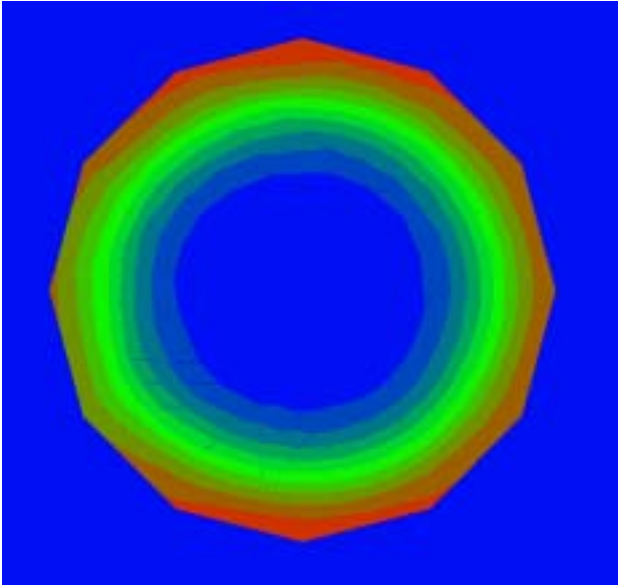
Skin

Proximity

Gap

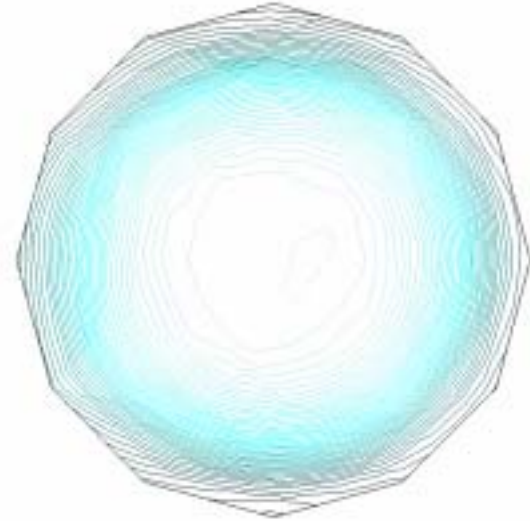
Interleaving

Skin effect



Shaded drawing

150kHz



Lined drawing

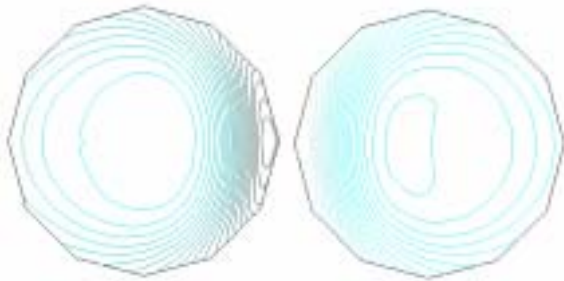
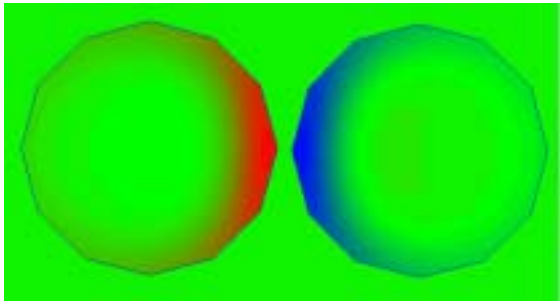
Skin depth

$$\delta = \frac{1}{\sqrt{2\pi f \mu_0 \sigma}}$$

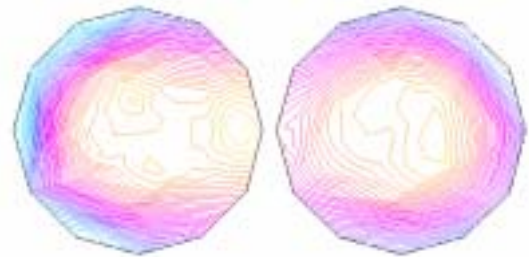
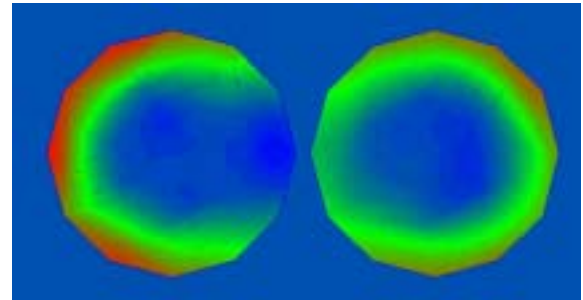
At high frequency, current tends to flow through the surface

Proximity effect

Opposite currents

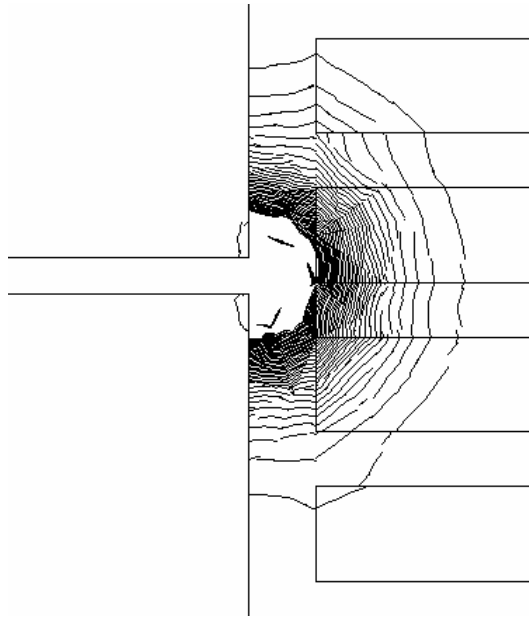


Parallel currents

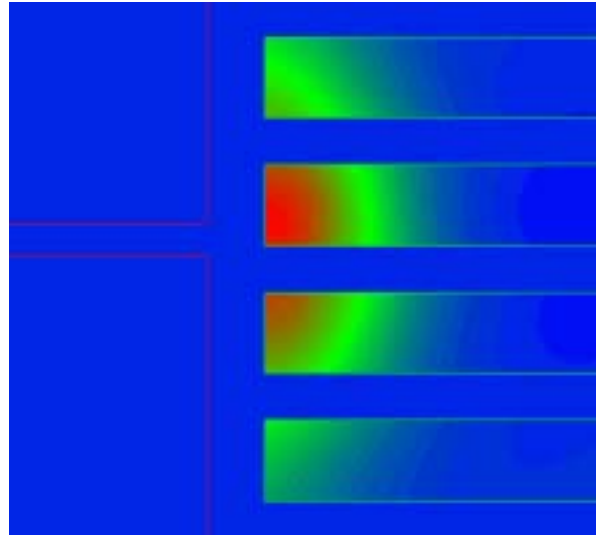


- ✓ Opposite currents tend to flow together
- ✓ Parallel currents tend to separate

Gap effect



Fringing flux

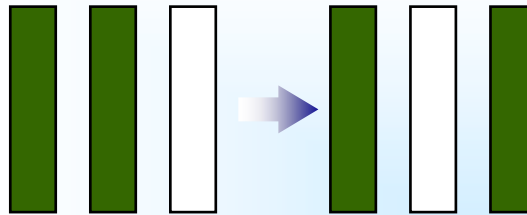


Current density distribution

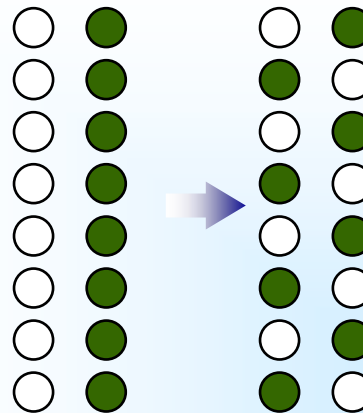
Fringing flux affects to conduction losses

Interleaving

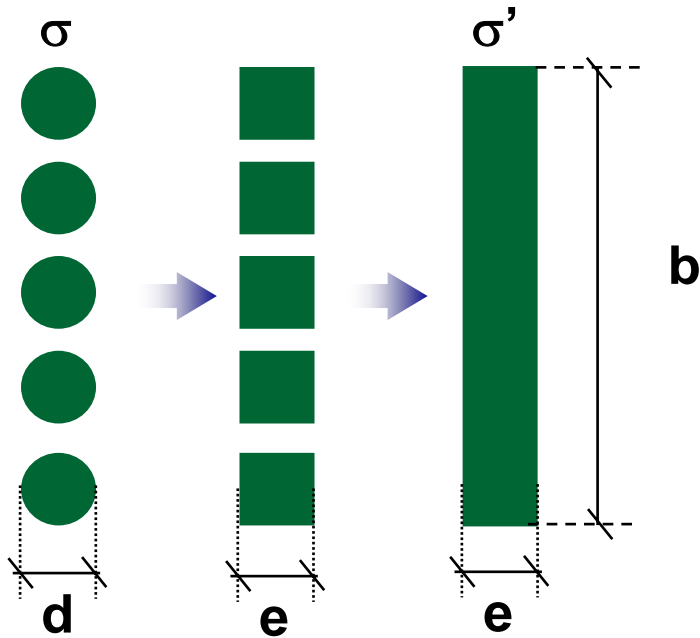
INTERWINDING



INTRAWINDING

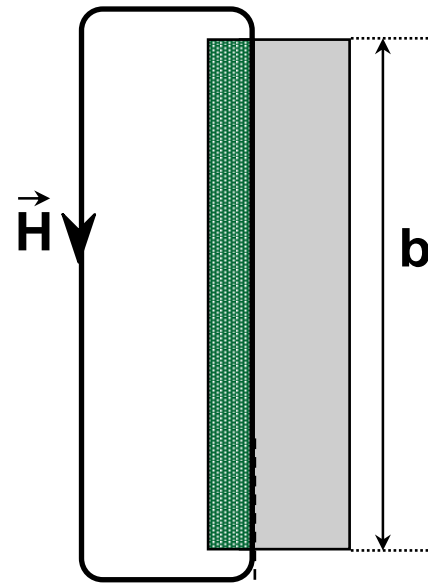


Current sheet



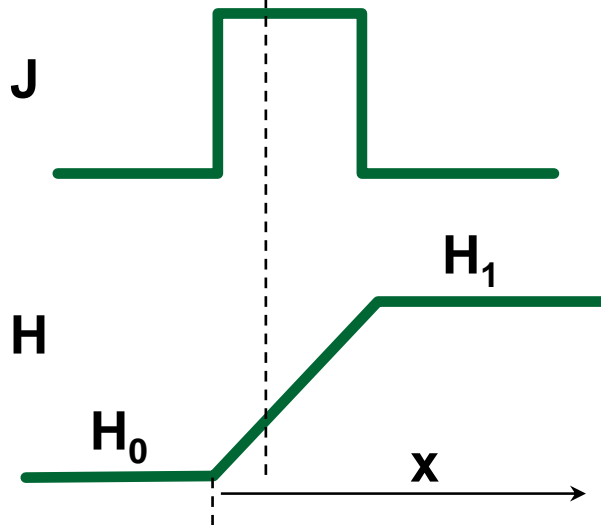
$$e = \sqrt{\frac{\pi}{4} \cdot d^2}$$
$$\eta = \frac{e \cdot N}{b} \quad \sigma' = \sigma \cdot \eta$$

Current sheet with same equivalent resistance



$$\oint \vec{H} \cdot d\vec{l} = n \cdot I$$

$$H(x) \cdot b = H_0 \cdot b + J \cdot x \cdot b$$

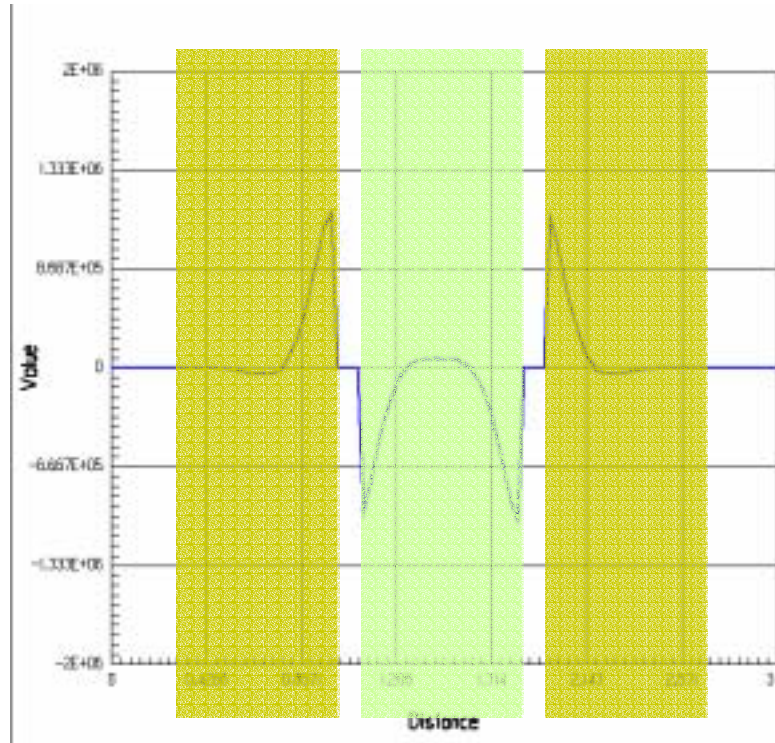
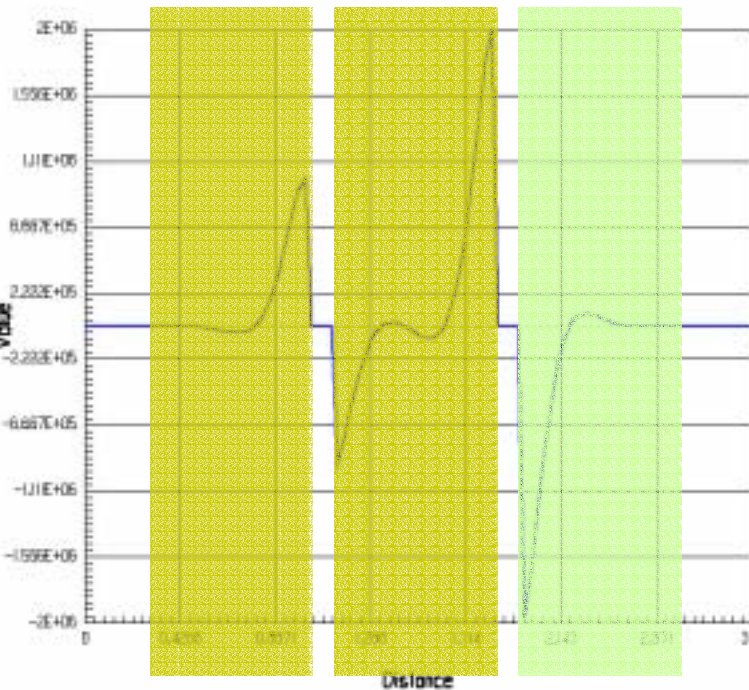


$$H(x) = H_0 + J \cdot x$$

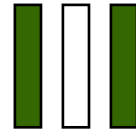
Interleaving

Reduction of the AC resistance
CURRENT DENSITY (J)

ONLY
in AC

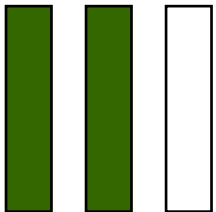
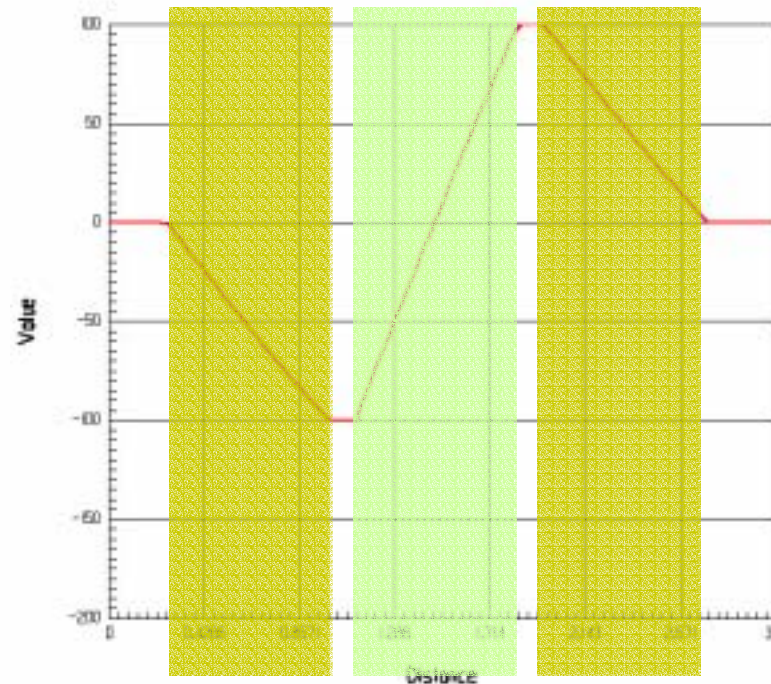
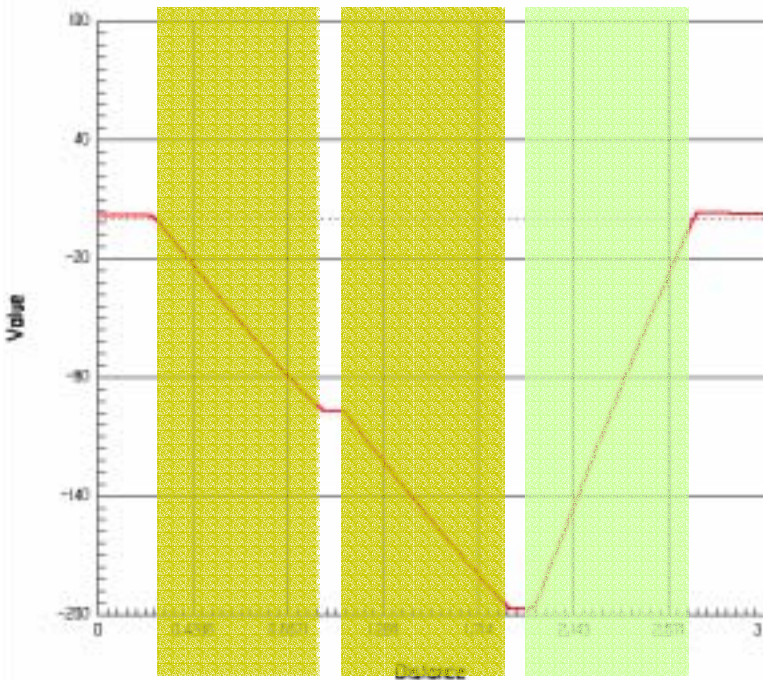


J distribution improves

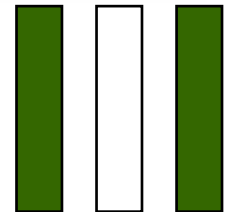


Interleaving

Reduction of the leakage inductance
MAGNETIC FIELD (H)

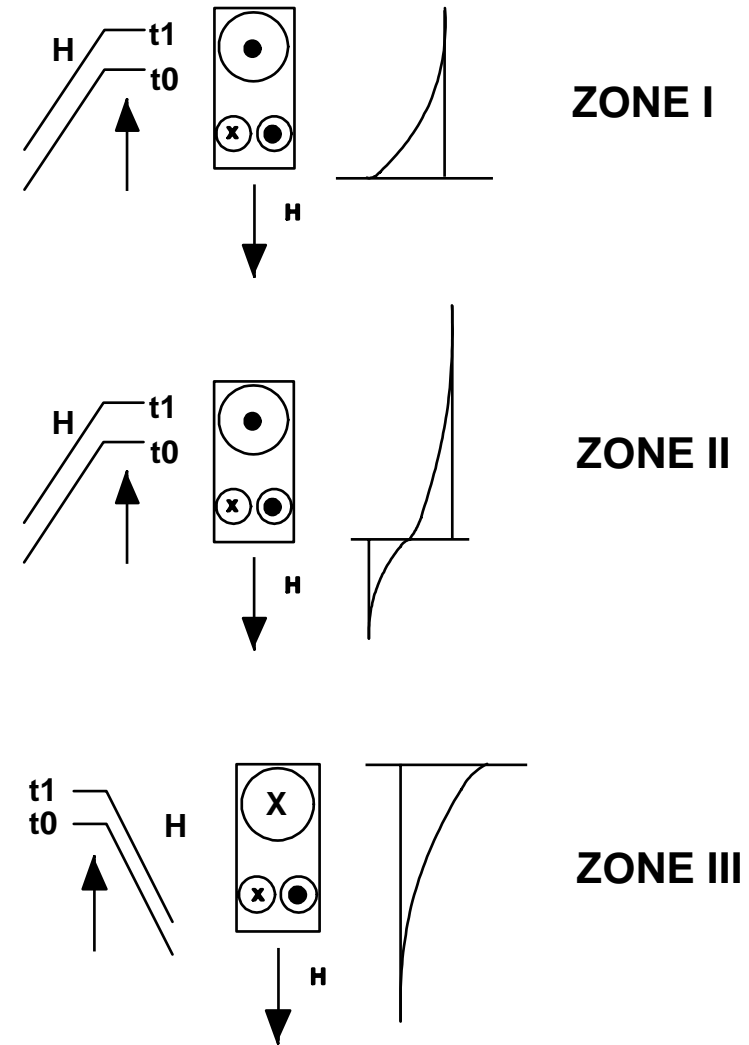
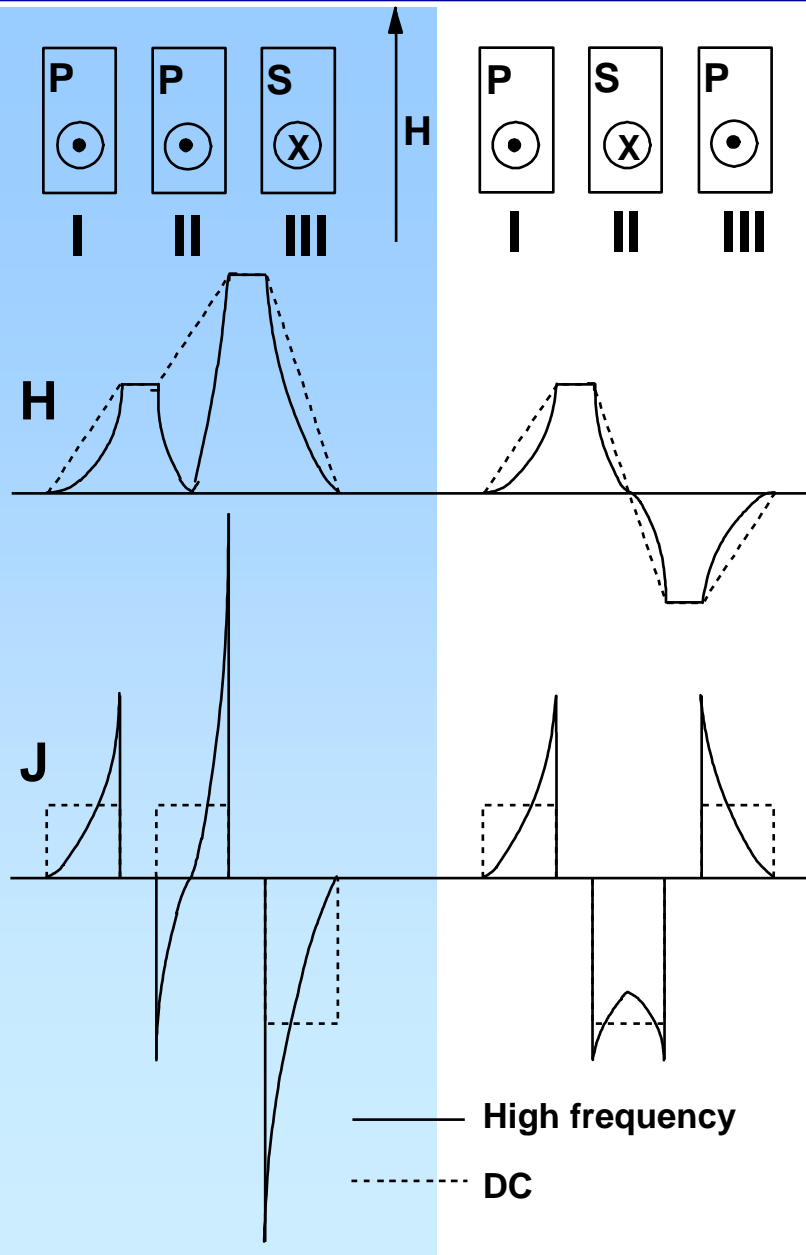


H distribution improves



Interleaving

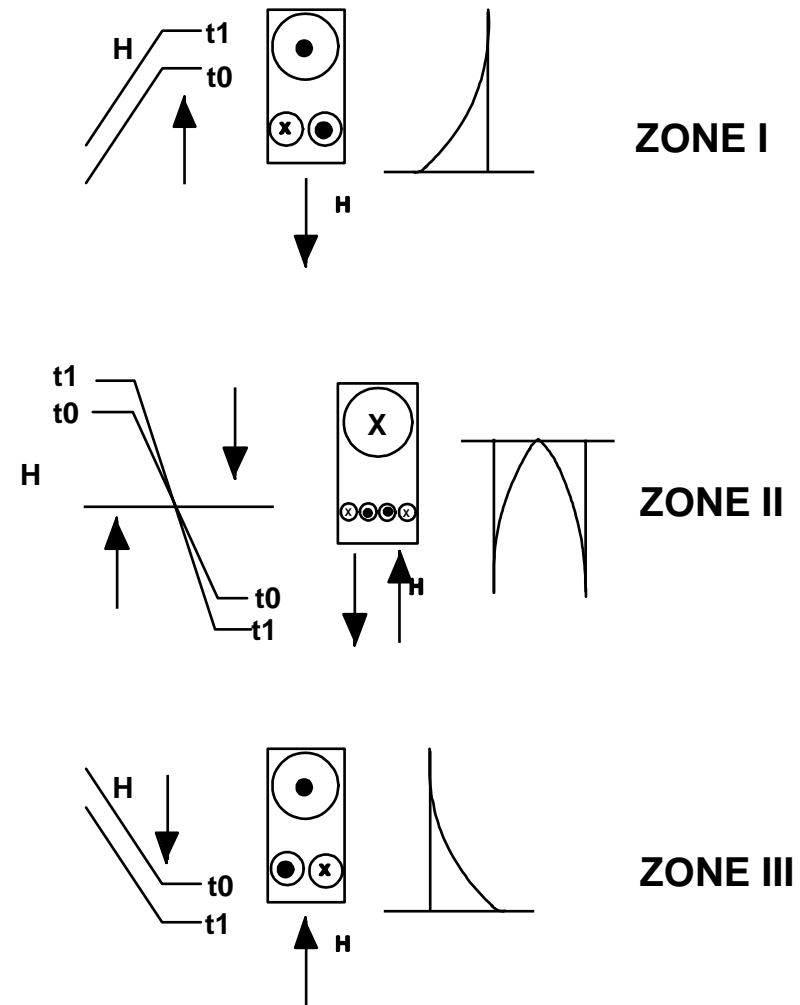
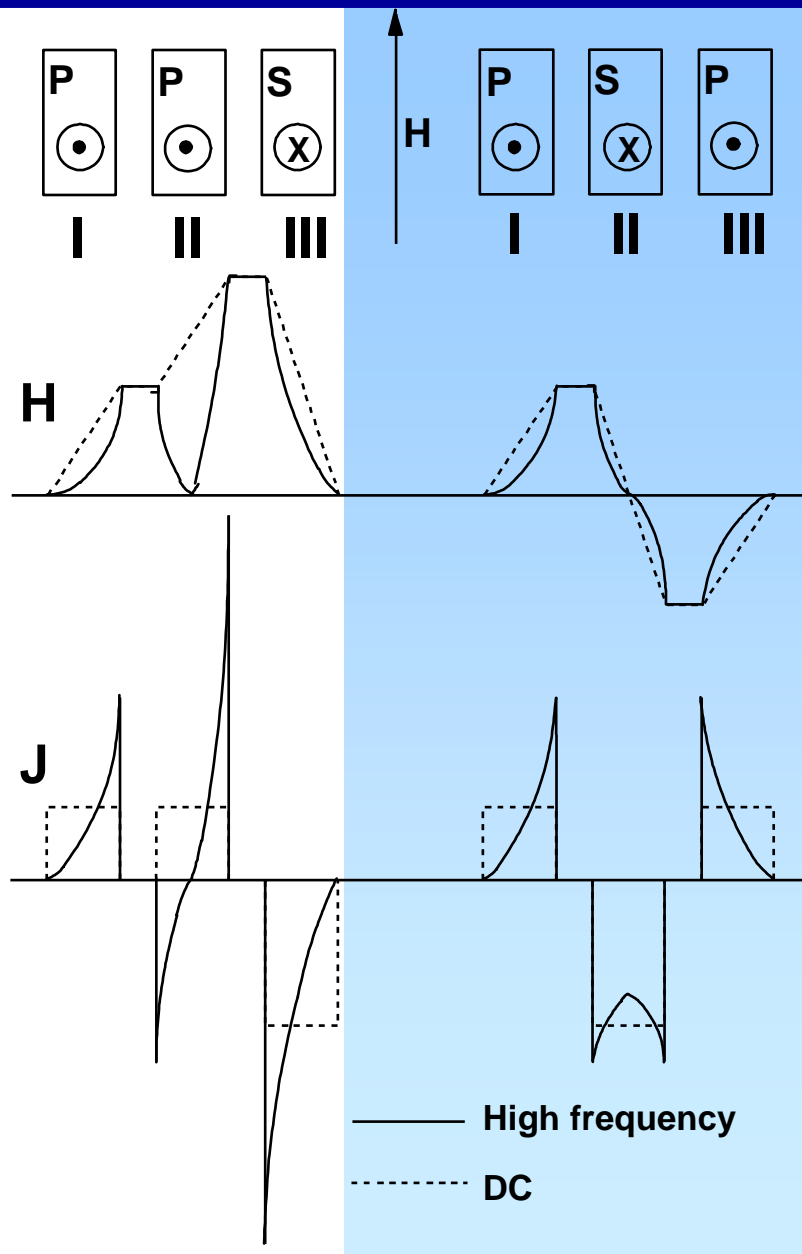
Current layers



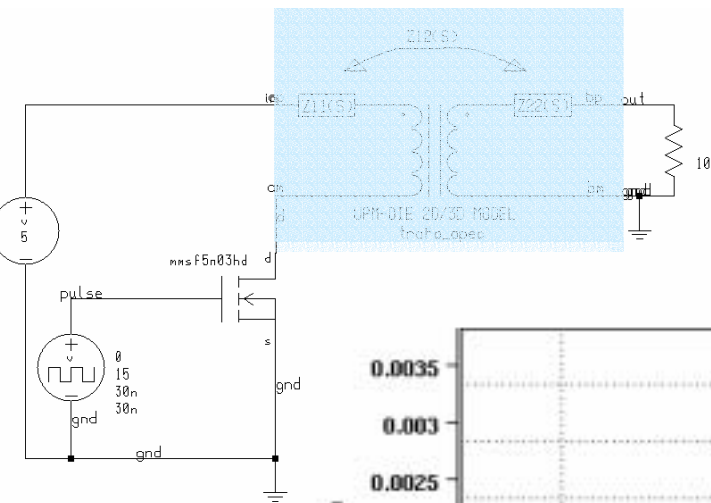
Without interleaving

Interleaving

Current layers



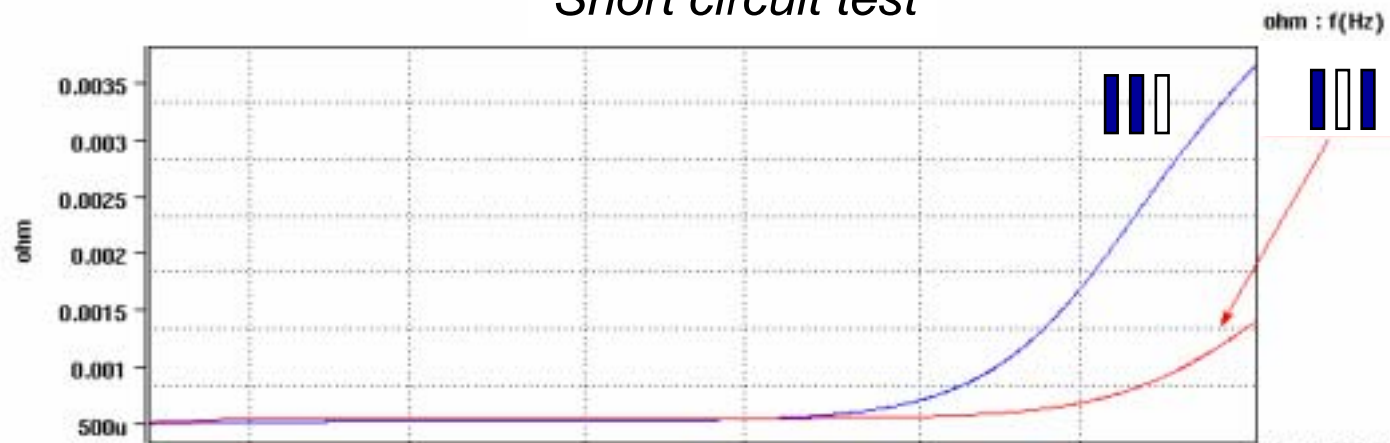
With interleaving



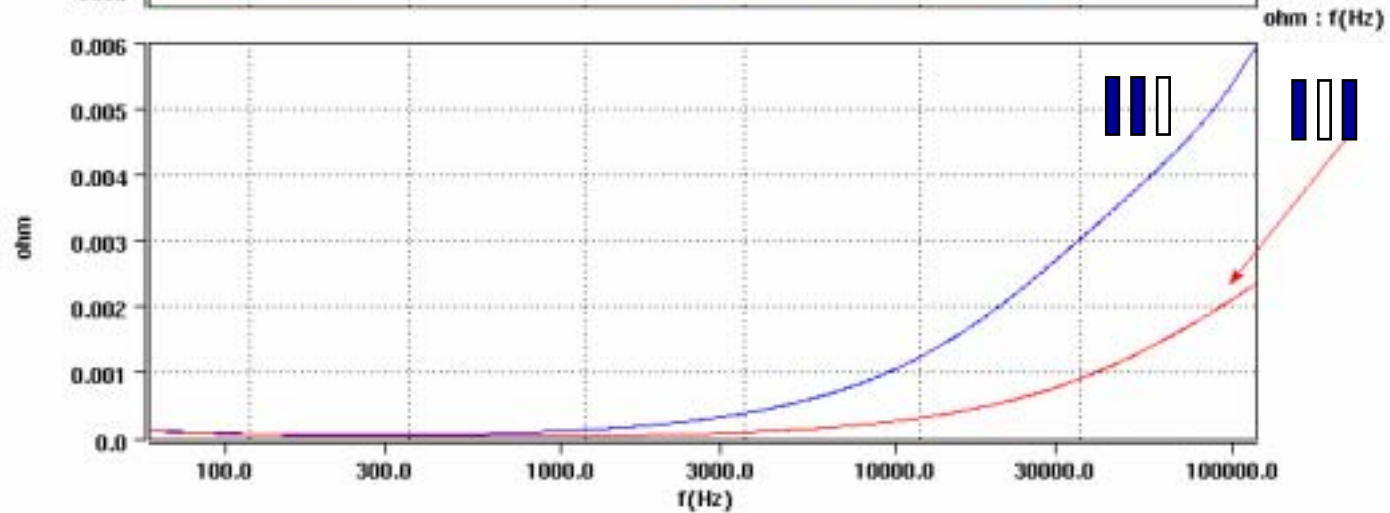
Frequency behavior

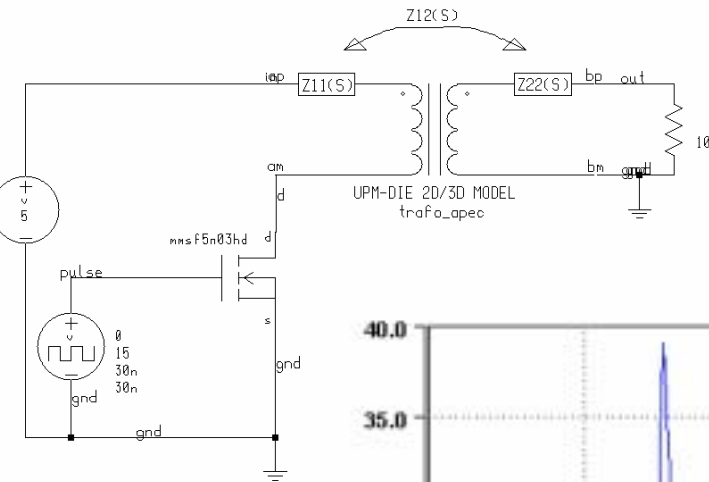
Short circuit test

Resistance



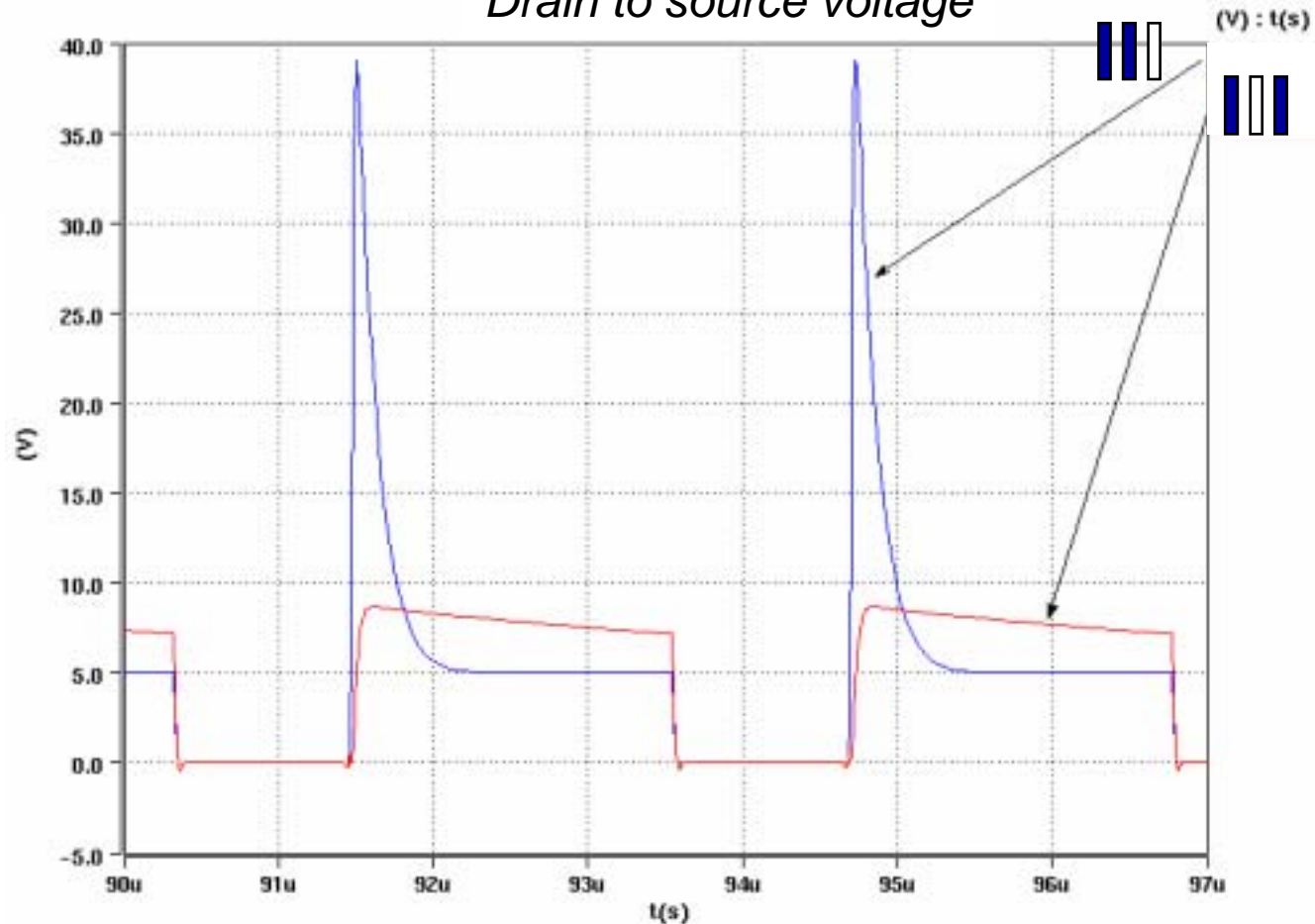
Reactance

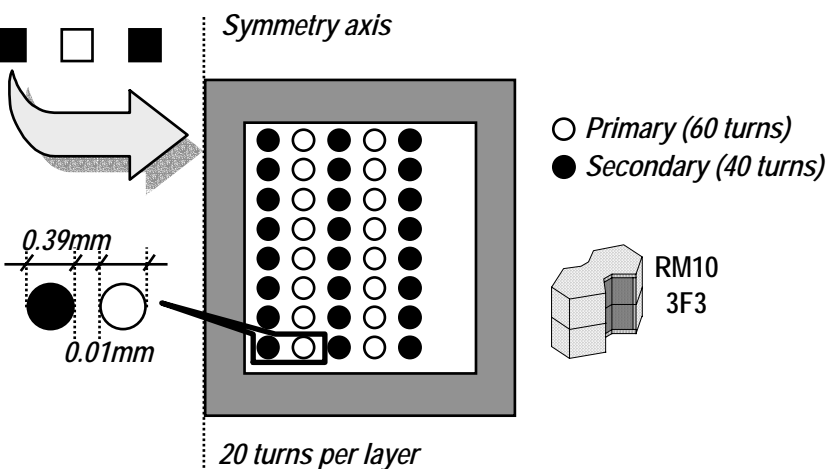




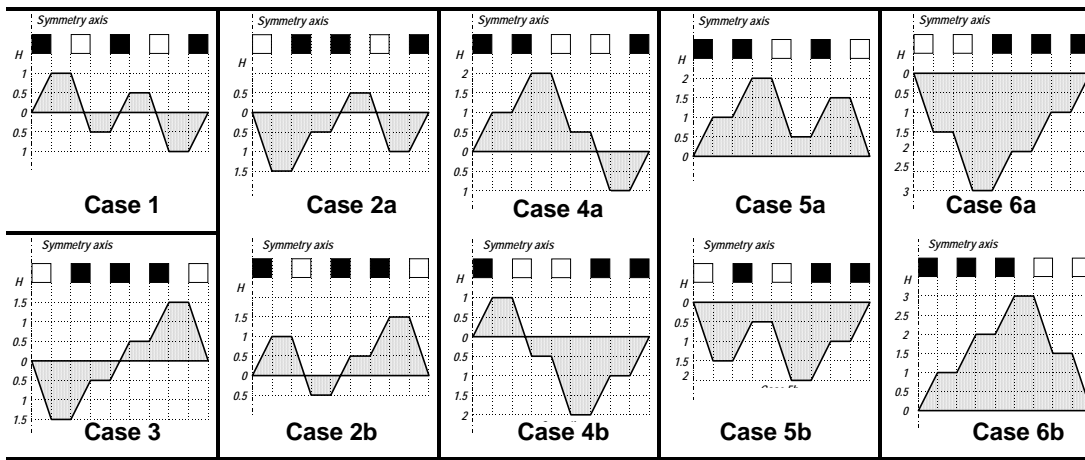
Voltage spikes due to leakage inductance

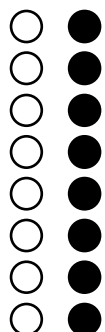
Drain to source voltage



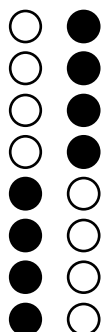


Case	R (Ω) @200kHz	L _{leakage} (μ H) @200kHz
1	1.1	1.4
2a	1.5	1.9
2b	1.6	2.0
3	2.0	2.8
4a	2.4	3.5
4b	2.5	3.6
5a	2.8	4.2
5b	2.8	4.3
6a	5.7	9.5
6b	5.9	9.9

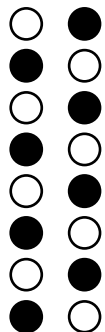




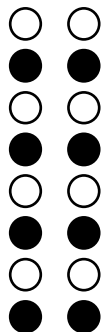
CASE A



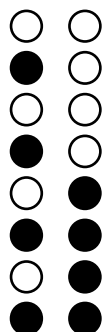
CASE B



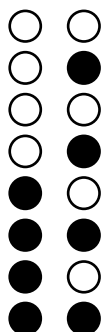
CASE C



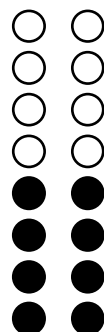
CASE D



CASE E



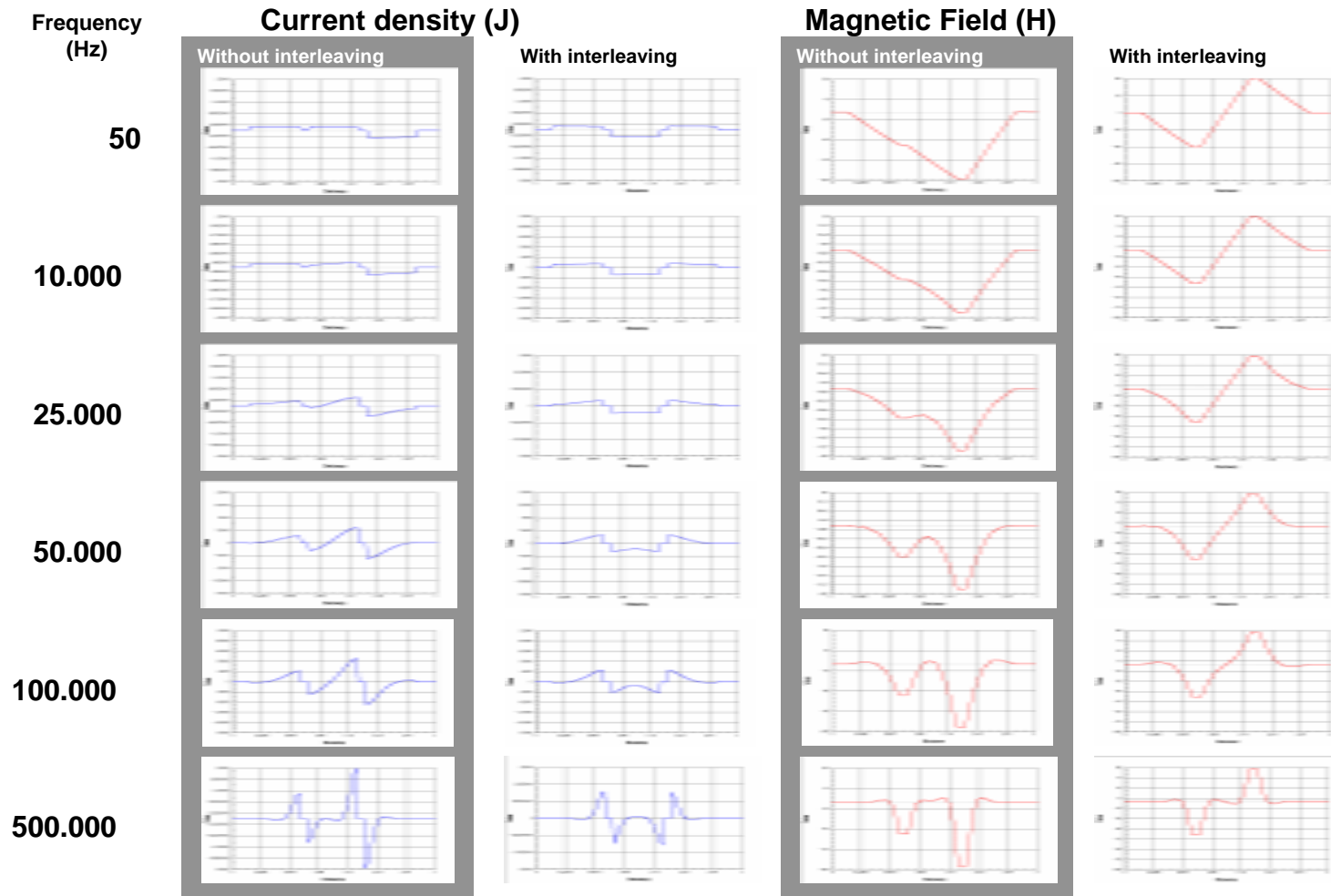
CASE F



CASE G

Case	$L_{\text{leakage}} (\mu\text{H})$ @200kHz	$L_{\text{leakage}} (\mu\text{H})$ @2MHz
A	0.475	0.248
B	0.432	0.231
C	0.130	0.087
D	0.276	0.185
E	4.144	2.827
F	4.239	2.857
G	13.979	9.496

Interleaving



➤ Basic concepts

➤ High frequency effects

➤ **Modeling**

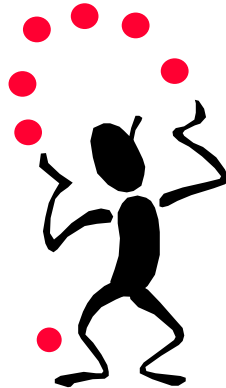
➤ Advanced design

➤ Application to converters

Mr Designer at UPM lab



before...



...after

Mr Designer
learns to
design



Mr Designer
has a problem



Mr Designer
finds a solution



Mr Designer
can use it !



Mr Designer
succeeds !!



What is the real dimension of Modeling...?

Do I make
simulations?

Do I trust
them?

if not, are magnetic
component models
the reason?

Do I need a model...

...or just design
guidelines?

Others or MY OWN
design guidelines?

I need MY OWN
QUANTIFICATION!!



What is the real dimension of Modeling...?

How many
modeling works
have I read?

How many
of them
am I using?

Do I wish to
IMPLEMENT,
or **just USE** them?

MODEL

...tool to obtain
MY OWN
design guidelines

...gate to
simulation

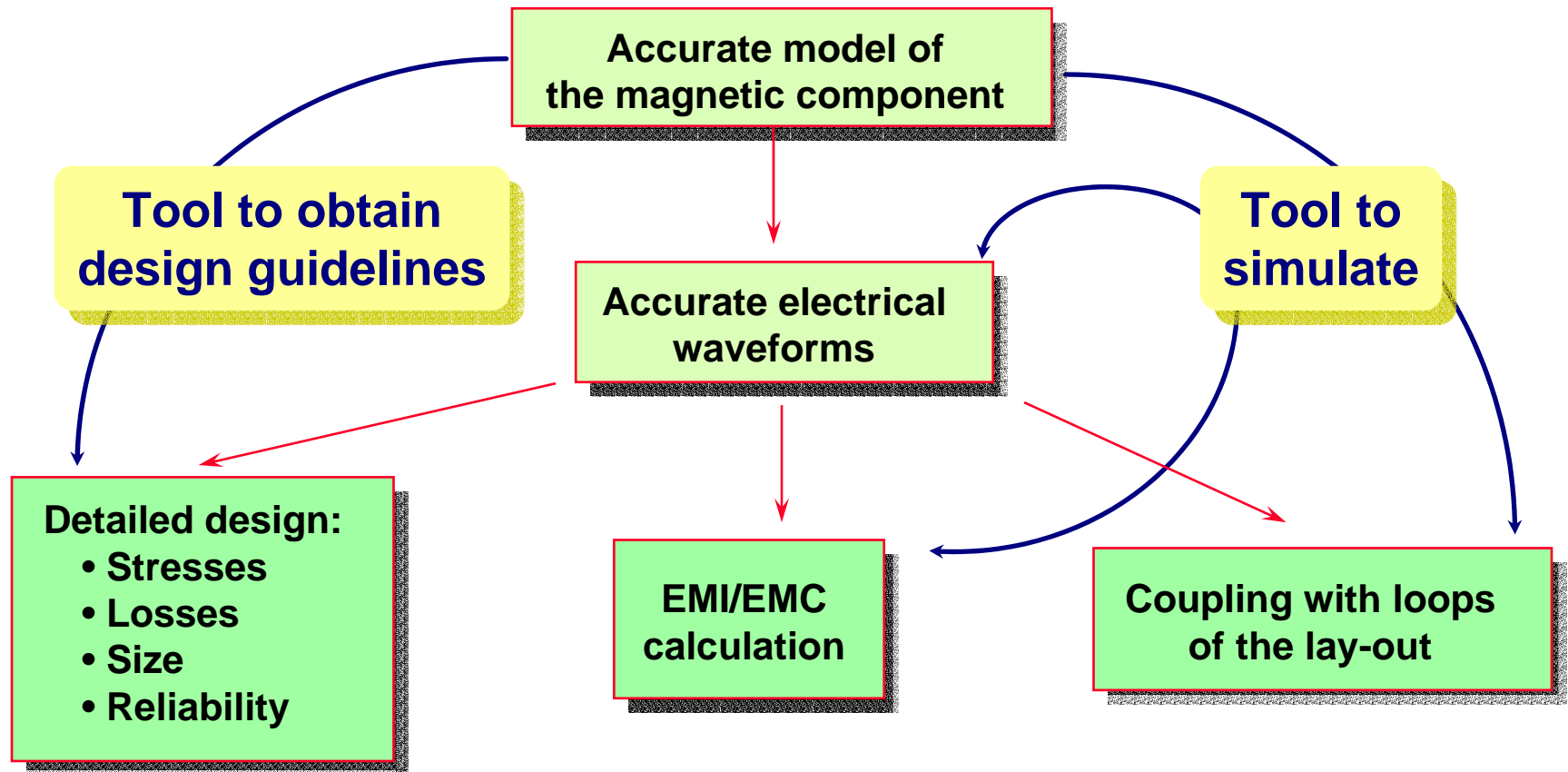
Modeling Review

Basic concepts

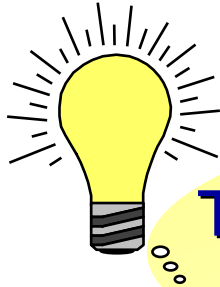
Analytical (1D effects)

FEA tools (2D/3D effects)

Basic concepts



Basic concepts



To obtain an accurate model, *physical effects* must be deeply analyzed

Distribution
of

Magnetic fields
Electric fields
Current
Voltage

depend
strongly on

Frequency
Waveform
(harmonic content, SMPS)
Geometry & Materials

Practical
approach

Maxwell equations

1D problem: Analytical
2D/3D problem: FEA tool

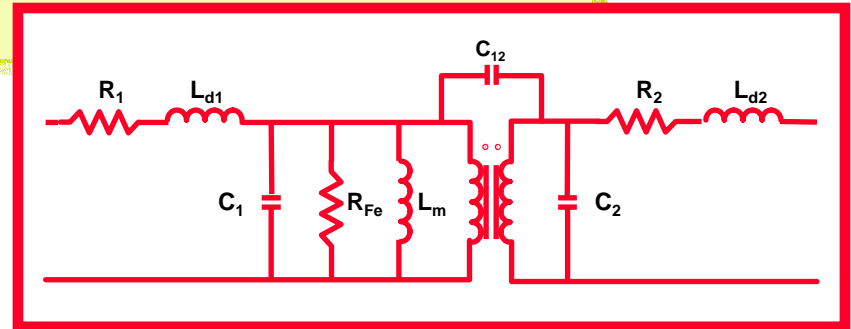
Non linear problem

Windings are linear!!

Basic concepts

CLASSICAL MODEL

- Frequency and geometry effects neglected (only for sinusoidal waveforms)
- Measurement needed to calculate parameters
- Dimensional effects neglected

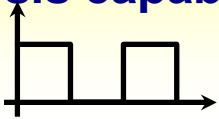


OTHER APPROACHES

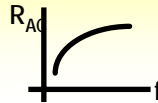
- Analytical approaches in simple cases or using rough approximations
- FEA is used to “see” the fields but no model is usually generated

Main effects to be modeled

Non sinusoidal
analysis capabilities



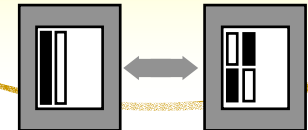
AC resistance



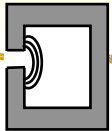
AC inductance



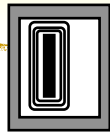
Winding strategy
influence



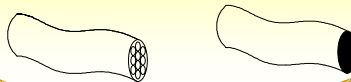
Gap effect



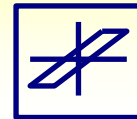
End effects



Conductor type



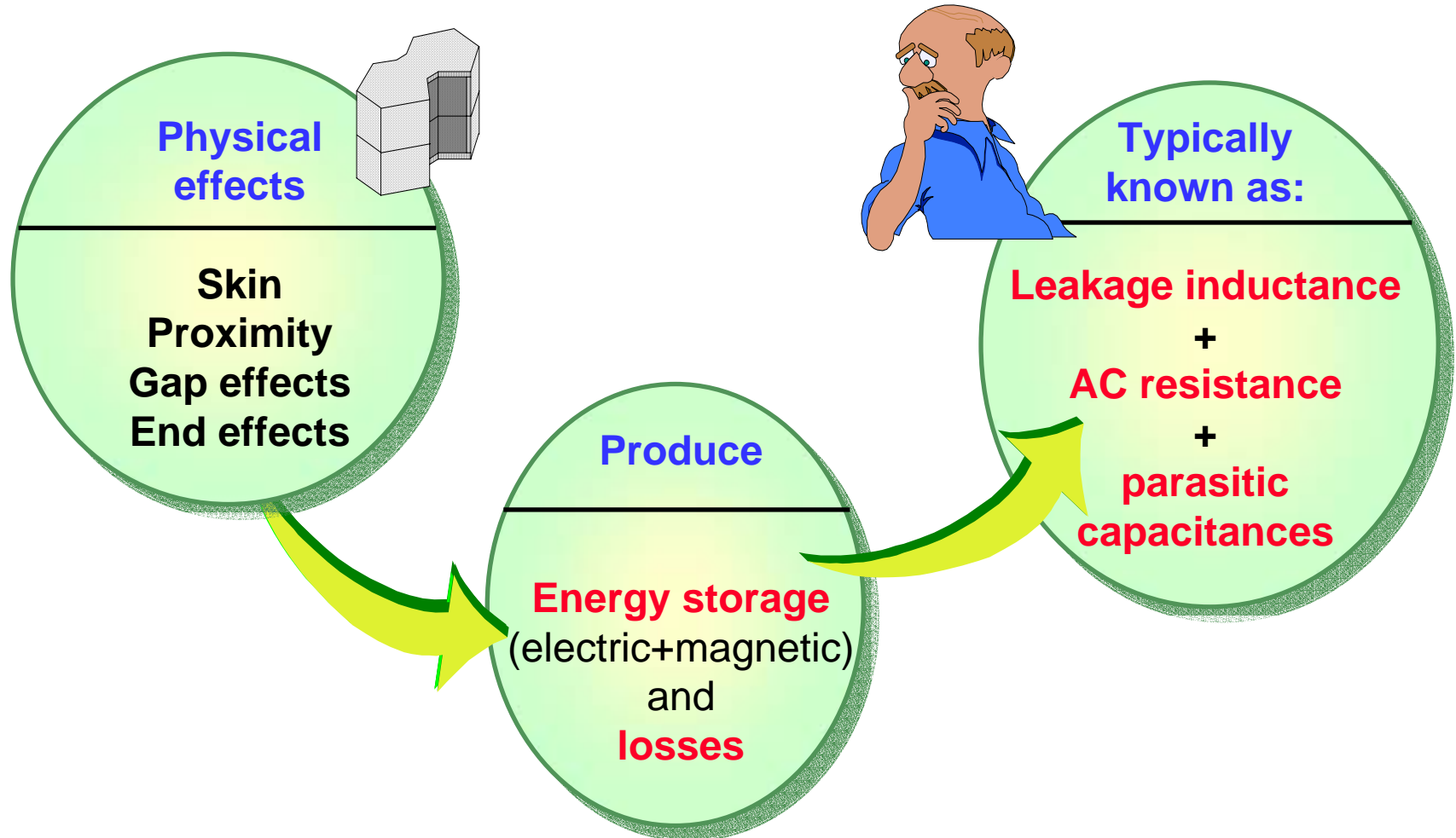
Hysteresis
in the core



...

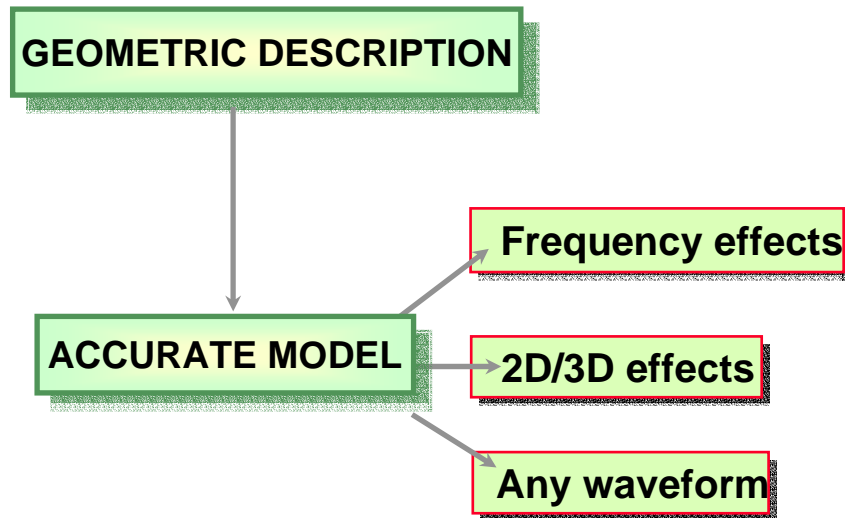
Basic concepts

Main effects to be modeled in the windings



Modeling Procedure

Objective

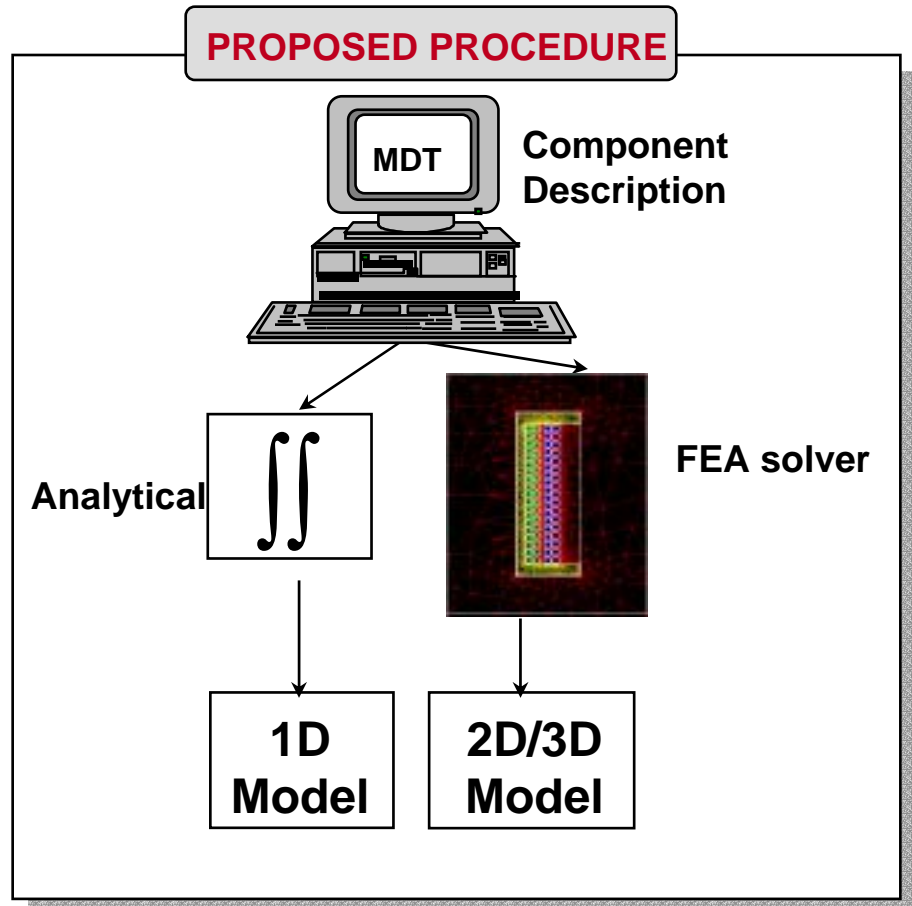
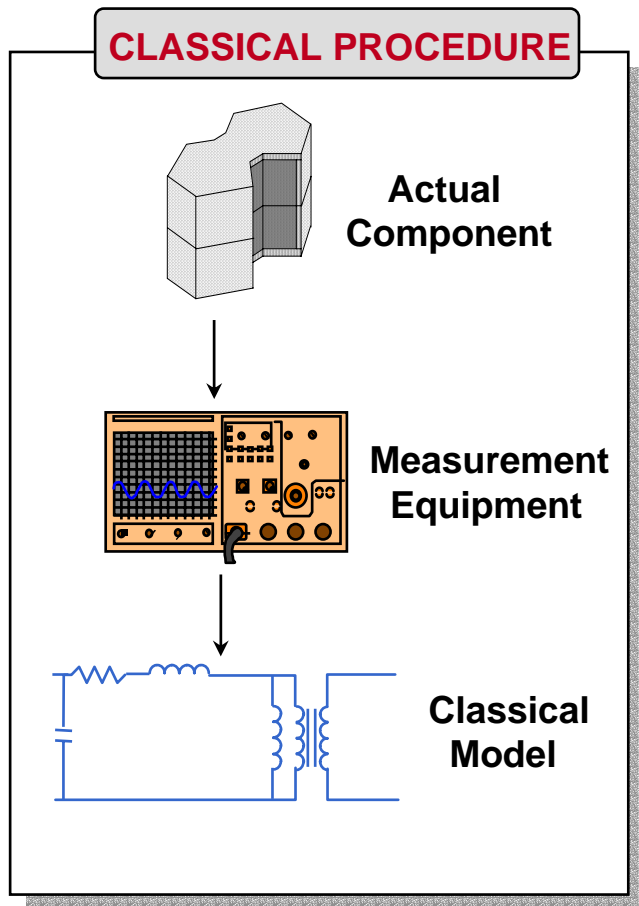


Avoid redesigns:
save time and money

Modeling strategy

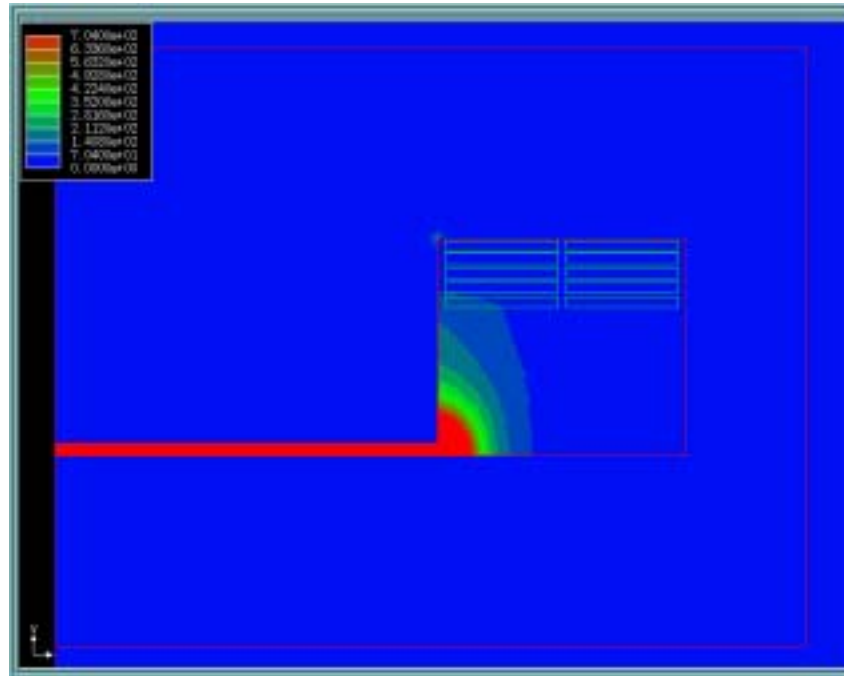
- Use commercial models for the core
- Develop accurate models for the windings, using *Finite Element Analysis* (FEA) tool or analytical expressions
- Combine the core model and the winding model

Modeling Procedure



- No actual magnetic component is built until expected performance is obtained
- Influence of the winding strategy can be tested

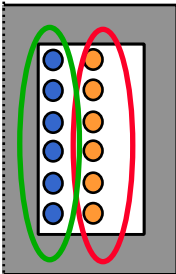
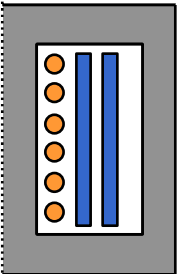
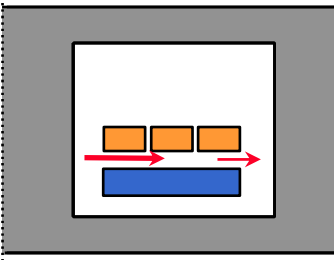
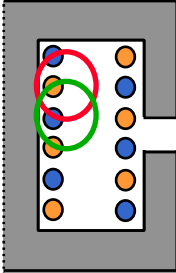
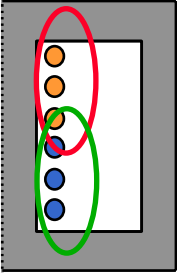
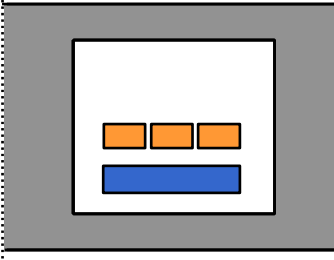
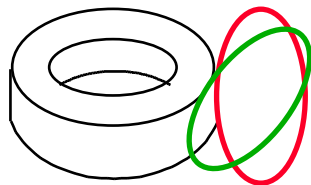
Modeling procedure



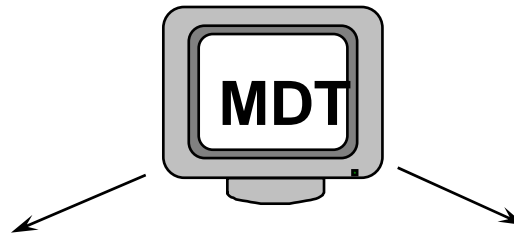
GOALS to model windings:

- Energy and losses in the windings are the main goals
- Core properties that affect to windings are considered
- Energy in the core is also calculated

Types of flux distribution

1D	 <p>concentric</p>	 <p>concentric</p>	 <p>planar or PCB</p>
2D	 <p>twisted and parallel</p>	 <p>top/down</p>	 <p>planar or PCB</p>
3D	 <p>toroid</p>		

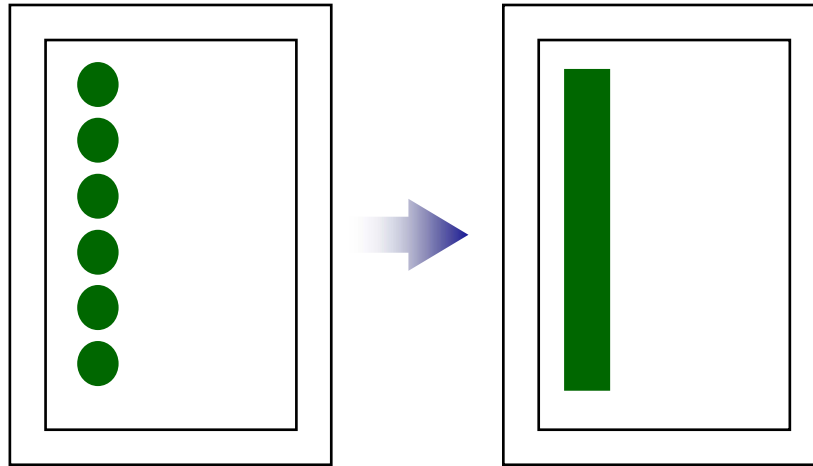
Basic features of the models



	1D MODEL	2D/3D MODEL
<i>Flux & Field Distribution (Freq. effects)</i>	1D effects	2D/3D effects
<i>Geometries</i>	Most concentric and top-down	Any
<i>Capacitive effects</i>	Theoretical (interlayer)	FEA solver
<i>Generation time</i>	Instantaneous	FEA solver (2-3 hours)

1D model features

Very useful to model 1D winding strategies



Advantages

- Fast model generation
- Easy to implement
- Frequency effects are taken into account

Disadvantages

- 2D effects neglected (gap, end...)
- Only valid in 1D winding strategies

1D model description

Maxwell equations (1D)

$$\frac{\partial E}{\partial x} = \mu_0 \frac{\partial H}{\partial t}$$

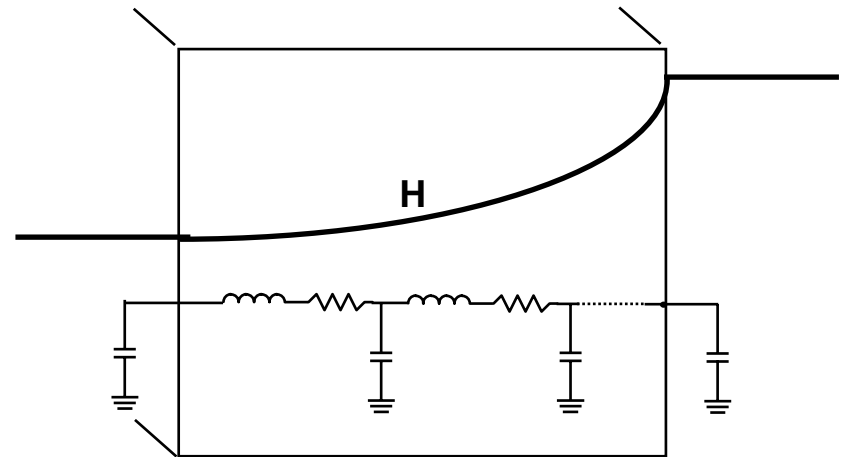
$$\frac{\partial H}{\partial x} = \sigma E + \varepsilon \frac{\partial E}{\partial t}$$



Transmission line equations

$$\frac{\partial i}{\partial x} = C \frac{\partial u}{\partial t}$$

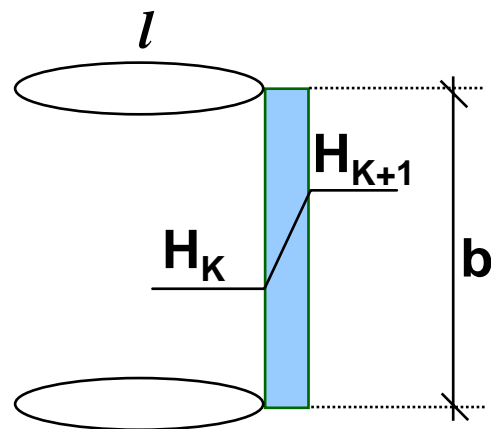
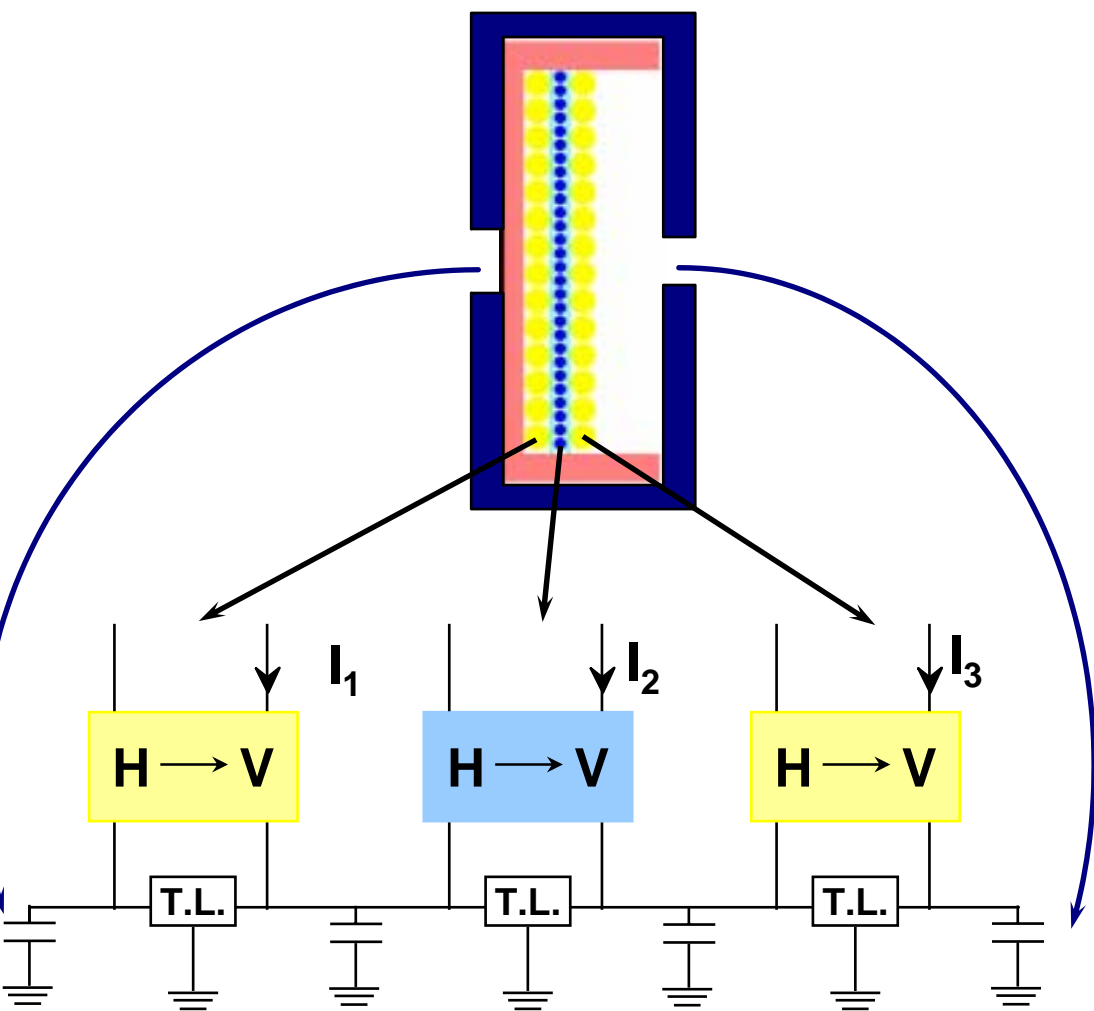
$$\frac{\partial v}{\partial x} = R \cdot i + L \frac{\partial i}{\partial t}$$



$$H = v; \quad E = \frac{i}{lb}$$
$$c = \mu_0 \cdot l \cdot b; \quad L = \frac{\varepsilon}{lb}; \quad R = \frac{\sigma}{lb}$$

Based on the analogy between transmission line and Maxwell equations for 1D

1D model description



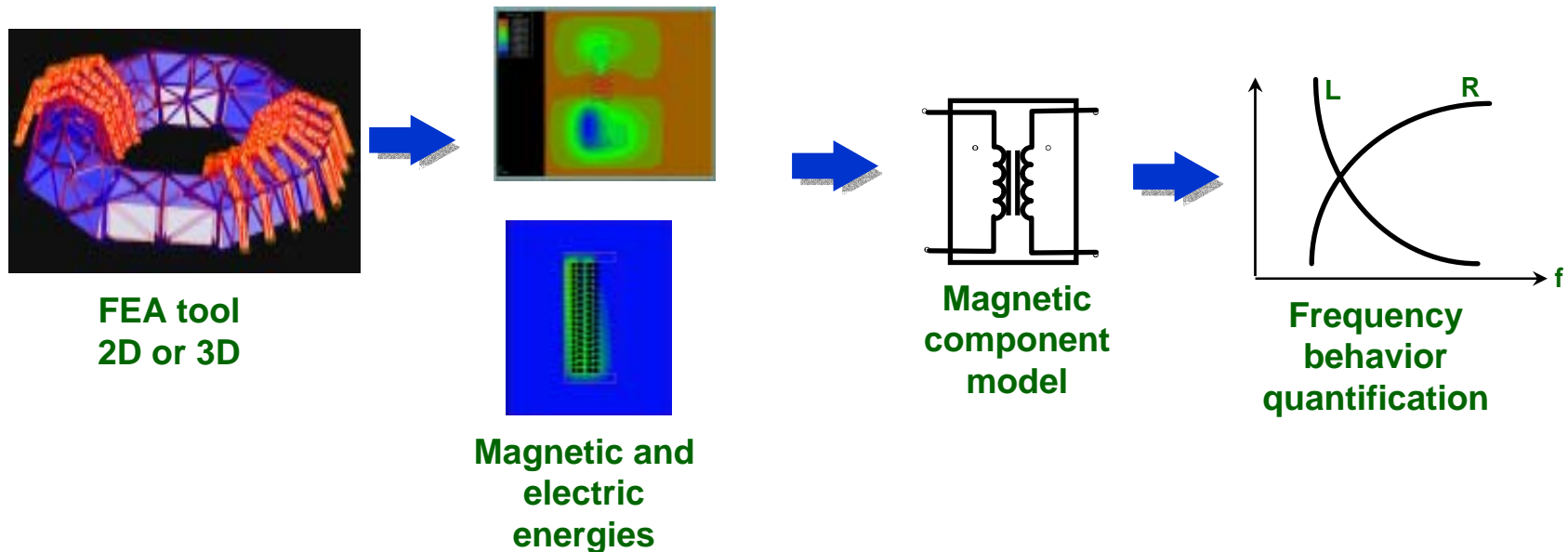
$$\oint H dl = ni$$

$$H_{K+1} - H_K = \frac{ni}{b}$$

$$H \rightarrow V$$

Magnetic Components Modeling (2D/3D model)

- Use FEA to compute the magnetic and electric behavior



Frequency and geometry effects *in the windings* are taken into account

Magnetic Components Modeling (2D/3D model)

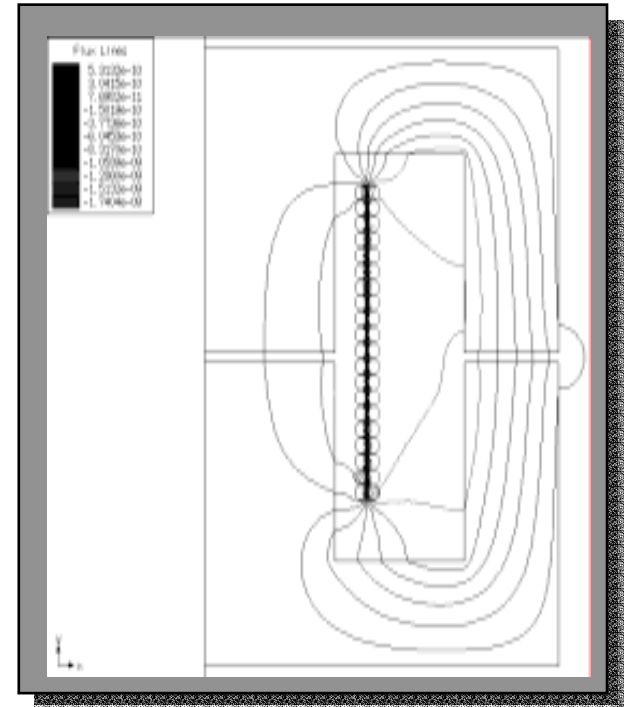
Why FEA?

Geometry and frequency effects

- × Gap effect
- × End effect
- × Skin effect
- × Proximity effect

✓ 3D Effects

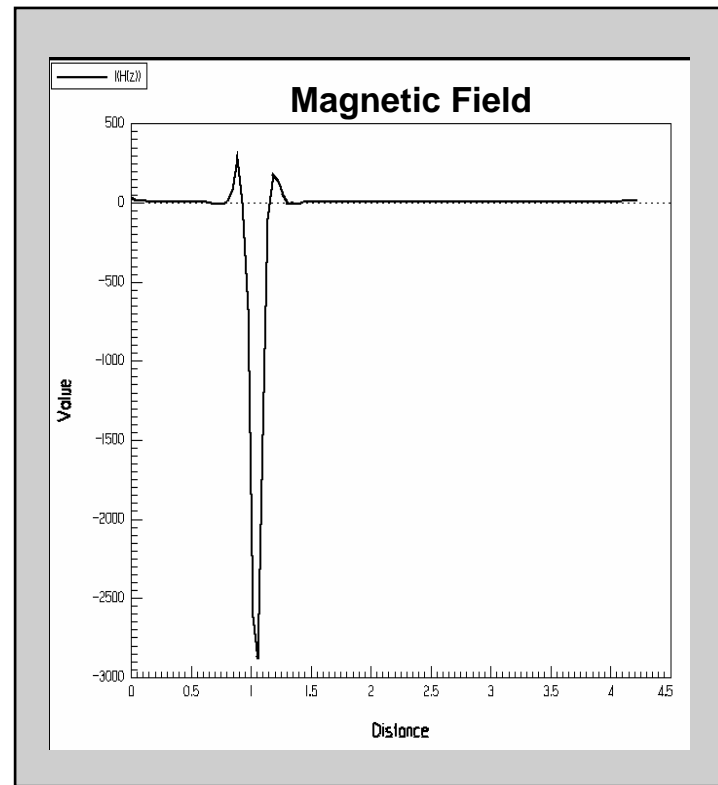
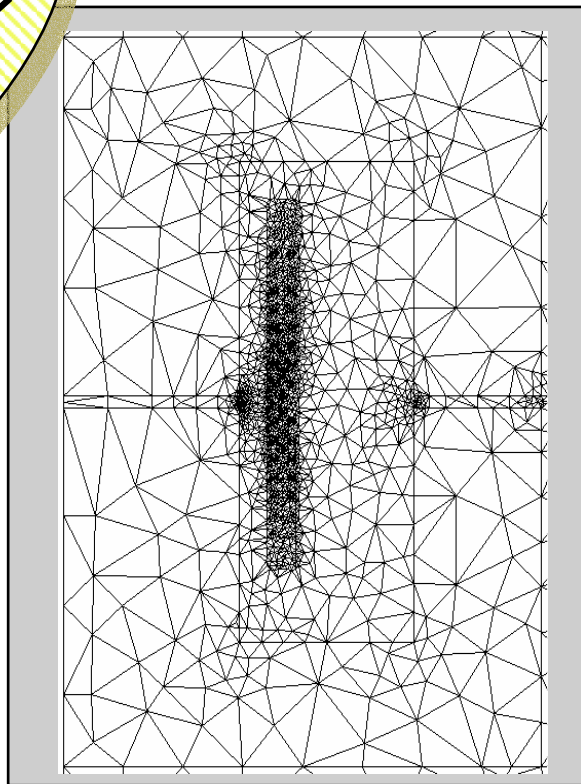
- × Effect of the connections
- × Toroids



Dimensional effects for **any structure**
are only taken into account by FEA

Finite Element Analysis (FEA) Solver

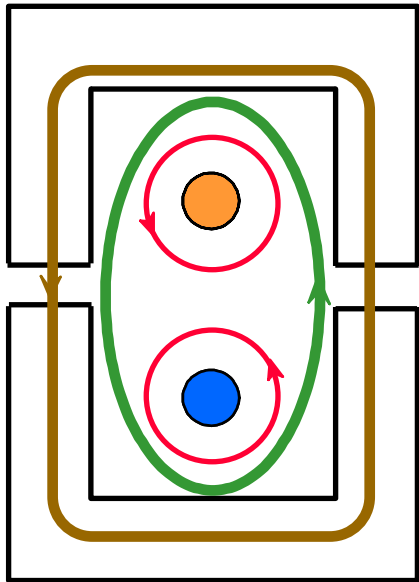
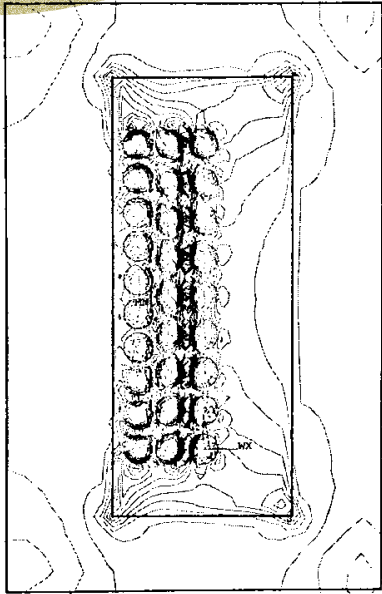
Additional
advantages of FEA



Insight in any physical quantity

Magnetic Components Modeling (2D/3D model)

How from FEA
to the model?



Energy tests (frequency sweep)

➤ Energy in the core

Mainly common energy

➤ Energy in the air

Common energy

Self energy

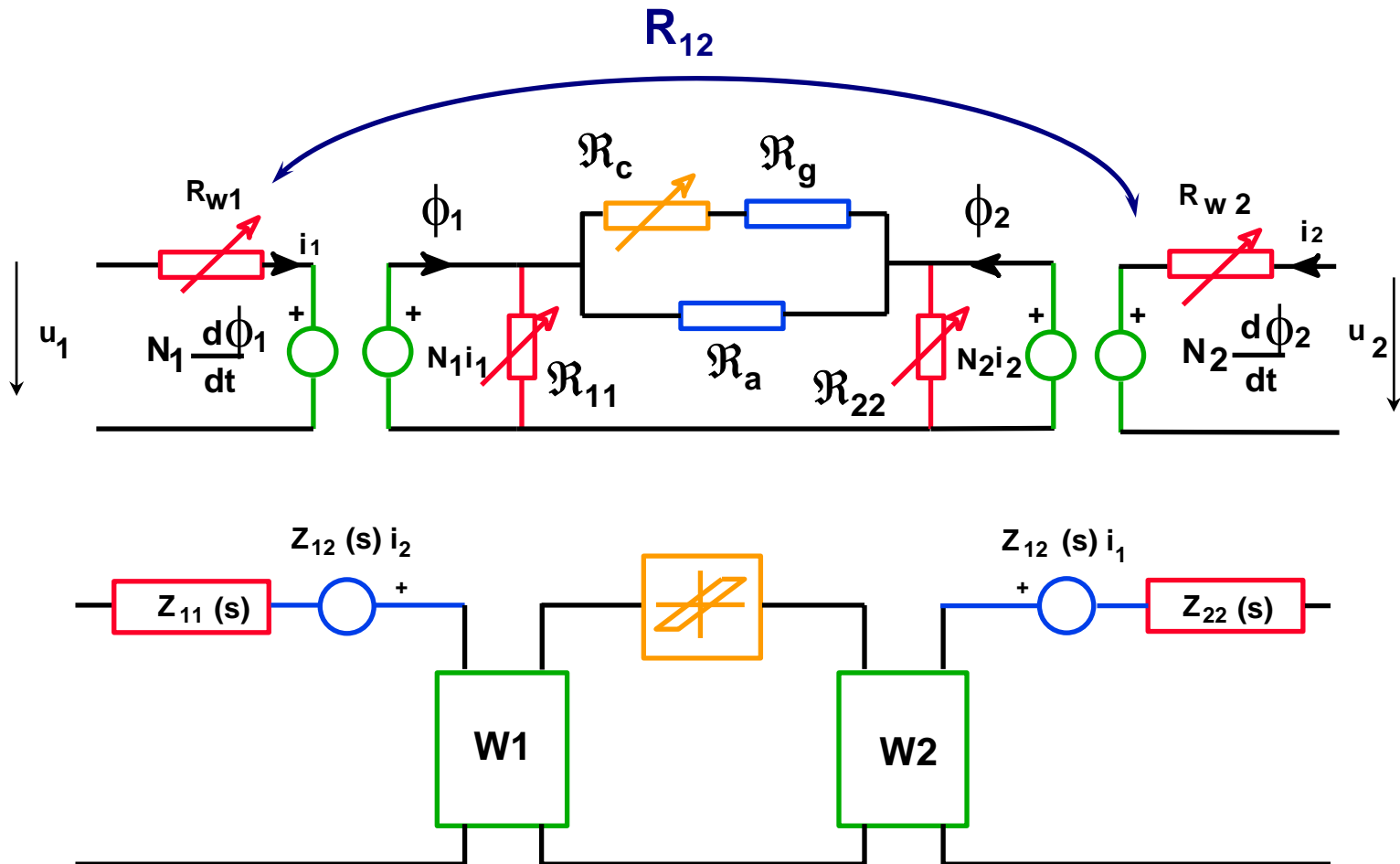
➤ Energy in the windings

➤ Losses in each winding

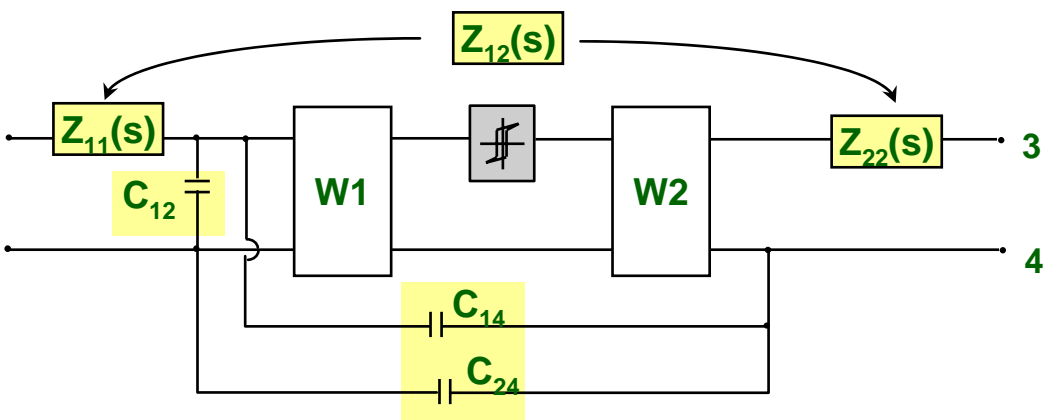
Self losses

“Coupled” losses

PRELIMINARY APPROACH



Magnetic Components Modeling (2D/3D model)



➤ Z_{11}, Z_{22} :

✓ losses and energy due to I_1 OR I_2
INDEPENDENTLY

➤ Z_{12} :

✓ losses and energy due to I_1 AND I_2
SIMULTANEOUSLY

UPM windings

- Geometry and frequency effects taken into account
- Distributed model
 - ✓ Coupled inductors
 - ✓ Multiwinding transformers

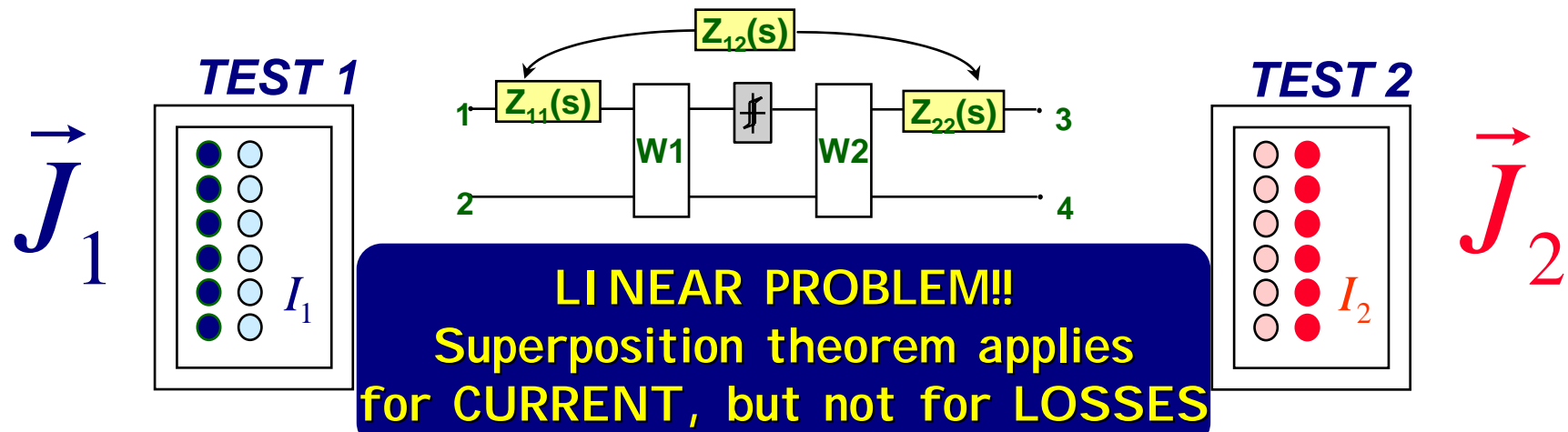
$$Z(s) = c_0 + c_1 s + \sum_{i=1}^{NPF} \frac{c_{2i} s}{s + c_{2i-1}}$$

$$R(\omega) = c_0 + \sum_{i=1}^{NPF} \frac{c_{2i} \omega^2}{\omega^2 + c_{2i-1}^2}$$

$$X(\omega) = \omega L(\omega) = \left[c_1 + \sum_{i=1}^{NPF} \frac{c_{2i} \omega^2}{\omega^2 + c_{2i-1}^2} \right]$$

Commercial core model

Winding modeling using FEA



FEA losses

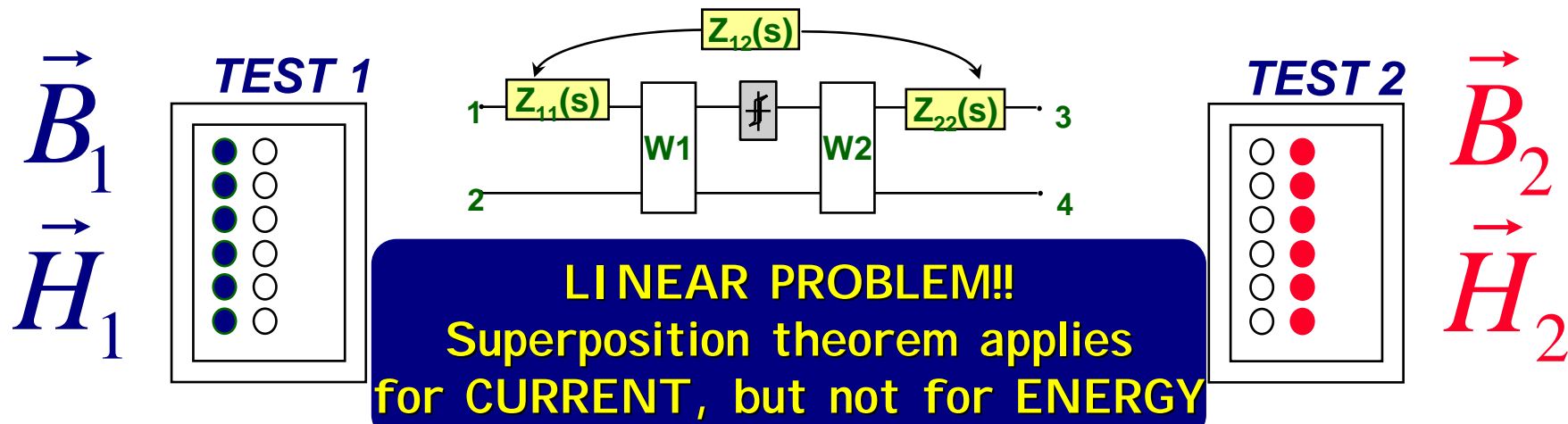
$$\begin{aligned}
 P &= \iiint \frac{1}{\sigma} \vec{J} \cdot \vec{J}^* dv = \\
 &= \iiint \frac{1}{\sigma} (\vec{J}_1 + \vec{J}_2) \cdot (\vec{J}_1^* + \vec{J}_2^*) dv \\
 &\quad \left\{ \begin{aligned} &= \iiint \frac{1}{\sigma} \vec{J}_1 \cdot \vec{J}_1^* dv \dots\dots\dots \\ &+ \iiint \frac{1}{\sigma} \vec{J}_2 \cdot \vec{J}_2^* dv \dots\dots\dots \\ &+ \iiint \frac{1}{\sigma} (\vec{J}_1 \cdot \vec{J}_2^* + \vec{J}_2 \cdot \vec{J}_1^*) dv \dots\dots\dots \end{aligned} \right.
 \end{aligned}$$

Model losses

$$P = R_1 I_1^2 + R_2 I_2^2 + 2 R_{12} I_1 I_2$$

$$\left\{ \begin{aligned} &R_1 I_1^2 \\ &R_2 I_2^2 \\ &2 R_{12} I_1 I_2 \end{aligned} \right.$$

Winding modeling using FEA



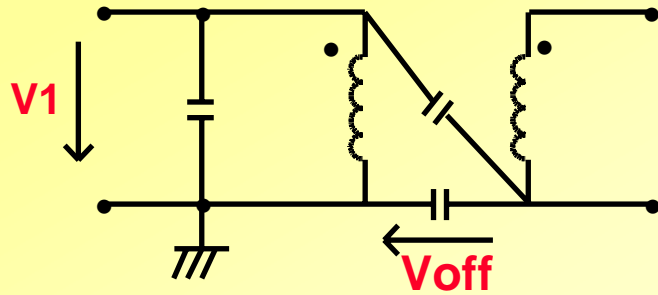
FEA magnetic energy

$$\begin{aligned}
 E &= \frac{1}{2} \iiint \vec{B} \cdot \vec{H}^* dv \\
 &= \frac{1}{2} \iiint (\vec{B}_1 + \vec{B}_2) \cdot (\vec{H}_1^* + \vec{H}_2^*) dv \\
 &\left\{ \begin{aligned} &= \frac{1}{2} \iiint \vec{B}_1 \cdot \vec{H}_1^* dv \\ &+ \frac{1}{2} \iiint \vec{B}_2 \cdot \vec{H}_2^* dv \\ &+ \frac{1}{2} \iiint (\vec{B}_1 \cdot \vec{H}_2^* + \vec{B}_2 \cdot \vec{H}_1^*) dv \end{aligned} \right.
 \end{aligned}$$

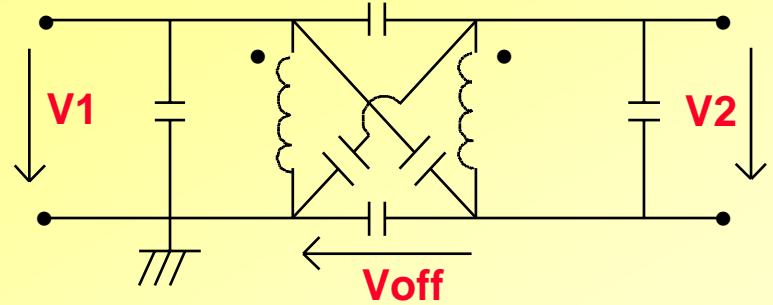
Model magnetic energy

$$\begin{aligned}
 E &= \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 + L_{12} I_1 I_2 \\
 &\left\{ \begin{aligned} &= \frac{1}{2} L_1 I_1^2 \\ &+ \frac{1}{2} L_2 I_2^2 \\ &+ L_{12} I_1 I_2 \end{aligned} \right.
 \end{aligned}$$

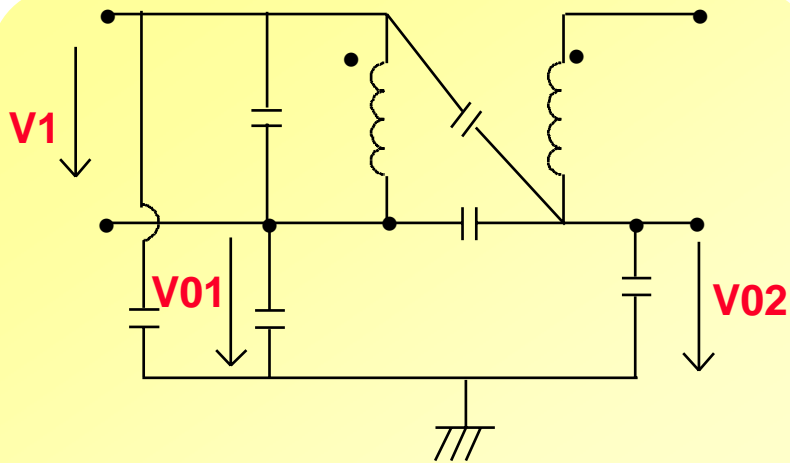
Proposed capacitive models (two winding transformer)



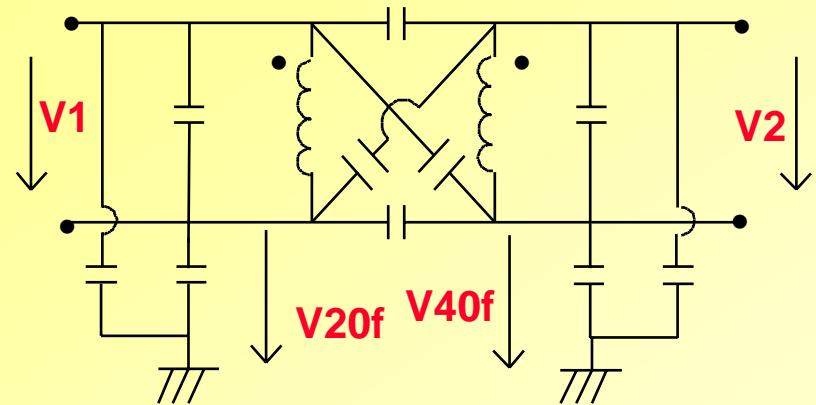
LEVEL 1



LEVEL 2

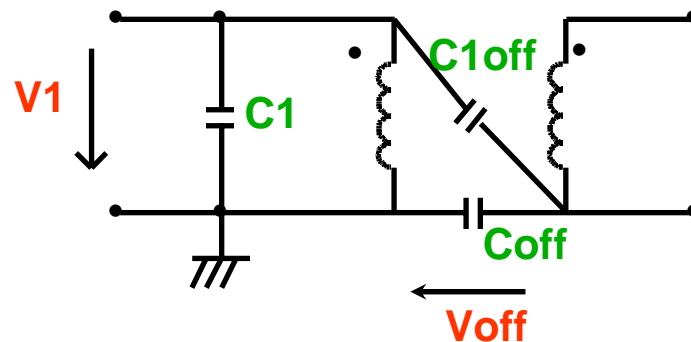


LEVEL 3



LEVEL 4

Level 1 Model. Two winding transformer



FEA Electric Energy

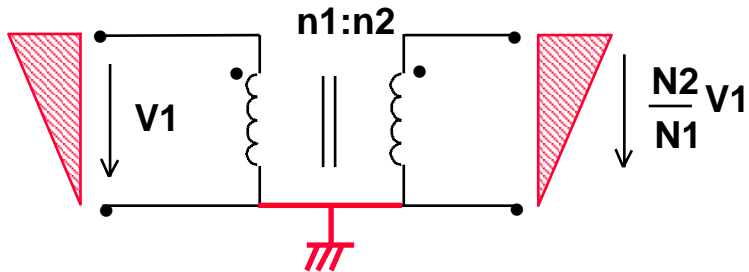
$$\begin{aligned}
 I &= \frac{1}{2} \iiint_V \vec{D} \vec{E} d\nu = \frac{1}{2} \iiint_V (\vec{D}_1 + \vec{D}_{off}) (\vec{E}_{off} + \vec{E}_1) d\nu = \\
 &= \frac{1}{2} \iiint_V \vec{D}_1 \vec{E}_1 d\nu + \dots \dots \dots \rightarrow \\
 &+ \frac{1}{2} \iiint_V \vec{D}_{off} \vec{E}_{off} d\nu + \dots \dots \dots \rightarrow \\
 &+ \frac{1}{2} \iiint_V (\vec{D}_1 \vec{E}_{off} + \vec{D}_{off} \vec{E}_1) d\nu \dots \dots \dots \rightarrow \\
 &= I_1 + I_{off} + I_{loff} \dots \dots \dots \rightarrow
 \end{aligned}$$

Model Electric Energy

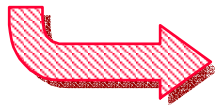
$$\begin{aligned}
 I &= \frac{1}{2} C_1 V_1^2 + \frac{1}{2} C_{off} V_{off}^2 + \frac{1}{2} (V_1 - V_{off})^2 C_{loff} = \\
 &= \frac{1}{2} (C_1 + C_{loff}) V_1^2 + \\
 &+ \frac{1}{2} (C_{off} + C_{loff}) V_{off}^2 - \\
 &- C_{loff} V_1 V_{off} = \\
 &= I_1 + I_{off} + I_{loff}
 \end{aligned}$$

Finite Element Analysis Procedure for Capacitive Effects

ANALYSIS 1



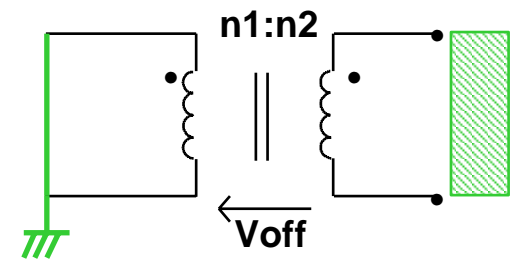
$$I_1 = \frac{1}{2} \iiint_V \vec{D}_1 \vec{E}_1 dV$$



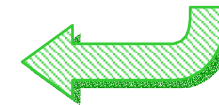
ENERGY CALCULATION

$$I_{\text{off}} = \iiint_V (\vec{D}_1 \vec{E}_{\text{off}} + \vec{D}_{\text{off}} \vec{E}_1) dV$$

ANALYSIS 2

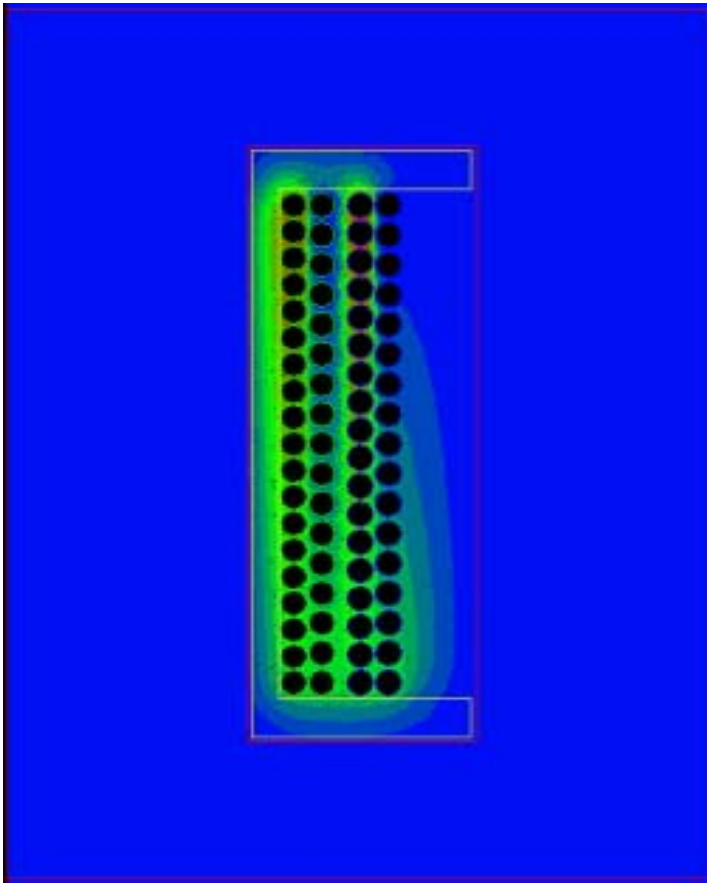


$$I_{\text{off}} = \frac{1}{2} \iiint_V \vec{D}_{\text{off}} \vec{E}_{\text{off}} dV$$

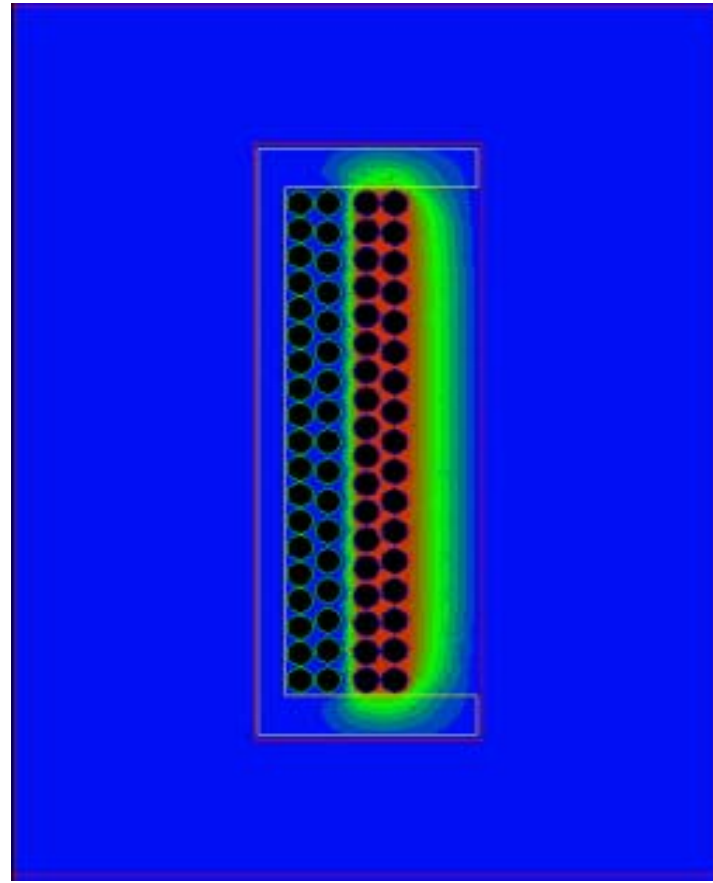


Finite Element Analysis Procedure for Capacitive Effects

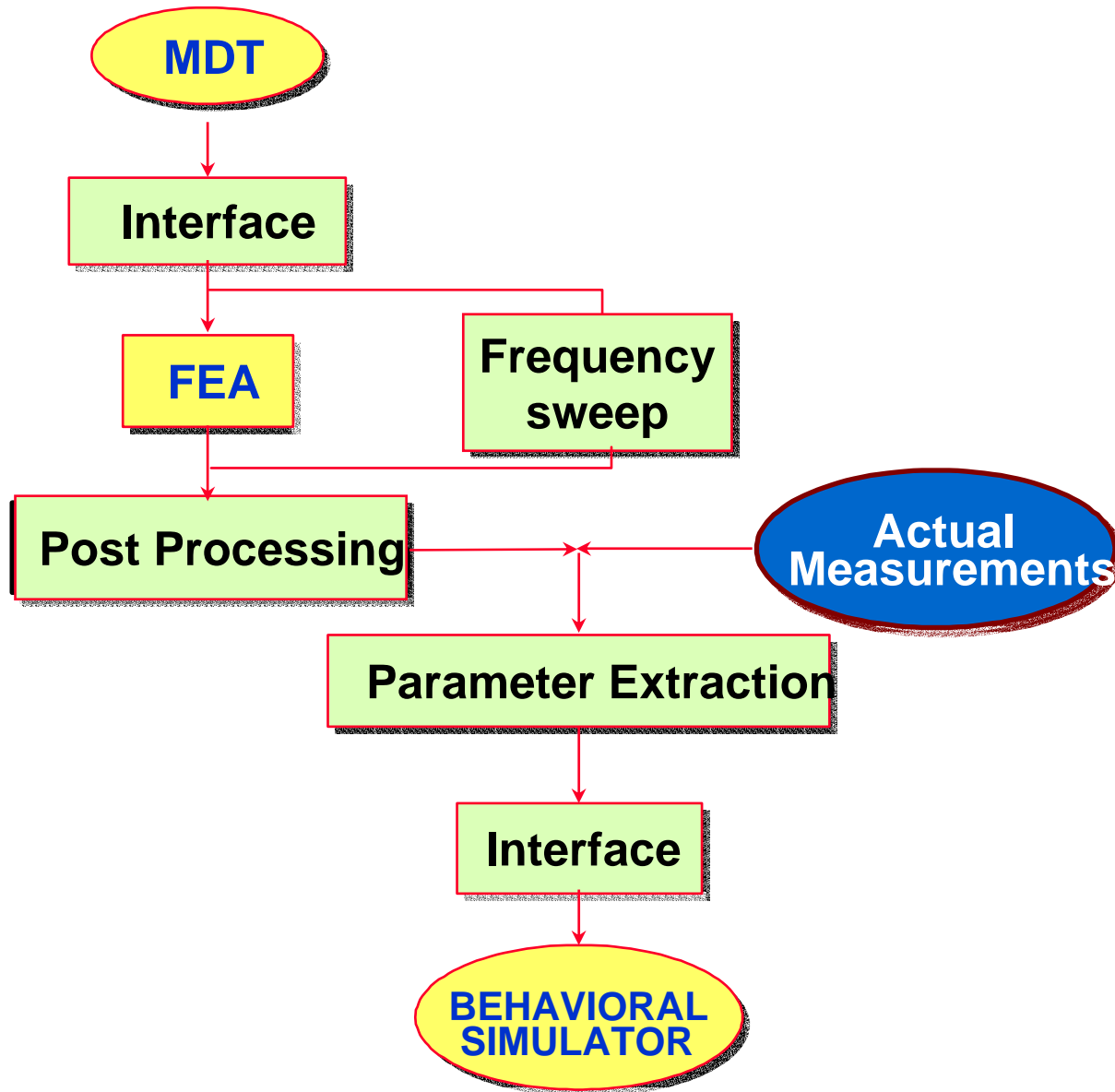
ANALYSIS 1



ANALYSIS 2

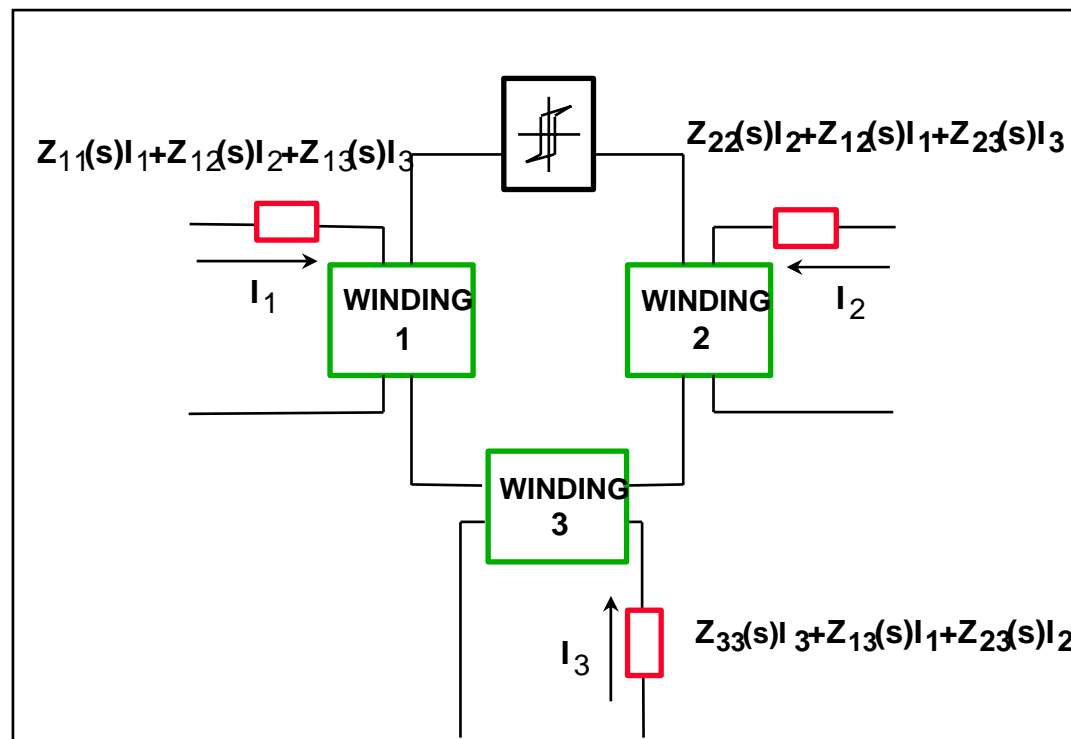
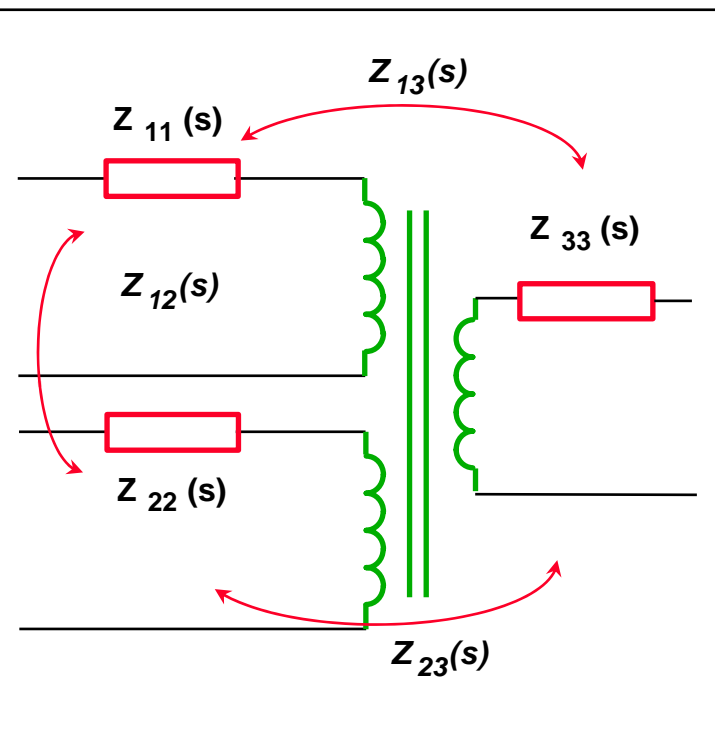


Magnetic Components Modeling (2D/3D model)



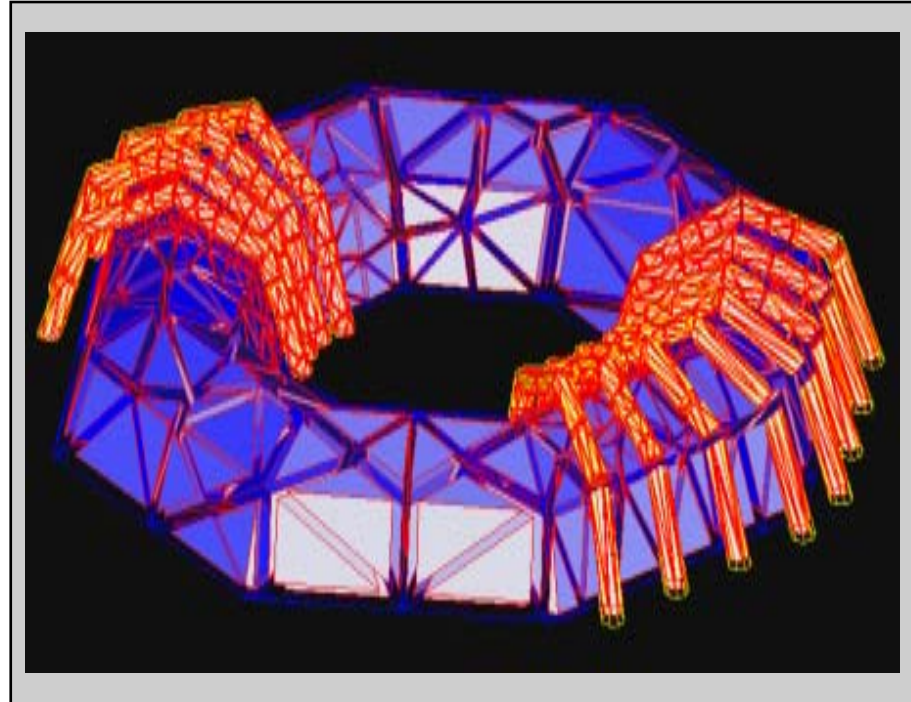
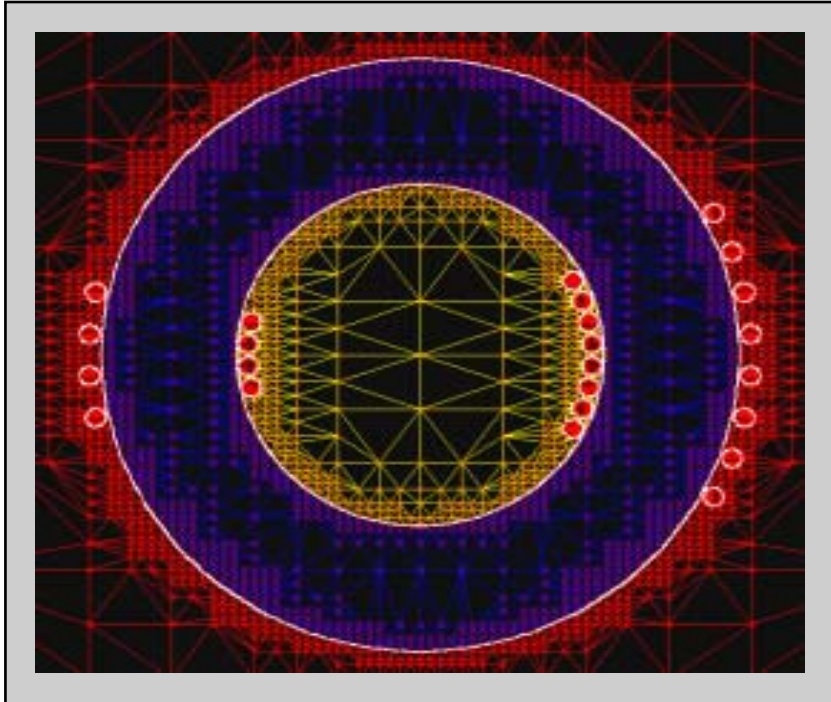
Magnetic Components Modeling (2D/3D model)

Behavioral model developed for *multi-winding* magnetic components



Magnetic Components Modeling (2D/3D model)

Procedure established for **2D** and **3D** simulations



➤ Basic concepts

➤ High frequency effects

➤ **Modeling**

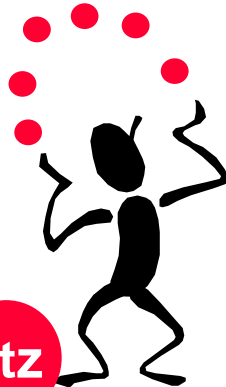
➤ Advanced design

➤ Application to converters

Mr Designer at UPM lab



before...



litz

...after

Mr Designer
learns to
design



Mr Designer
has a problem



Mr Designer
finds a solution



Mr Designer
can use it !



Mr Designer
succeeds !!



➤ Basic concepts

➤ High frequency effects

➤ Modeling

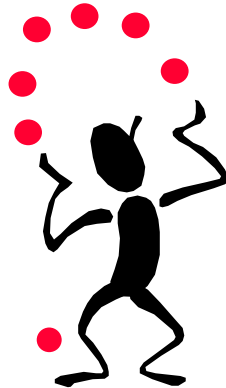
➤ Advanced design

➤ Application to converters

Mr Designer at UPM lab



before...



...after

Mr Designer
learns to
design



Mr Designer
has a problem



Mr Designer
finds a solution



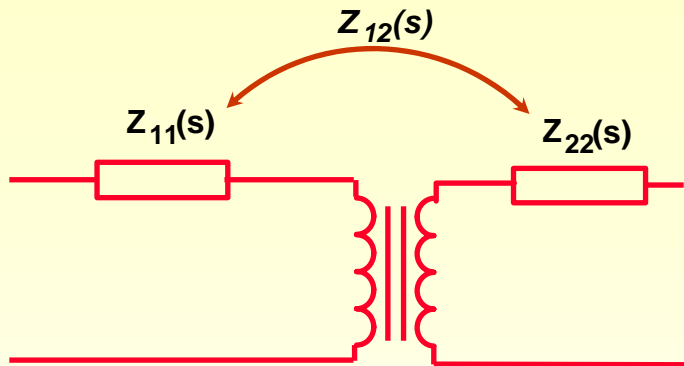
Mr Designer
can use it !



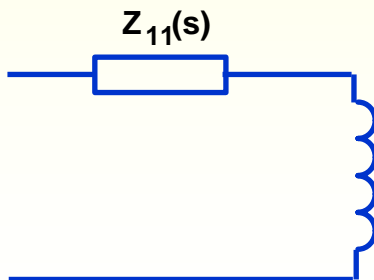
Mr Designer
succeeds !!



Magnetic Components



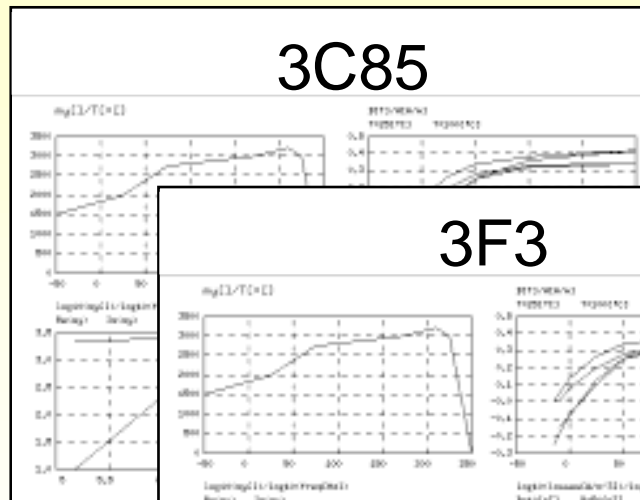
Transformers



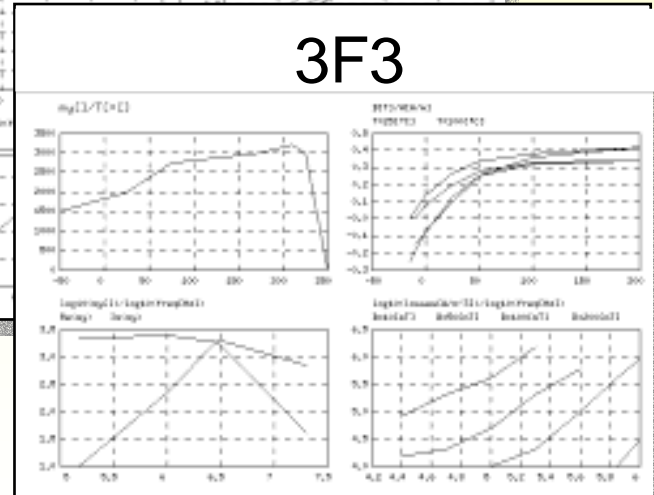
Inductors

Materials

3C85

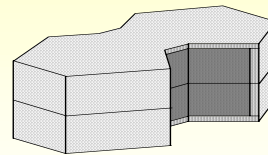
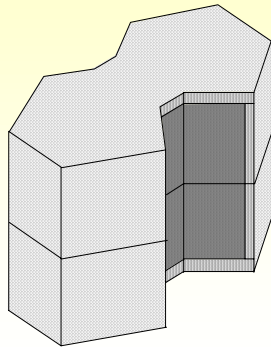
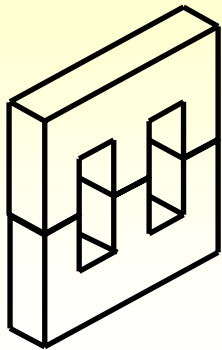


3F3



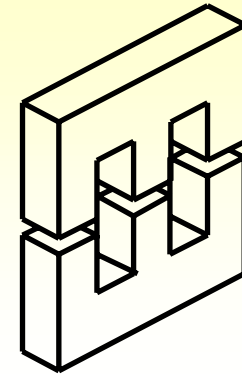
Test strategy

Core Shape Comparison

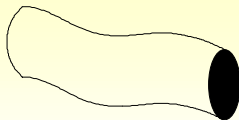


Low Profile

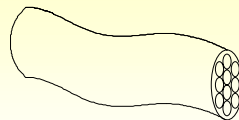
Gap Inclusion



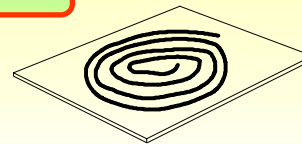
Conductor Types



Solid Wire



Litz Wire



Printed Circuit Wire

Experimental results

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:..... RM14

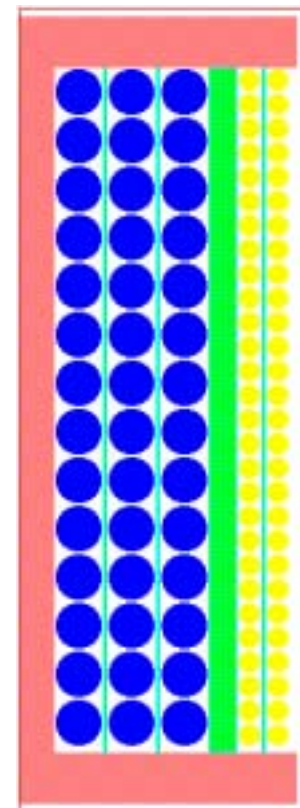
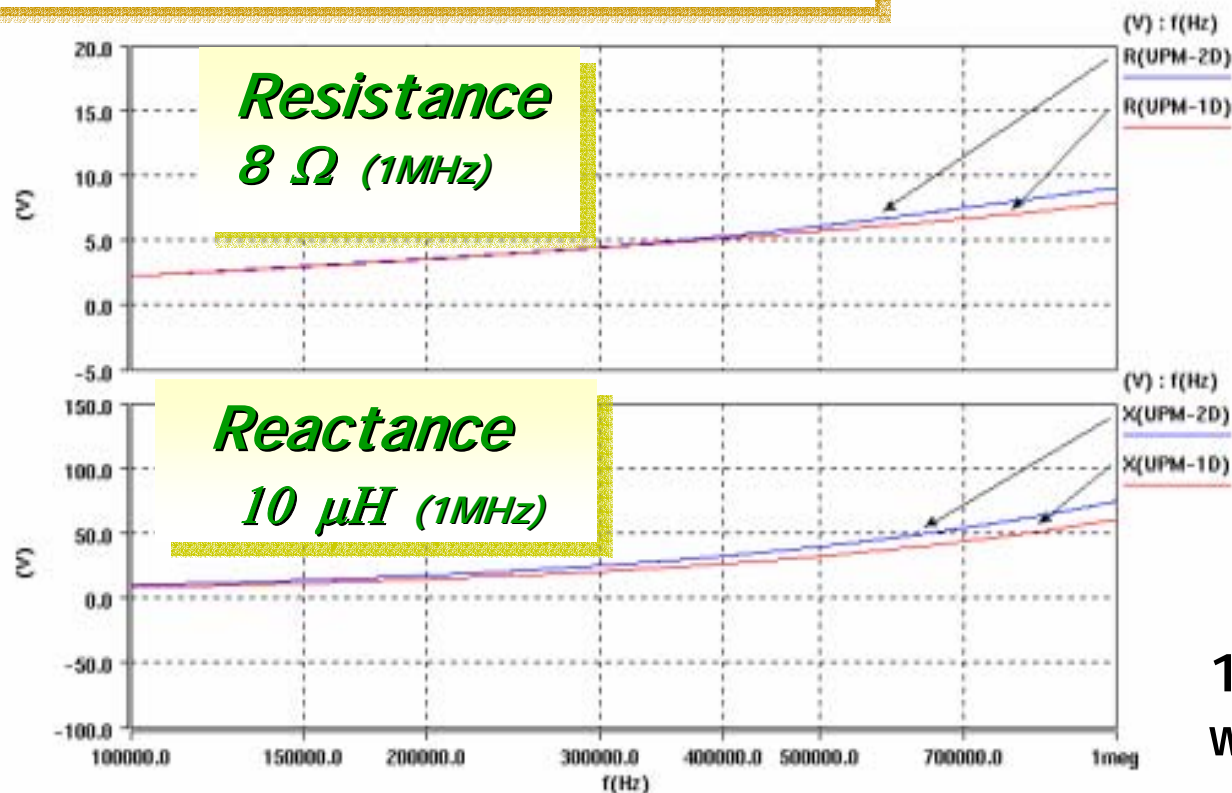
Core material:..... 3F3

Conductors:..... Solid, 1mm and 0.5mm diameter

Windings:..... Two in five layers (P:P:P:S:S)

Turns:..... Primary: 42; Secondary: 56

Short circuit test



1D transformer
without interleaving

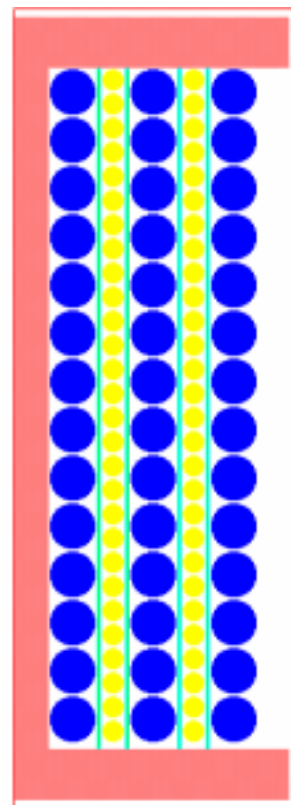
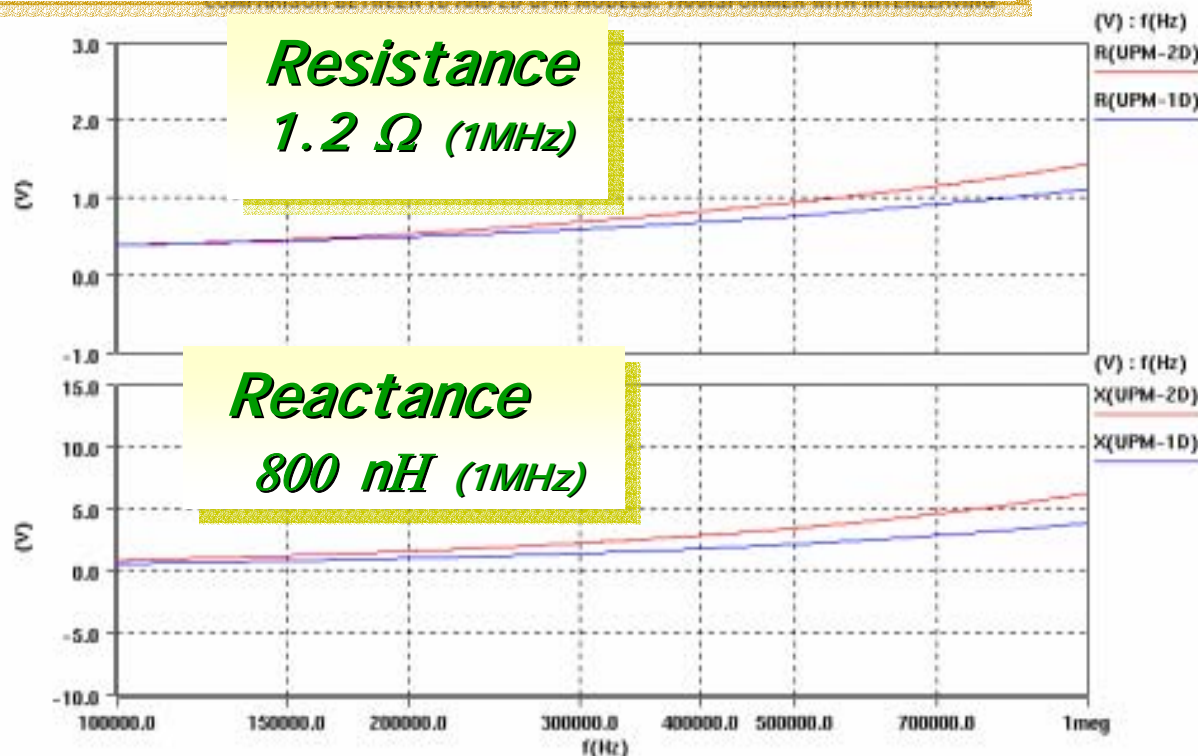
Experimental results

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:..... RM14
Core material:..... 3F3
Conductors:..... Solid, 1mm and 0.5mm diameter
Windings:..... Two in five layers (P:S:P:S:P)
Turns:..... Primary: 42; Secondary: 56

Short circuit test



1D transformer
with interleaving

Experimental results

TRANSFORMER STUDIED

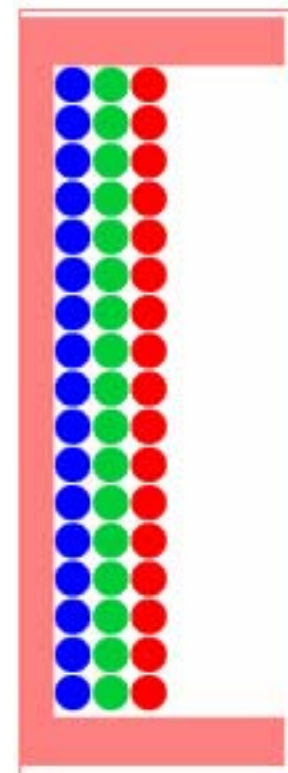
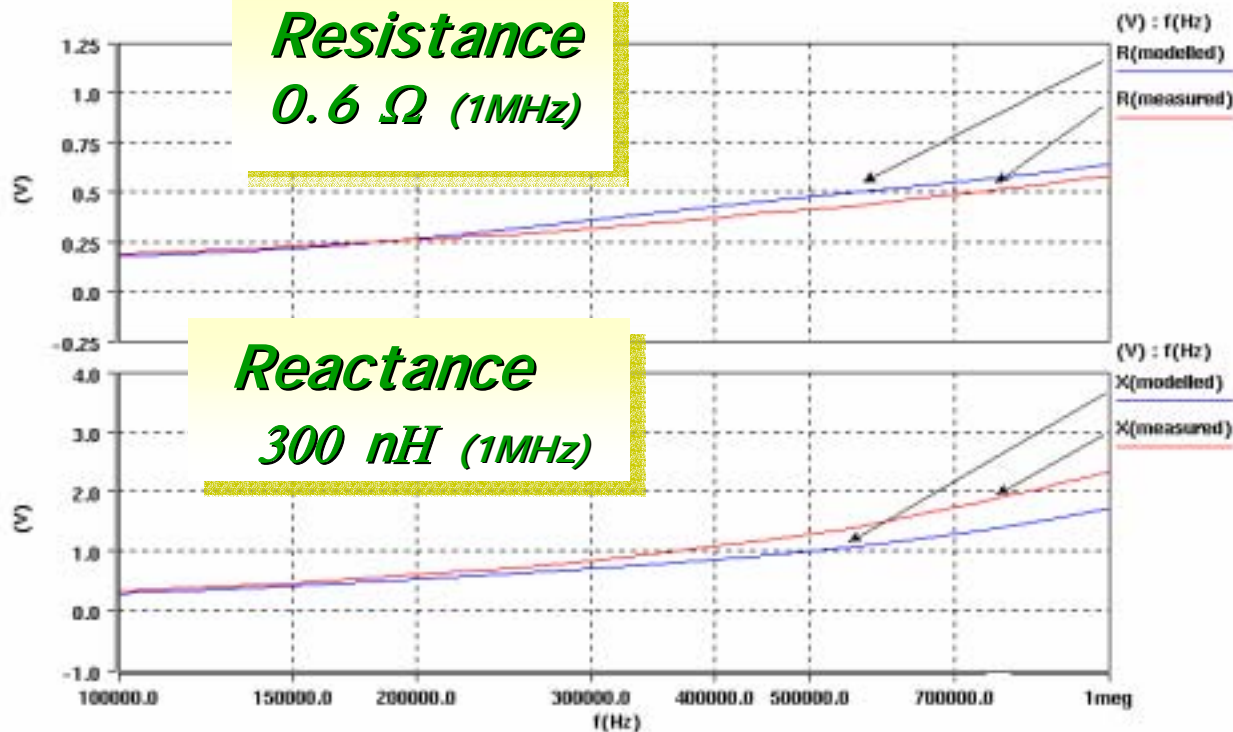
Geometric parameters

Core shape and size:..... RM12
Core material:..... 3F3
Conductors:..... Solid, 0.75mm diameter
Windings:..... Three in three layers (P:S:T)
Turns:..... Primary: 17; Secondary: 17
Tertiary: 17

Short circuit test

Resistance
0.6 Ω (1MHz)

Reactance
300 nH (1MHz)



1D transformer

Experimental results

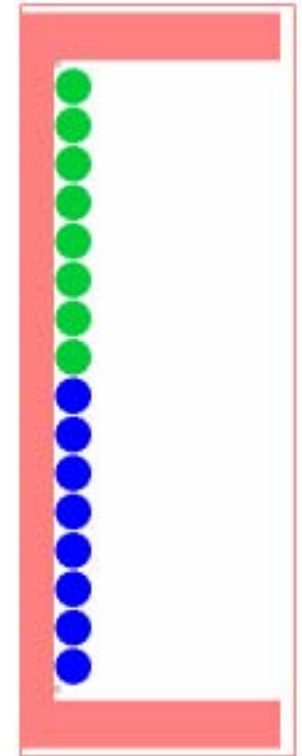
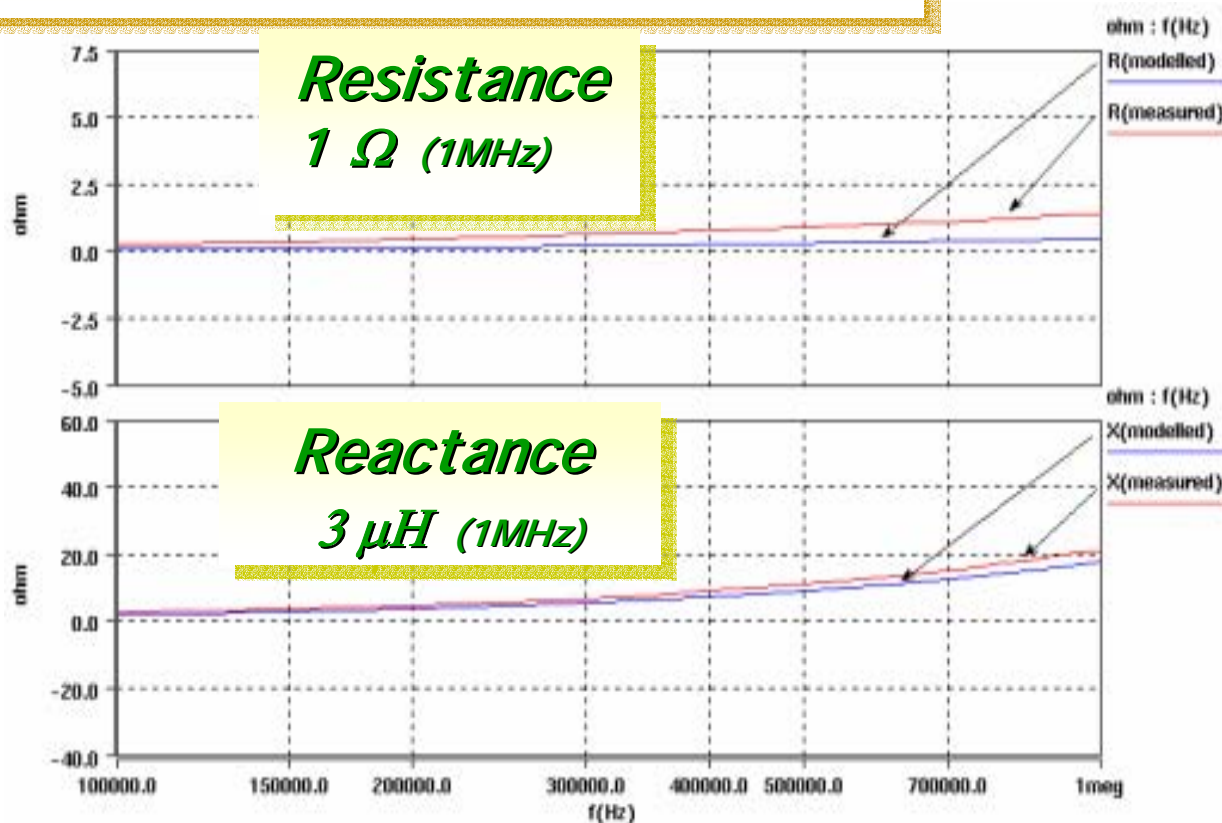
TRANSFORMER STUDIED

Geometric parameters

Core shape and size:..... RM12
Core material:..... 3F3
Conductors:..... Solid, 0.7mm diameter
Windings:..... Two in one layers (P:S)
Turns:..... Primary: 8; Secondary: 8

Short circuit test

Resistance
1 Ω (1MHz)



2D transformer

Experimental results

TRANSFORMER STUDIED

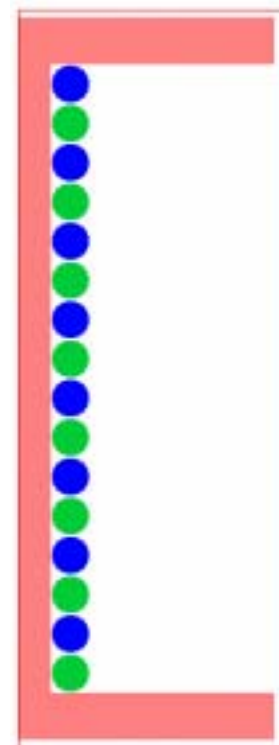
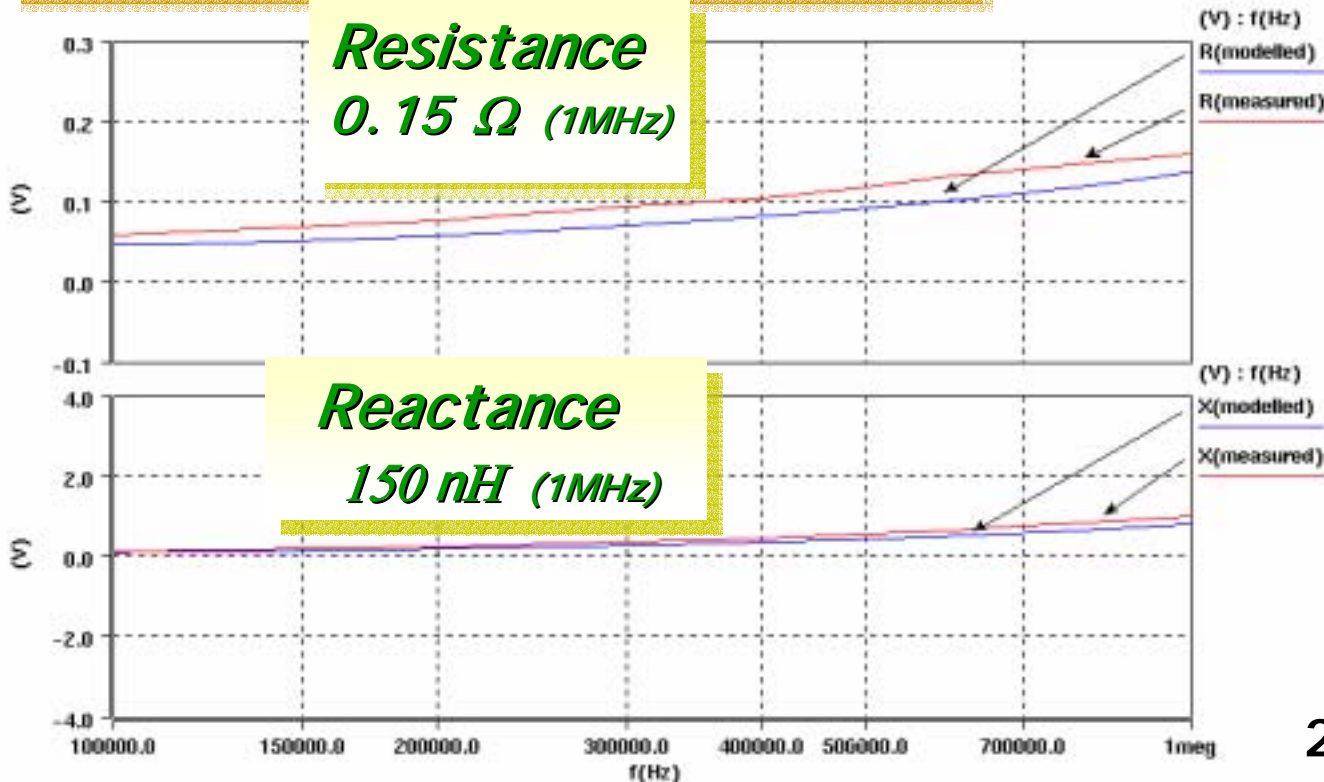
Geometric parameters

Core shape and size:..... RM12
Core material:..... 3F3
Conductors:..... Solid, 0.7mm diameter
Windings:..... Two in one layers (P:S)
Turns:..... Primary: 8; Secondary: 8

Short circuit test

Resistance
 0.15Ω (1MHz)

Reactance
 150 nH (1MHz)



2D transformer

Experimental results

TRANSFORMER STUDIED

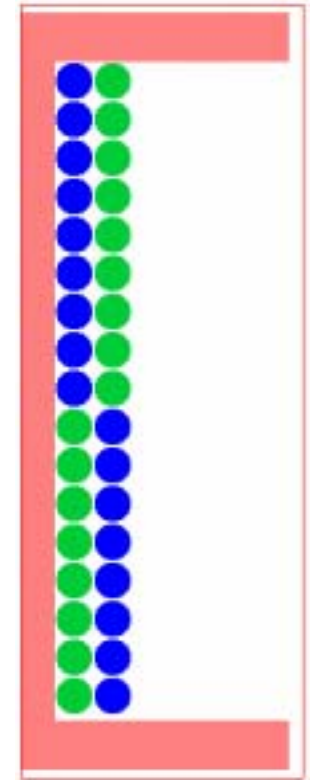
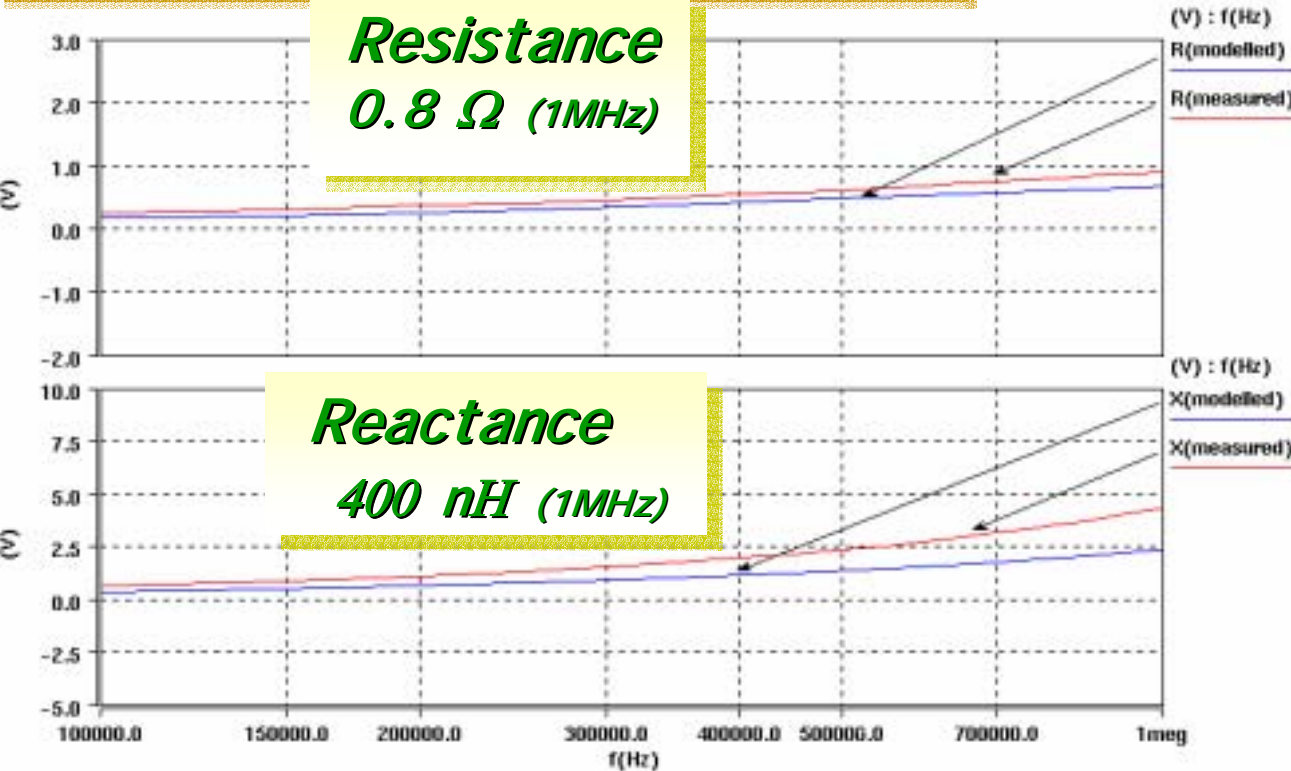
Geometric parameters

Core shape and size:..... RM12
Core material:..... 3F3
Conductors:..... Solid, 0.7mm diameter
Windings:..... Two in two layers
Turns:..... Primary: 17; Secondary: 17

Short circuit test

Resistance
 0.8Ω (1MHz)

Reactance
 400 nH (1MHz)



2D transformer

Experimental results

TRANSFORMER STUDIED

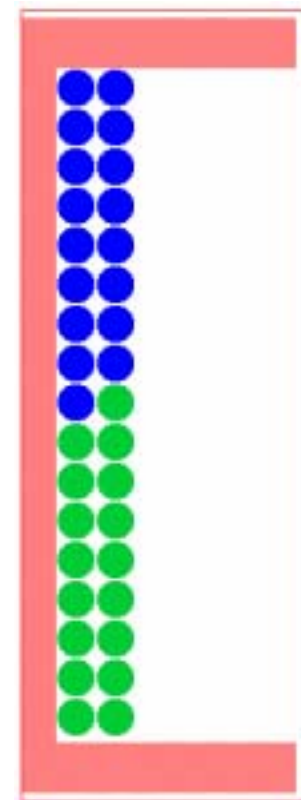
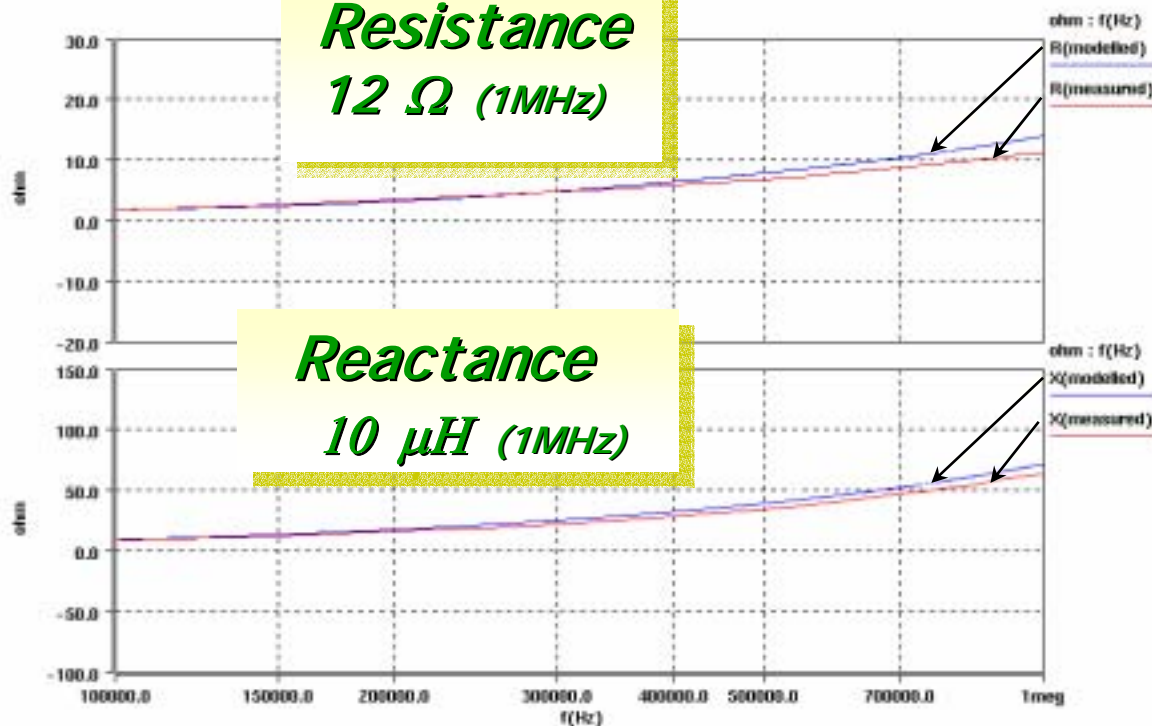
Geometric parameters

Core shape and size:..... RM12
Core material:..... 3F3
Conductors:..... Solid, 0.7mm diameter
Windings:..... Two in two layers
Turns:.....Primary: 17; Secondary: 17

Short circuit test

Resistance
12 Ω (1MHz)

Reactance
10 μH (1MHz)



2D transformer

Experimental results

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:.....custom made

Core material:..... 3F3

Conductors:..... foils, 70 μm thick

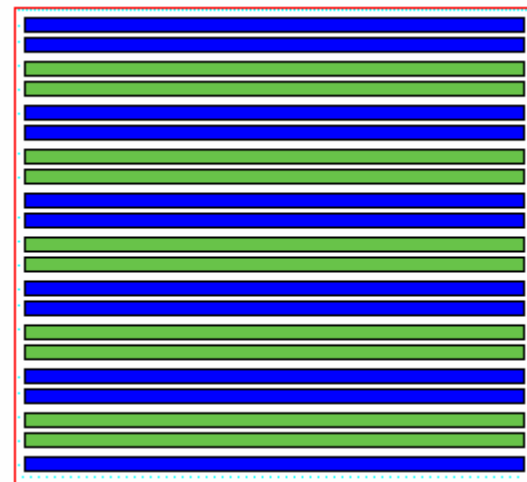
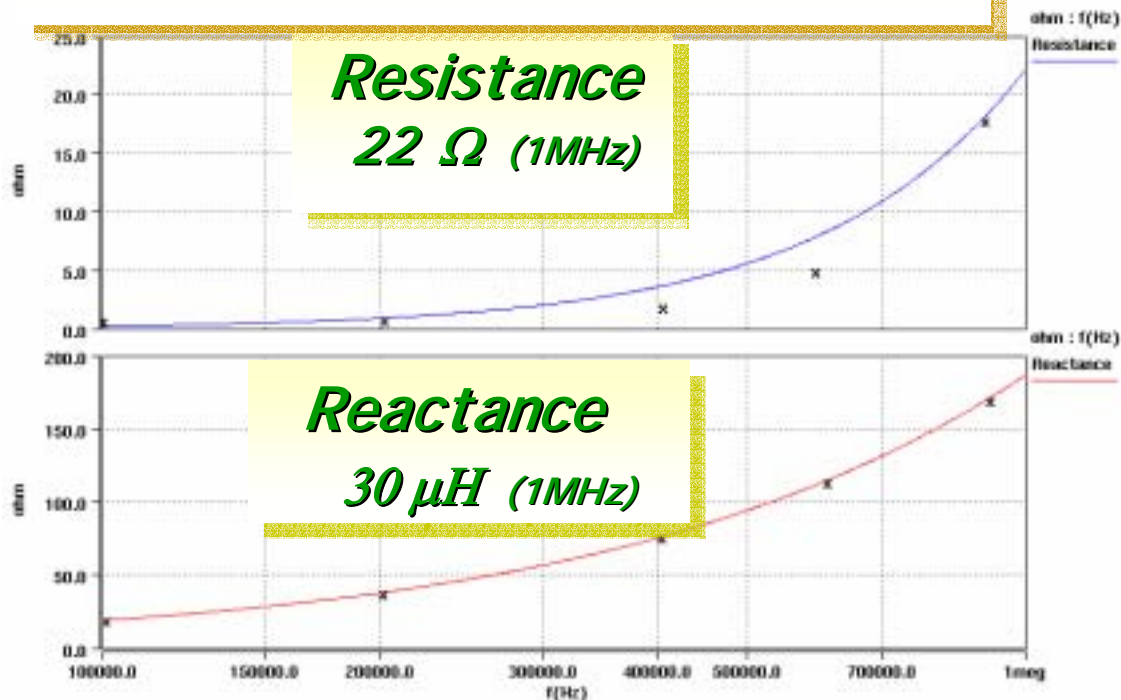
Windings:..... Two in 11 layers

Turns:..... Primary: 5; Secondary: 11

Open circuit test

Resistance
22 Ω (1MHz)

Reactance
30 μH (1MHz)



Experimental results

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:.....custom made

Core material:..... 3F3

Conductors:..... foils, 70 μm thick

Windings:..... Two in 11 layers

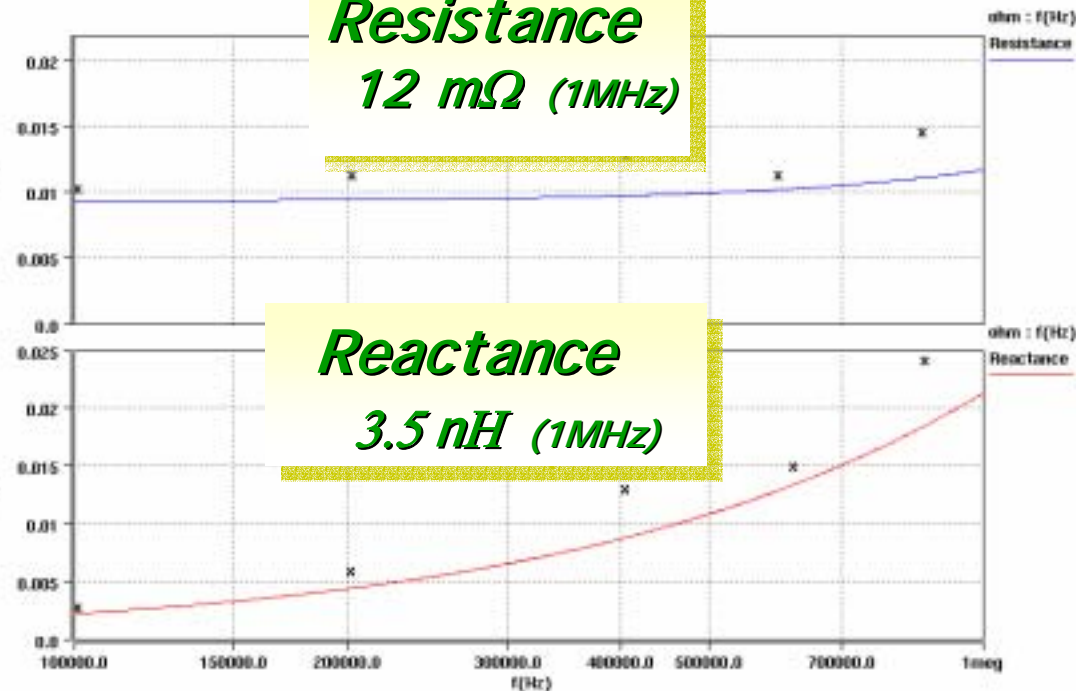
Turns:..... Primary: 5; Secondary: 11

Short circuit test



Resistance
12 m Ω (1MHz)

Reactance
3.5 nH (1MHz)



Experimental results

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:.....custom made

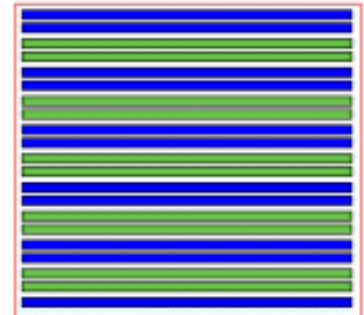
Core material:..... 3F3

Conductors:..... foils, 70 μm thick

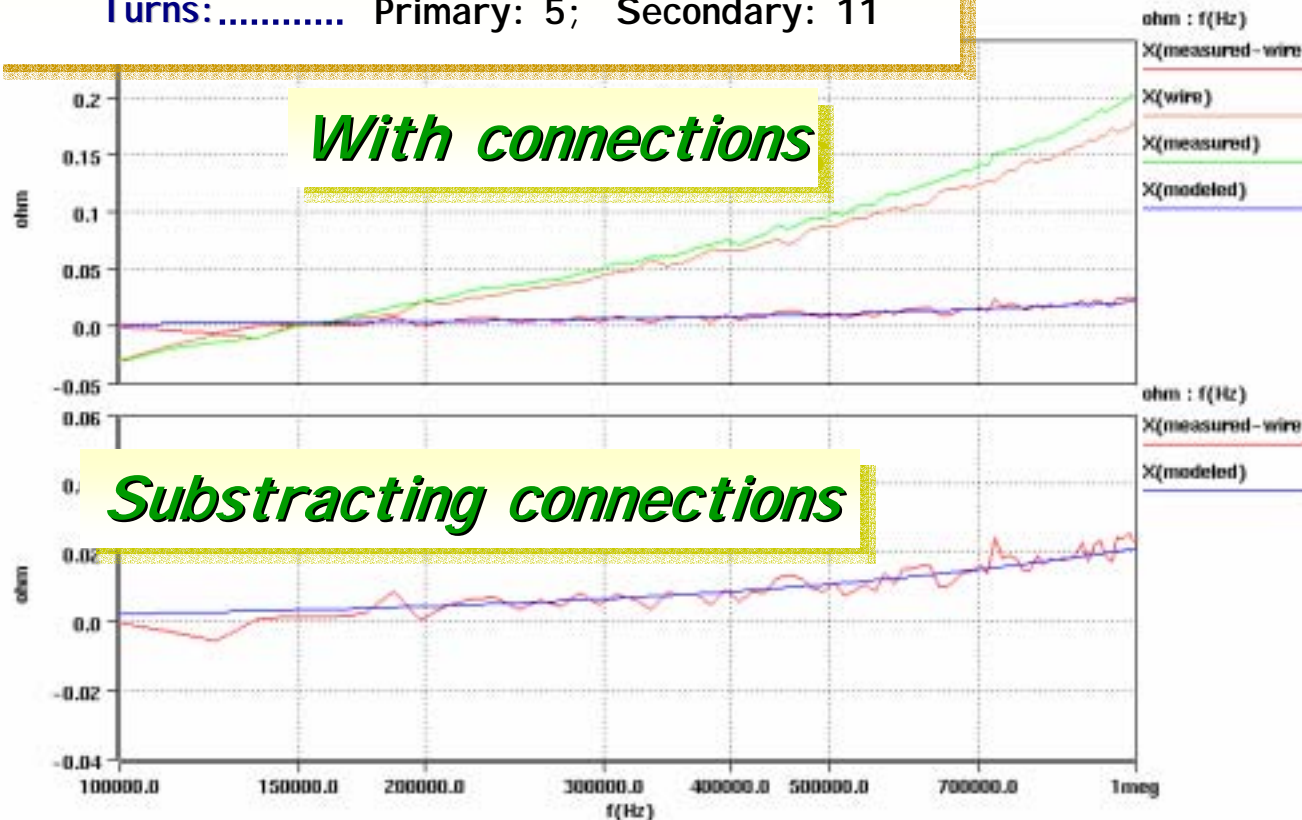
Windings:..... Two in 11 layers

Turns:..... Primary: 5; Secondary: 11

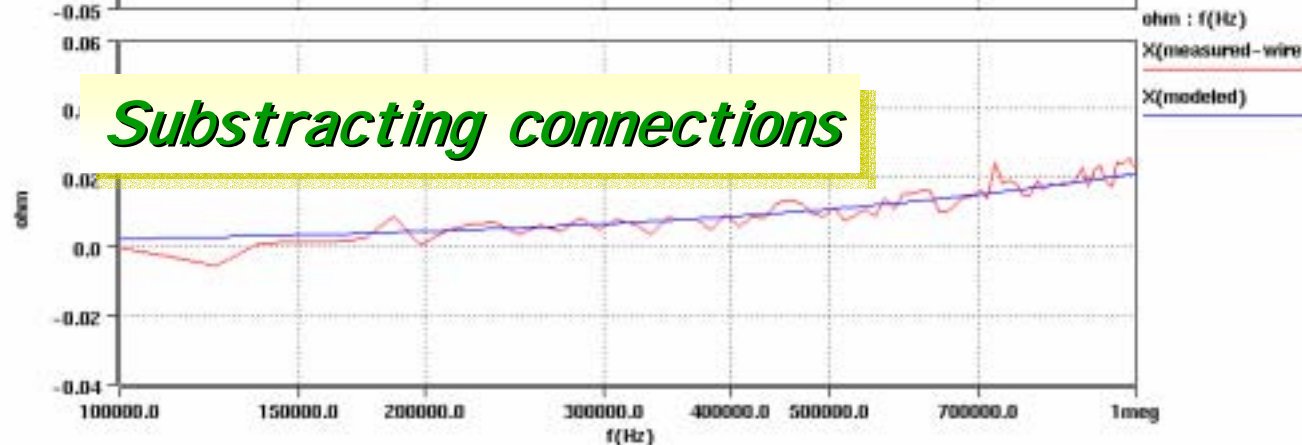
Effect of the connections



With connections



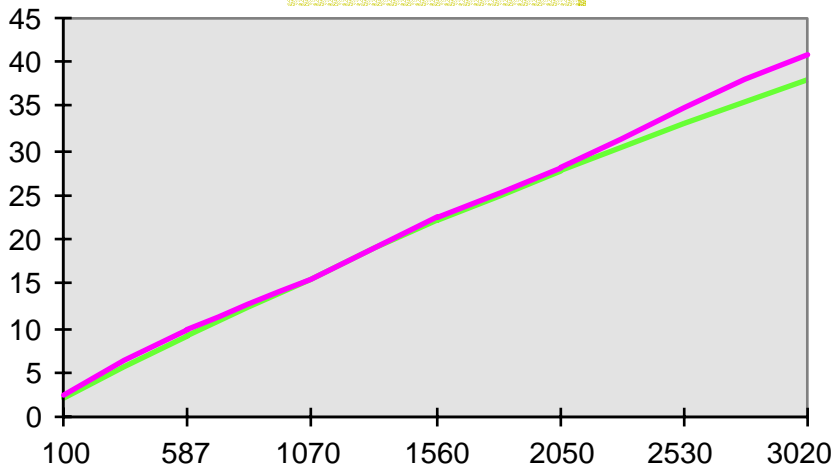
Subtracting connections



Using impedance analyzer instead of FEA

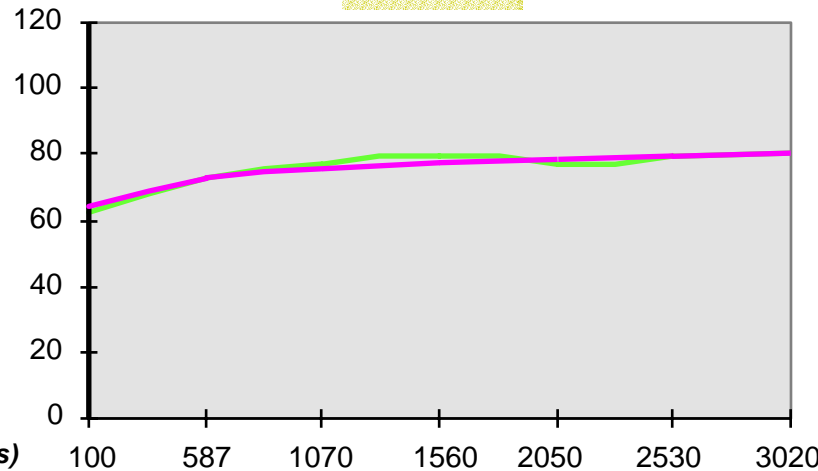
Short circuit test

Magnitude

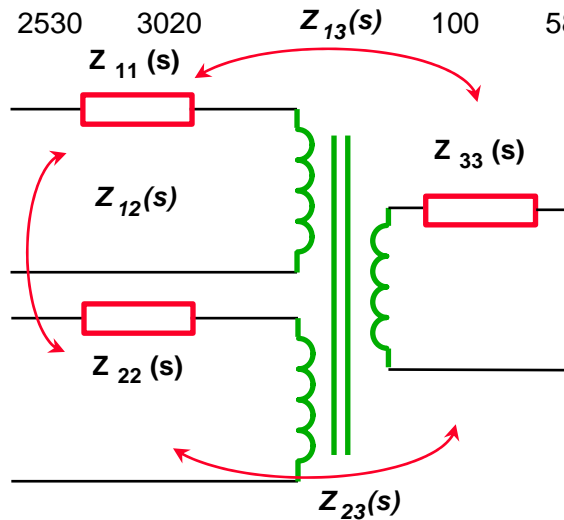


Frequency (kHz)

Phase



Frequency (kHz)



Summary of magnetic component modeling

ADVANTAGES

- Accurate model for the windings, based on a FEA tool or analytical expressions
- All high frequency and geometry effects are taken into account
- Valid for any electrical waveform (not only sinusoidal)
- Valid for both multi-winding transformers and coupled inductors
- Valid for behavioral simulator and for electrical simulators

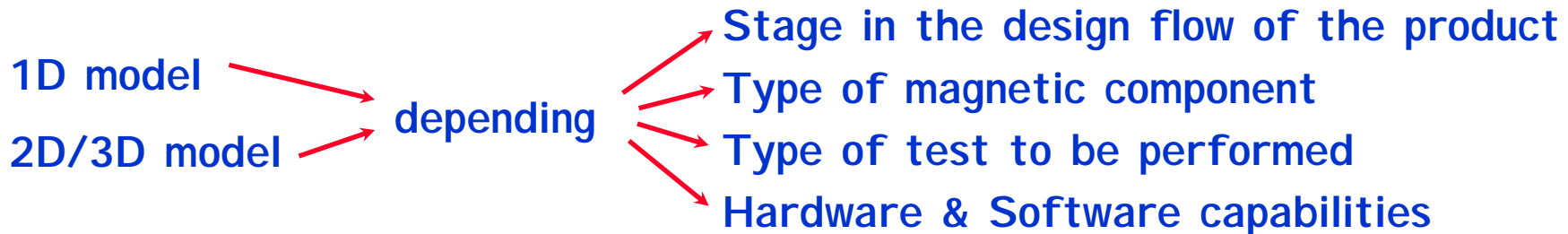
DRAWBACKS

- ☞ 1D model is only applicable when field distributions are uni-dimensional
- ☞ FEA solver needed for 2D/3D models
- ☞ Model generation time for 2D/3D models

Summary of magnetic component modeling

FEATURES

- Several degrees of accuracy have been established:



- Optimization of design process of magnetic components, since models are generated from geometry and material descriptions
- Generate an accurate model from an actual magnetic component
- Check the sensitivity of magnetic components to winding strategies and material properties

4

Advanced design and optimization process

Sensitivity analysis

Flyback transformer

Low profile issues

4.1

Sensitivity Analysis

Sensitivity analysis

GOAL

Quantification of the influence of constructive parameters on the electrical performance

**CONSTRUCTIVE
PARAMETERS**

Interwinding distance

Window height

Airgap

Conductors diameter

Insulator permittivity

Core permeability

Their whole influence

Losses
Magnetic energy
Electric energy

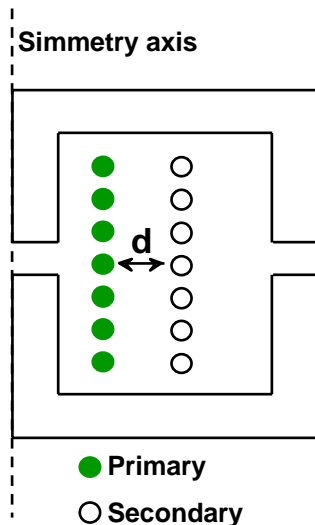
has to be analyzed

Influence of interwinding distance: *on leakage inductance*

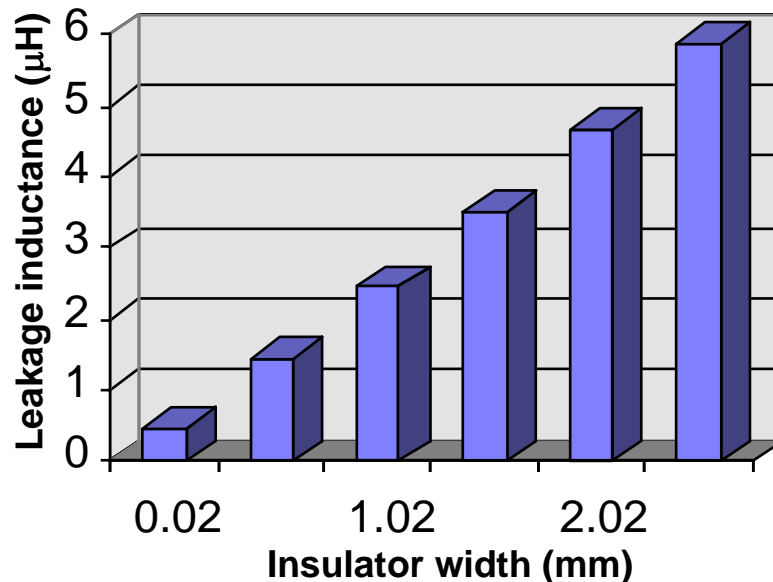
TRANSFORMER STUDIED

Geometric parameters

Core shape and size: RM8
Core material: 3F3
Conductors: Solid, 0.38mm diameter
Windings: Two
Turns: Primary: 20; Secondary: 20
Gap: 0.1mm



Leakage inductance @ 200kHz



Influence of interwinding distance: *on leakage inductance*

TRANSFORMER STUDIED

Geometric parameters

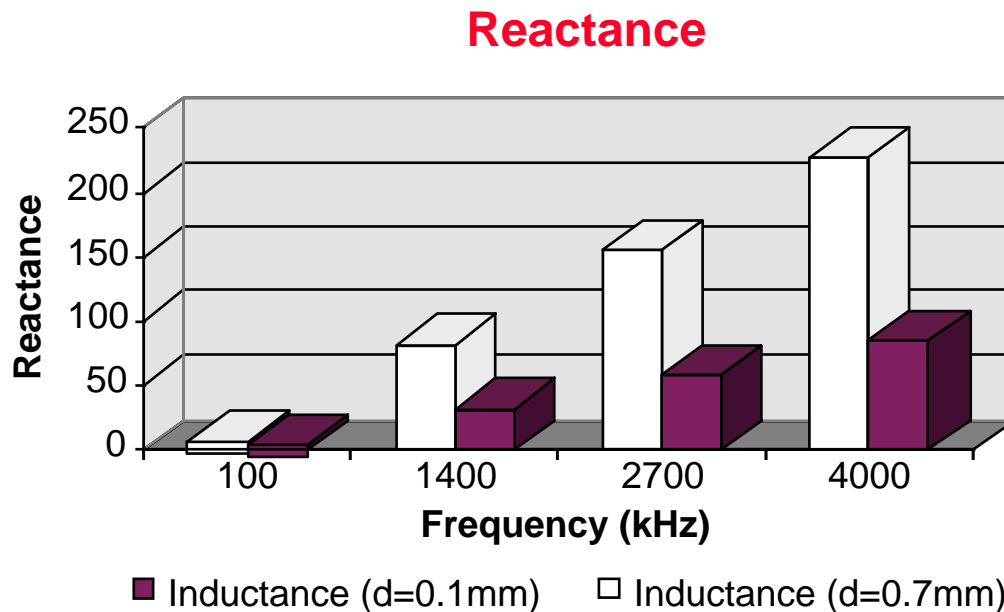
Core shape and size:.....RM14

Core material:.....3C85

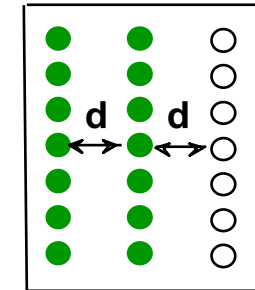
Conductors:.....Solid, 0.8mm diameter

Windings:.....Two in three layers (P:P:S)

Turns:.....Primary: 40; Secondary: 20



Simmetry axis



● Primary

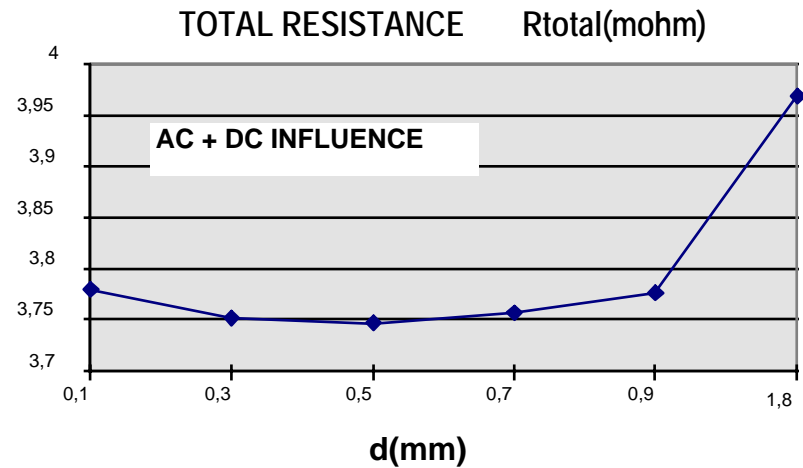
○ Secondary

Influence of interwinding distance . on AC resistance in concentric structures

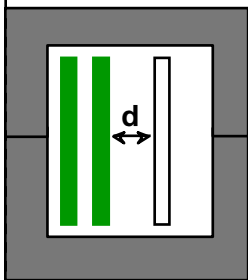
TRANSFORMER STUDIED

Geometric parameters:

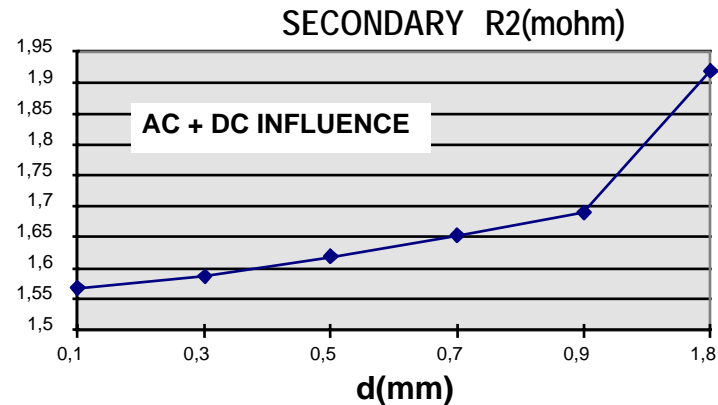
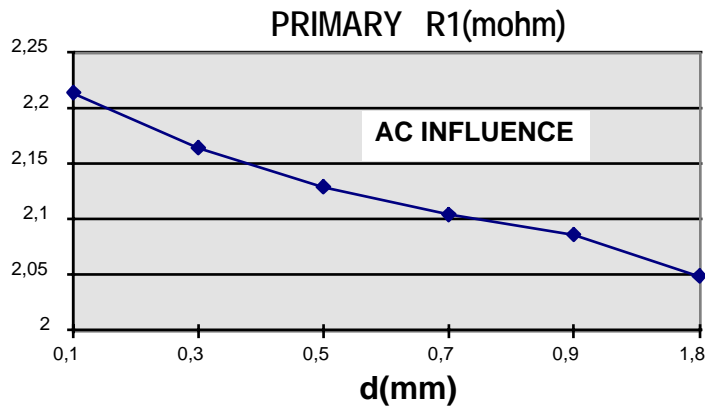
Core shape and size:.....RM10
Core material:..... 3F3
Conductors:Foils, 0.75 mm
Windings:Two
Turns:.....Primary: 2; Secondary: 1
Frequency:100kHz



Simmetry axis



● Primary
○ Secondary



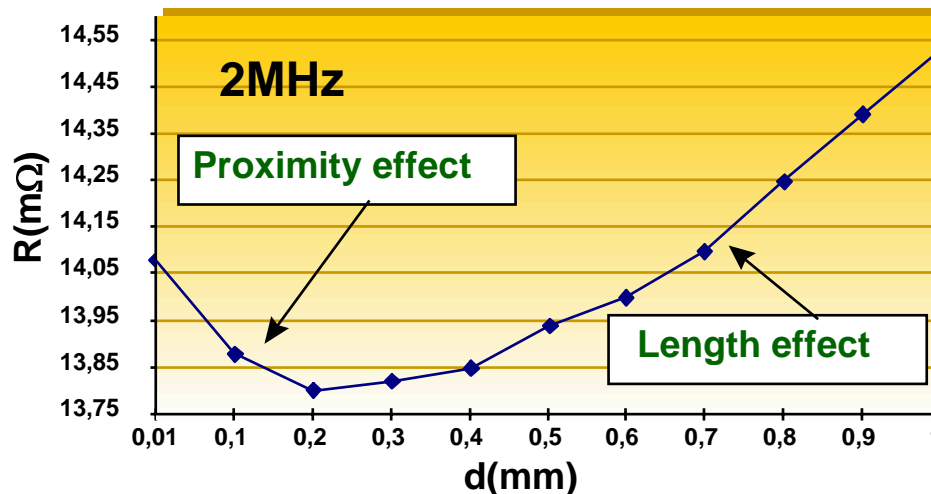
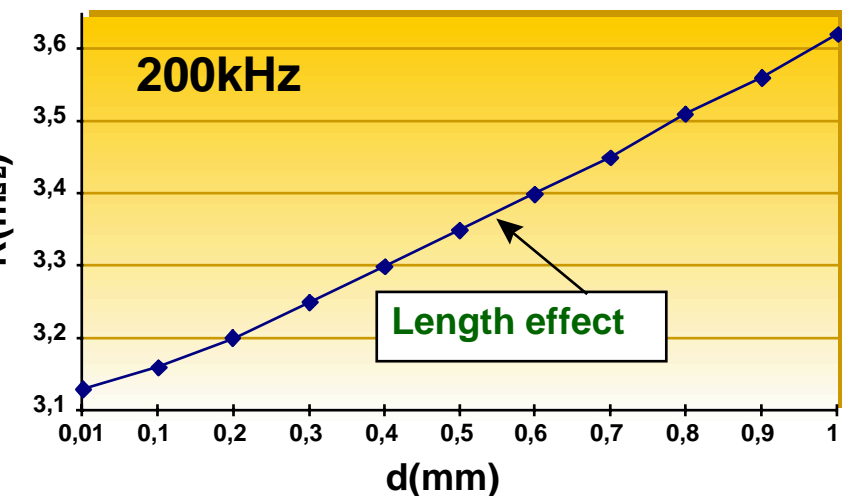
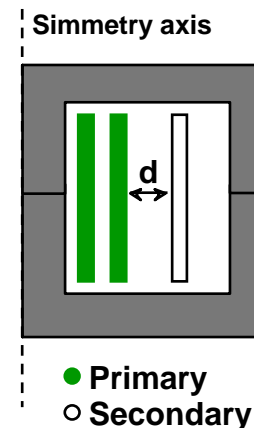
Conductor length must be considered

Influence of interwinding distance : on AC resistance in concentric structures

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:..... RM6
Core material:..... 3F3
Conductors: Foils, 0.2 mm
Windings: Two
Turns:..... Primary: 2; Secondary: 1



For the same structure, the optimum distance depends on the frequency

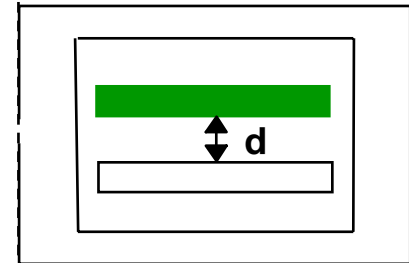
Influence of interwinding distance : on AC resistance in top-down structures

TRANSFORMER STUDIED

Geometric parameters

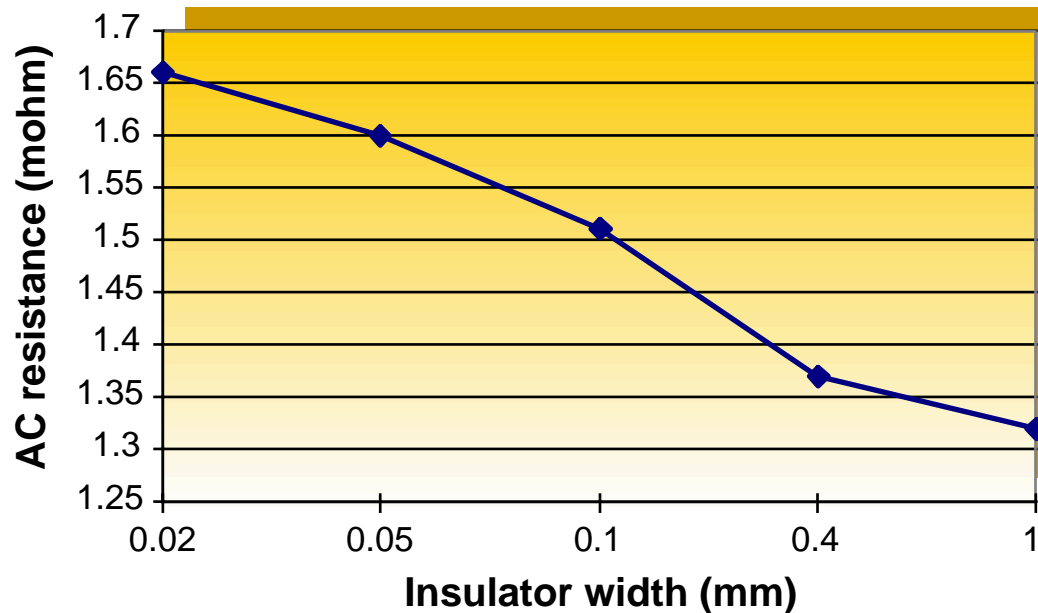
Core shape and size:..... RM8/LP
Core material:..... 3C85
Conductors:..... Foils, 0.2mm
Windings: Two
Turns:..... Primary: 1; Secondary: 1

Simmetry axis



● Primary

○ Secondary



@500kHz

Influence of interwinding distance :

on electric energy

TRANSFORMER STUDIED

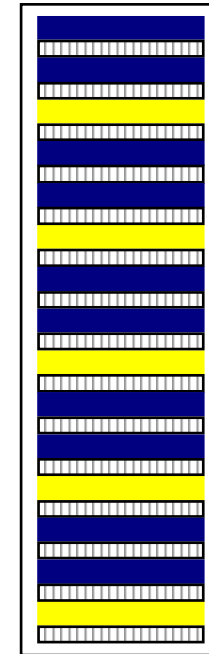
Geometric parameters

Core shape and size:..... RM10
Core material:..... 3F3
Conductors:..... Foils of 70 μ m
Windings:..... Two
Turns:..... Primary: 10; Secondary: 5

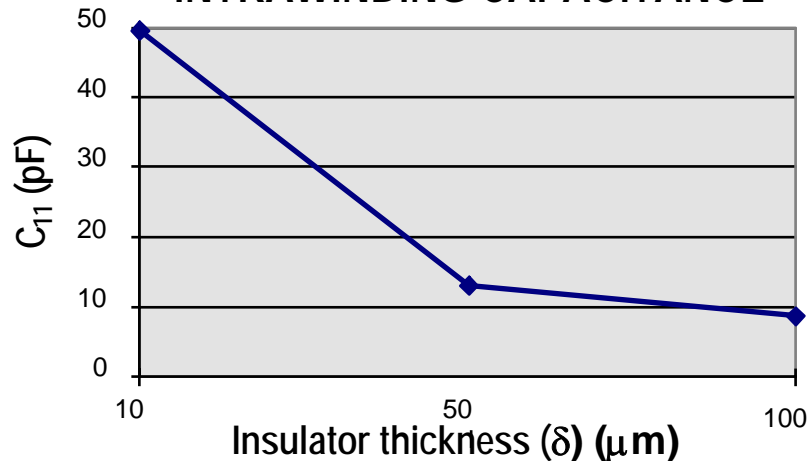
Electric parameters

Insulator relative permittivity:..... 5
Core relative permittivity:..... 1e5

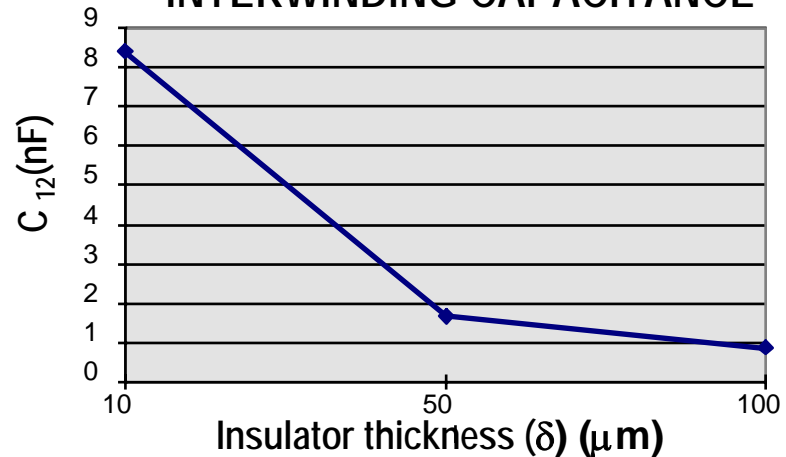
PRIMARY ■■■
SECONDARY ■■■
INSULATOR ■■■



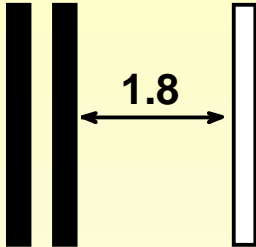


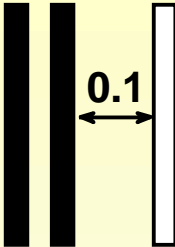
INTRAWINDING CAPACITANCE



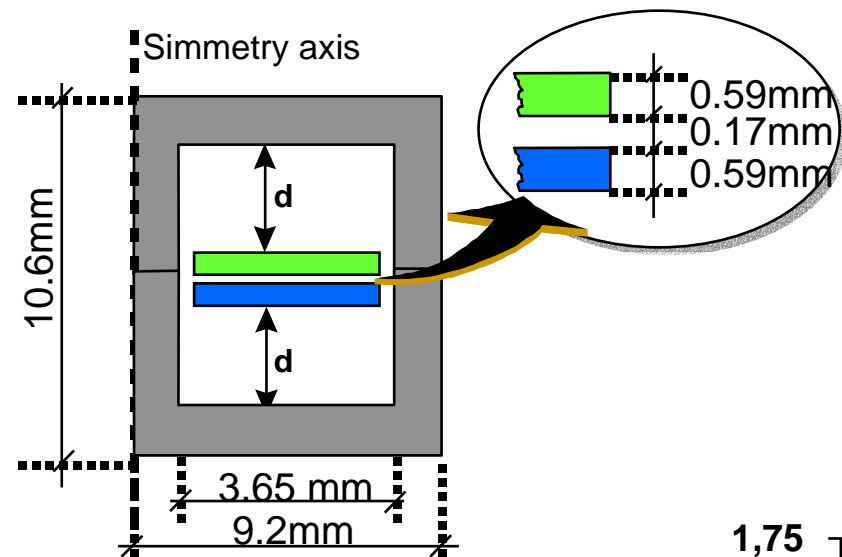
INTERWINDING CAPACITANCE



Influence of interwinding distance on R_{AC} , L_{leak} and C

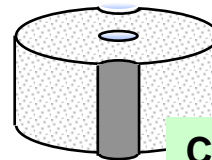
	 	
$R=3.97 \text{ m}\Omega$	4%	$R=3.78 \text{ m}\Omega$
$L_{leak}=50.27 \text{ nH}$	81%	$L_{leak}=9.46 \text{ nH}$
$C=42.80 \text{ pF}$	46%	$C=79.44 \text{ pF}$

Influence of window height

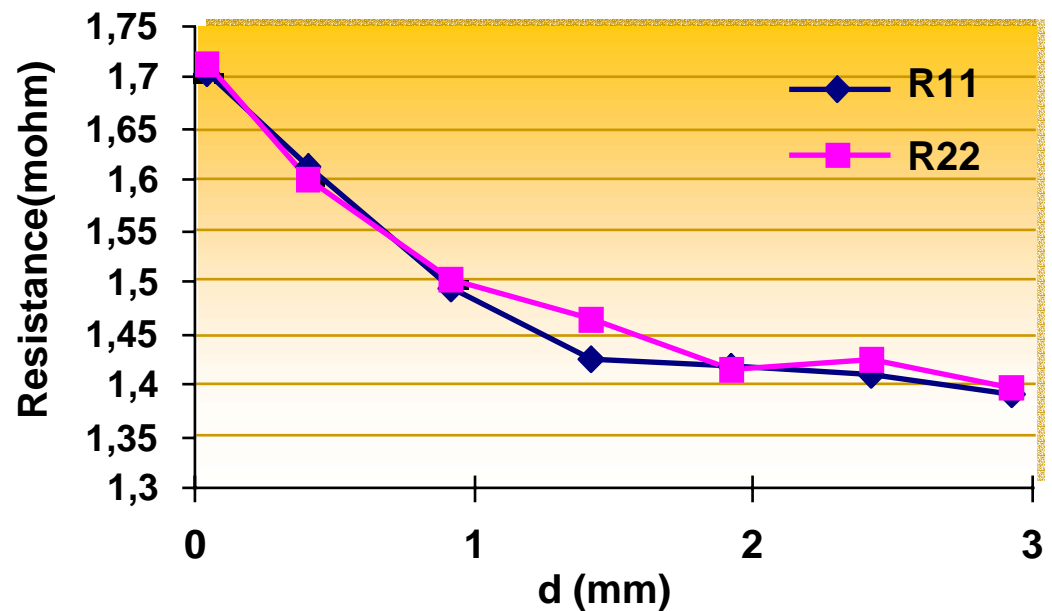


● Primary
● Secondary

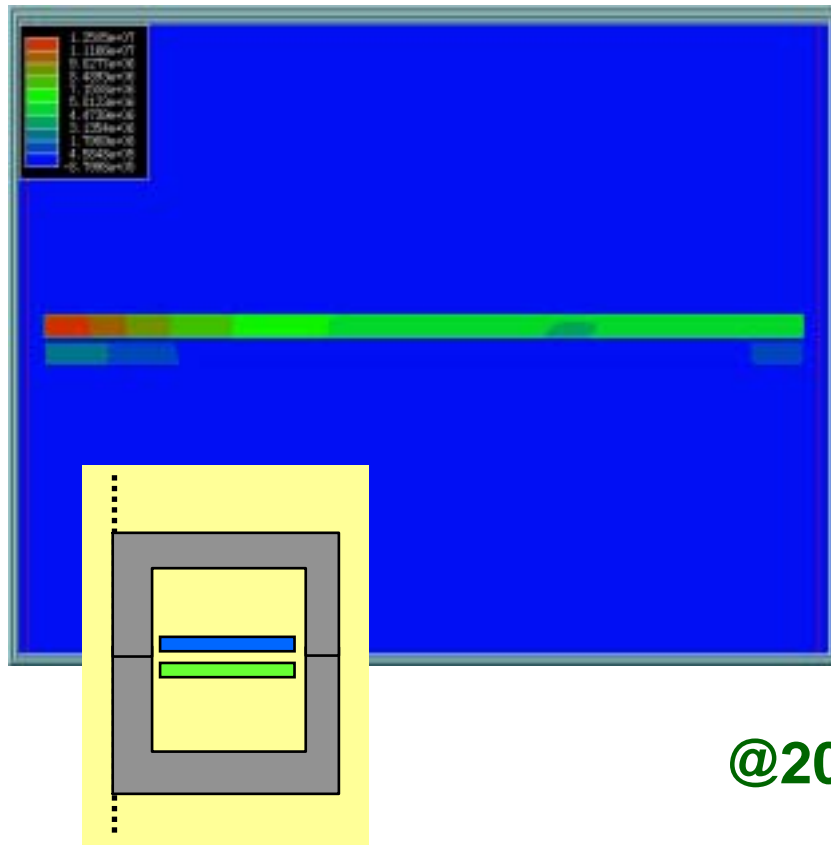
@150kHz



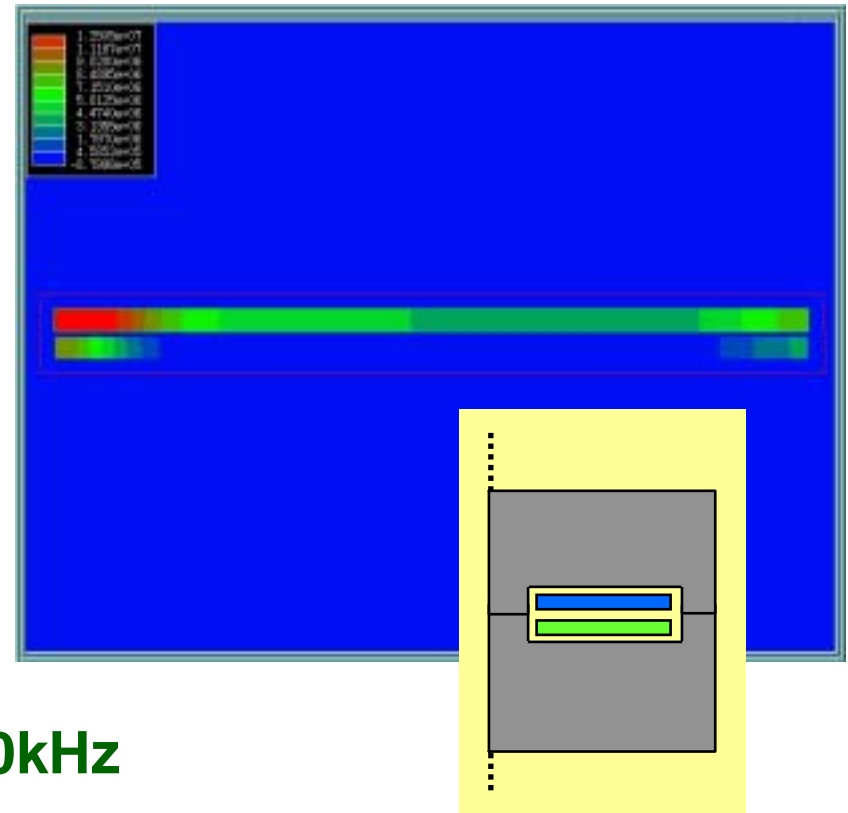
CORE SHAPE: POT
CORE MATERIAL: 3C85



Current distribution in primary winding

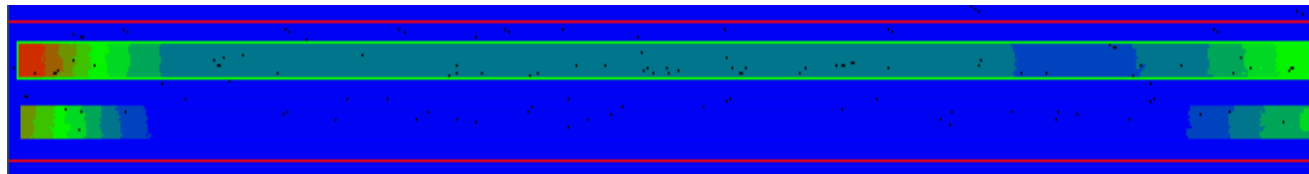
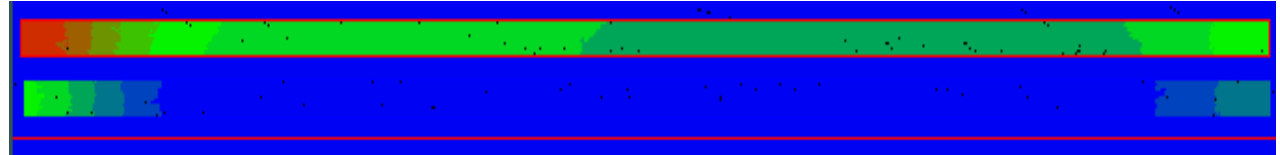
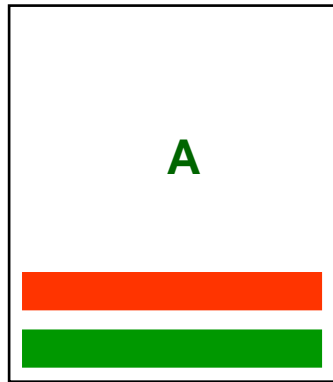


@200kHz



Influence of window height

@200kHz

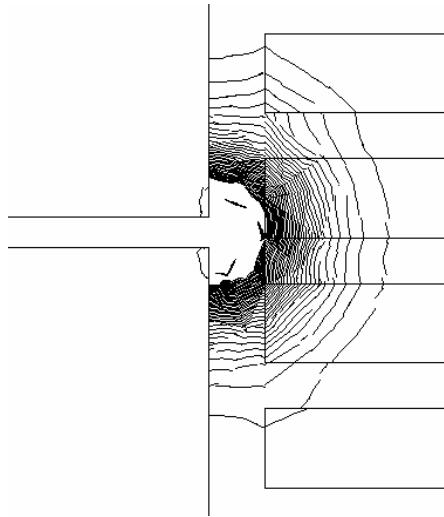


B

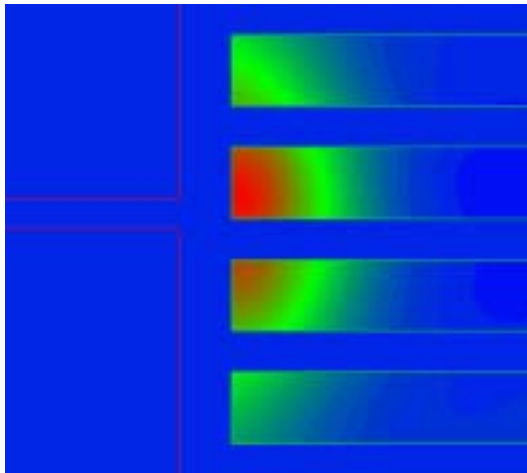
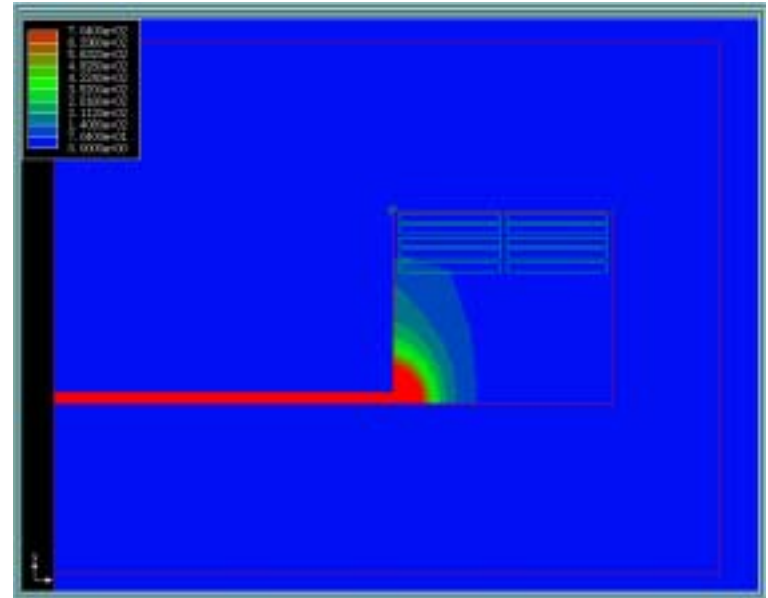


	R11 (mΩ)	R22 (mΩ)	R12 (mΩ)	Rprim (mΩ)	Lleak (nH)
A	3.5	3.65	0.72	5.74	1.69
B	6.32	6.33	3.45	5.74	1.71

Flyback resistance is affected (R11,R22)
but not Forward resistance (Rprim) !!



Fringing flux



**Current density
distribution**

**Fringing flux affects to current distribution
and conduction losses**

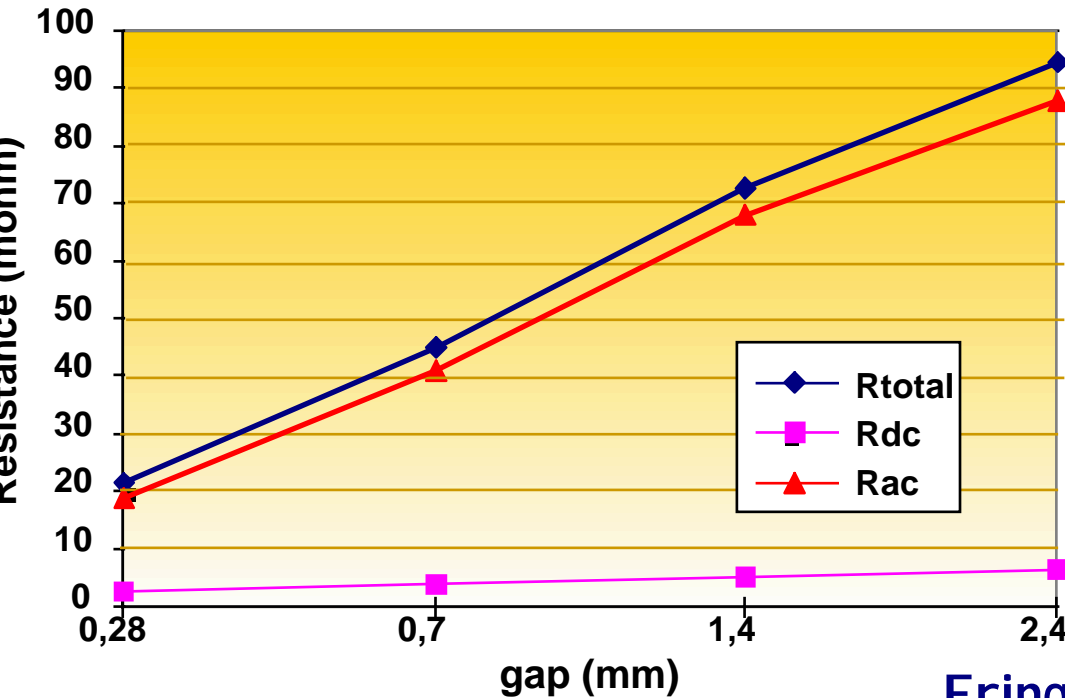
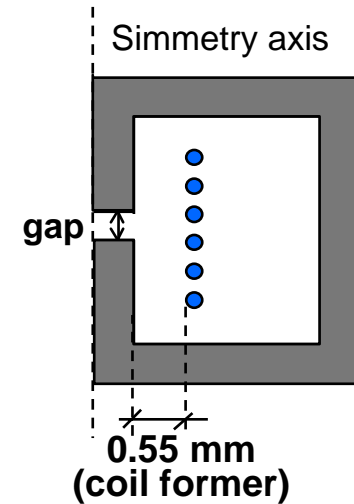
Influence of the air gap:

on the AC resistance

TRANSFORMER STUDIED

Geometric parameters

Core shape and size:.....POT 22/13
Core material:3C85
Conductors:..... Solid, 0.5mm diameter
Windings: One



@150kHz

Test conditions

$L_m = \text{constant}$

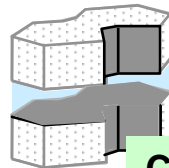
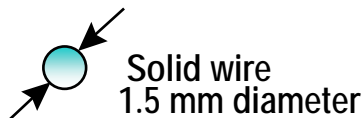
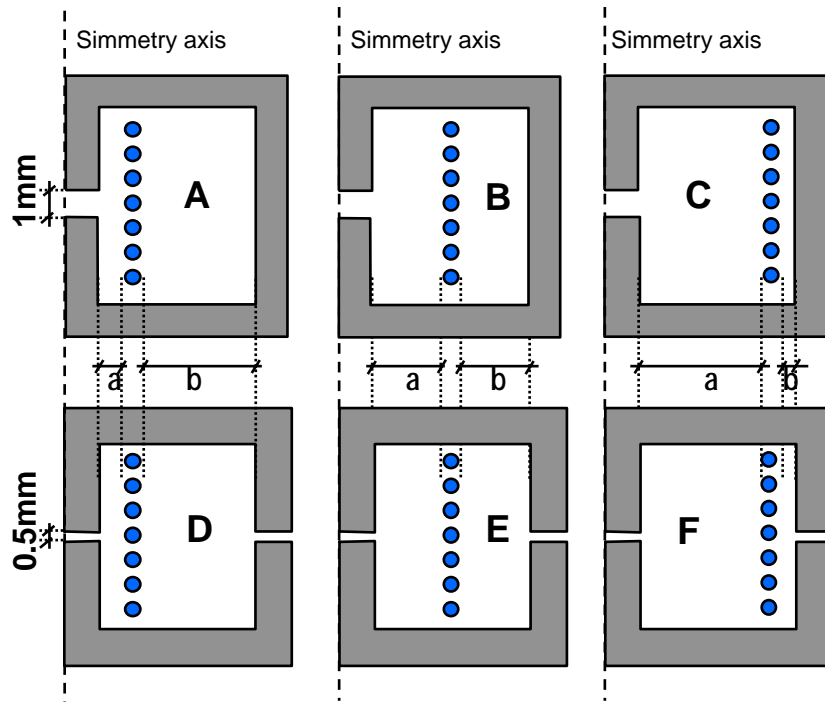
\downarrow
 $n \uparrow$
 \downarrow

$R_{DC} \uparrow$ (length effect)

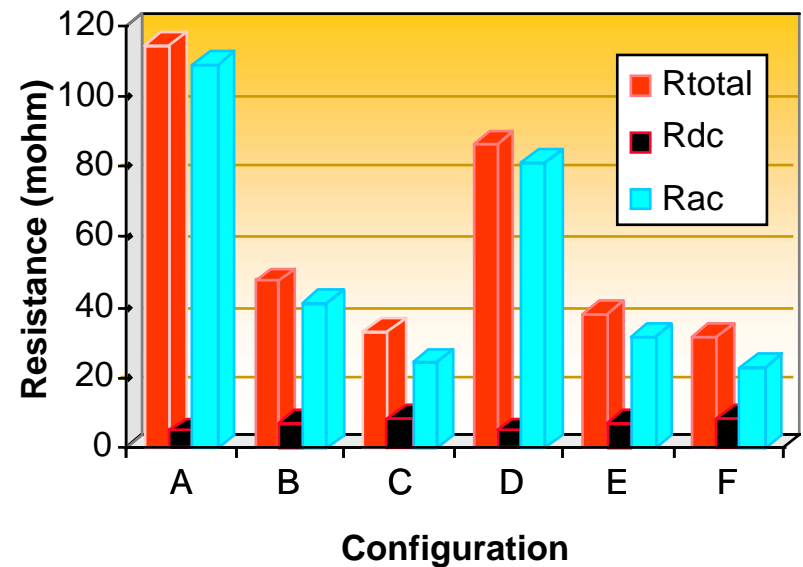
Fringing flux effect is much more important than length effect

Influence of the air gap:

on the AC resistance



CORE SHAPE: RM12
CORE MATERIAL: 3F3



@150kHz

Fringing flux affects to conduction losses

Influence of insulator permittivity

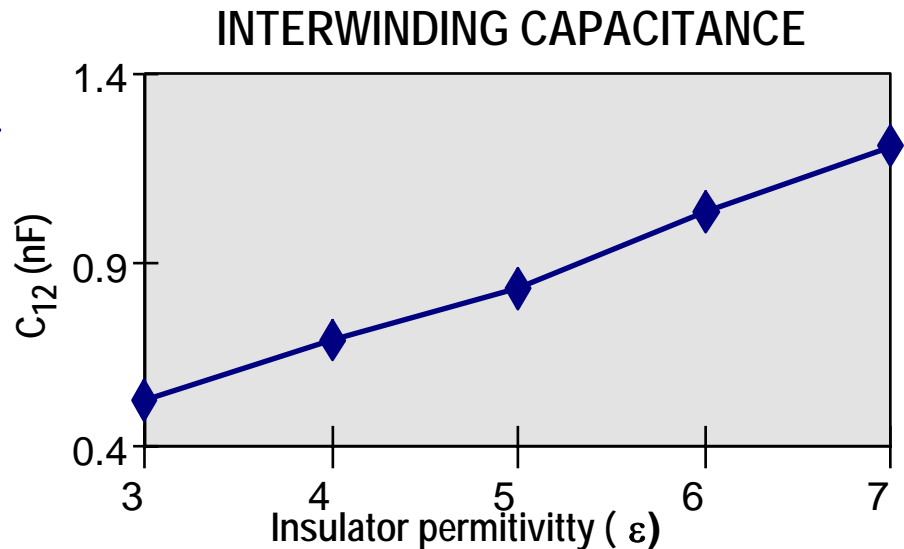
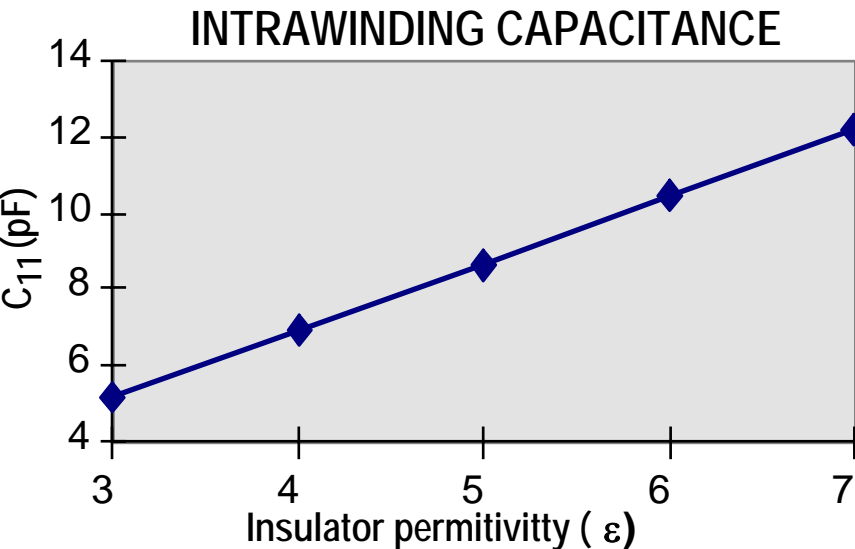
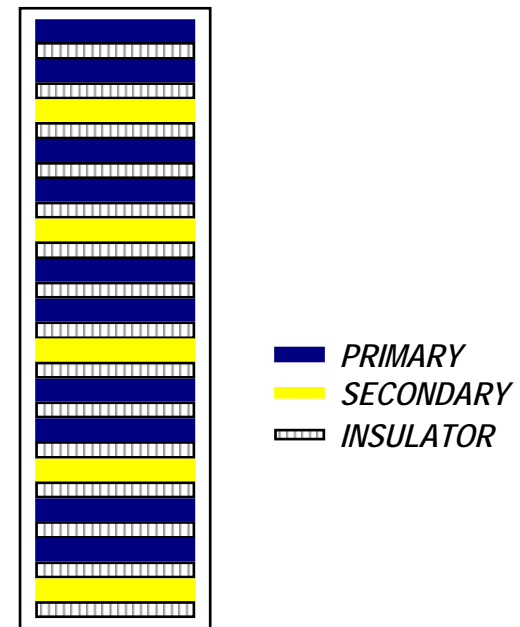
TRANSFORMER STUDIED

Geometric parameters

Core shape and size:..... RM10
Core material:..... 3F3
Conductors:..... Foils of 70 μ m
Windings:..... Two
Turns:..... Primary: 10; Secondary: 5
Insulator thickness:..... 100 μ m

Electric parameters

Core relative permittivity:..... 1e5

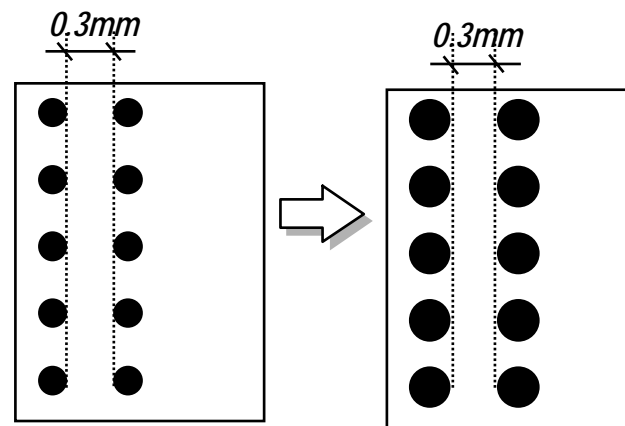


Influence of conductors diameter on AC resistance and leakage inductance

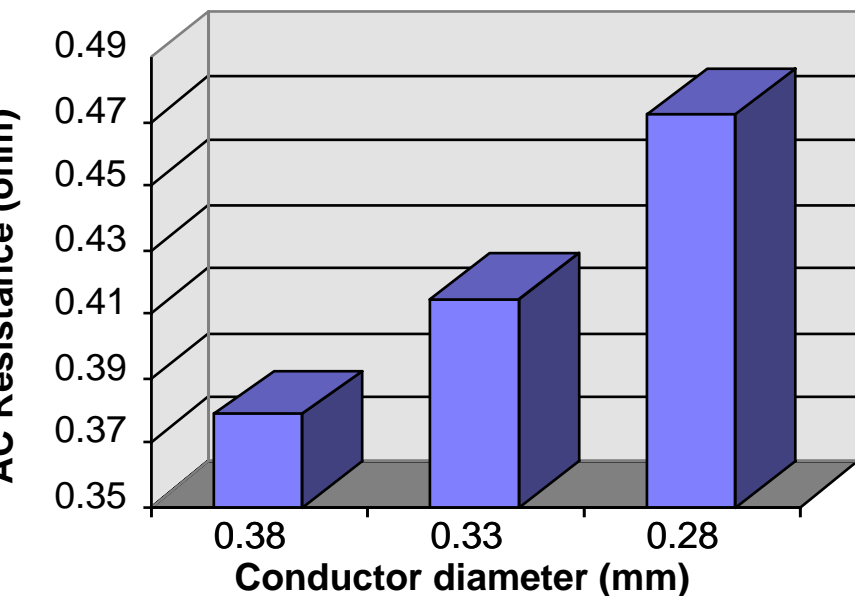
TRANSFORMER STUDIED

Geometric parameters

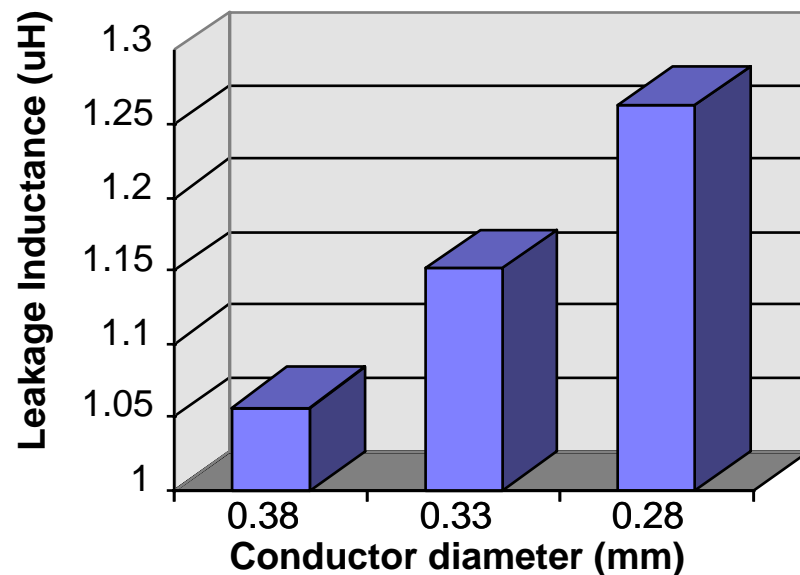
Core shape and size:	RM8
Core material:	3F3
Conductors:	Solid
Windings:	Two
Turns	Primary: 20; Secondary: 20
Winding thickness:	0.3 mm



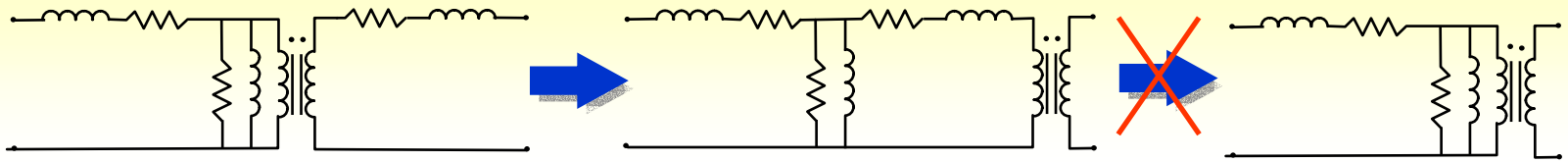
Resistance (ohm) @ 200kHz



Inductance (μH) @ 200kHz



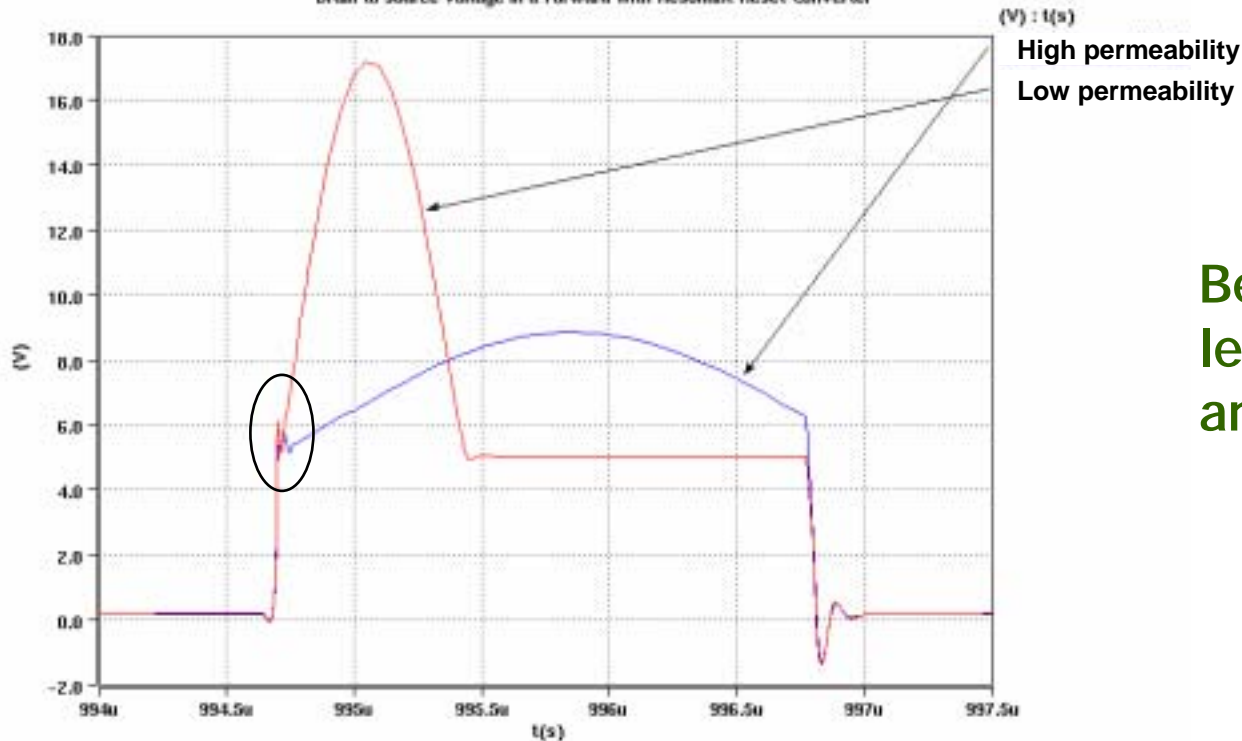
Influence of core permeability



A short circuit test and open circuit test
do not account for L_{leak} and L_m if μ_{core} is too low

V_{DS} in main switch

Drain to source voltage in a Forward with Resonant Reset Converter



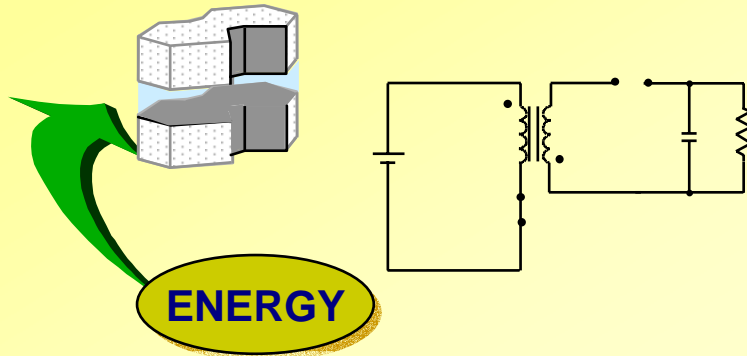
Better to quantify
leakage energy on
an actual converter

4.2

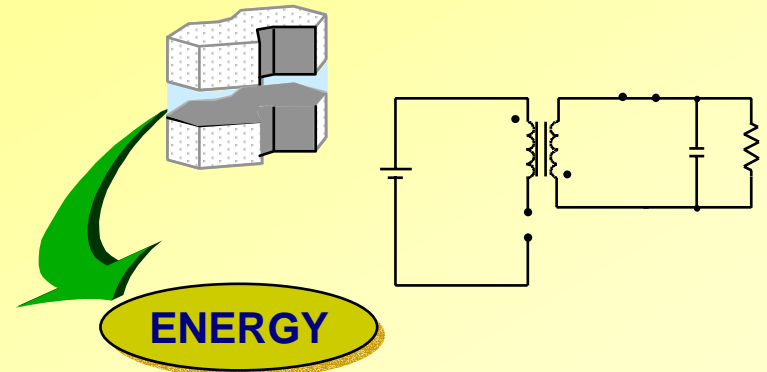
Flyback transformer

Electrical Description of Flyback Transformer

ON TIME



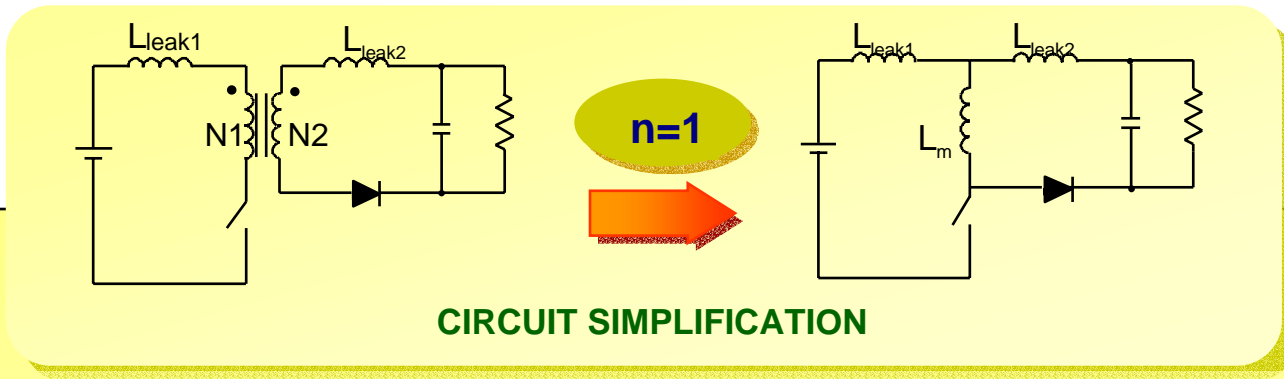
OFF TIME



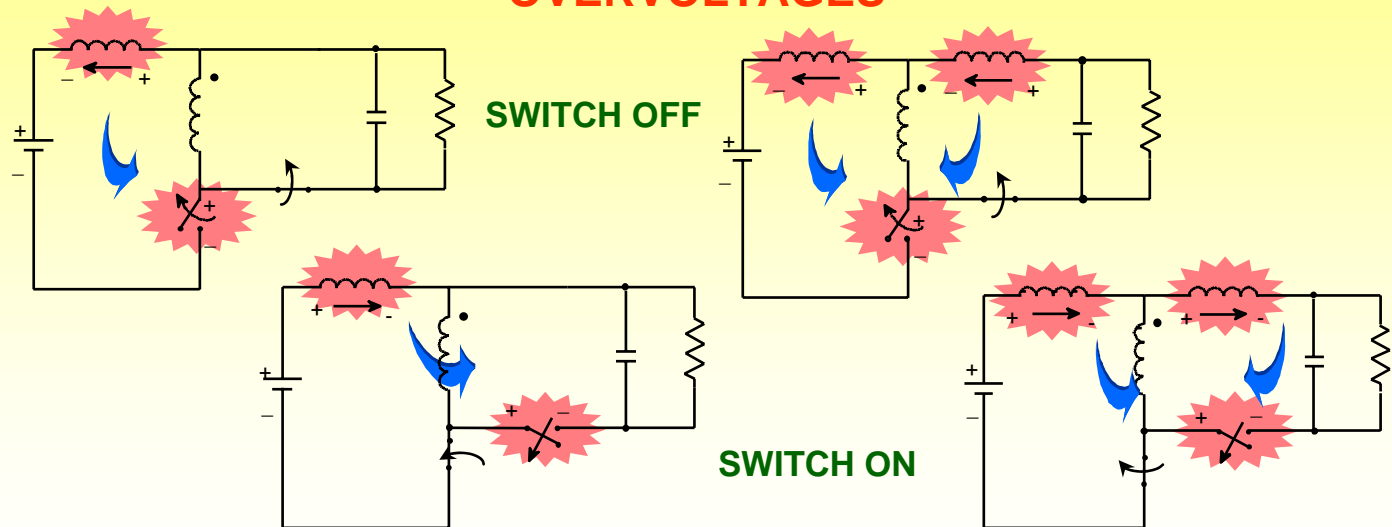
MAIN FEATURES

- Design in order to store energy
- Gap is usually needed
- Energy storage mainly in the gap
- Current is not flowing in both windings at the same time

Electrical study of flyback topology

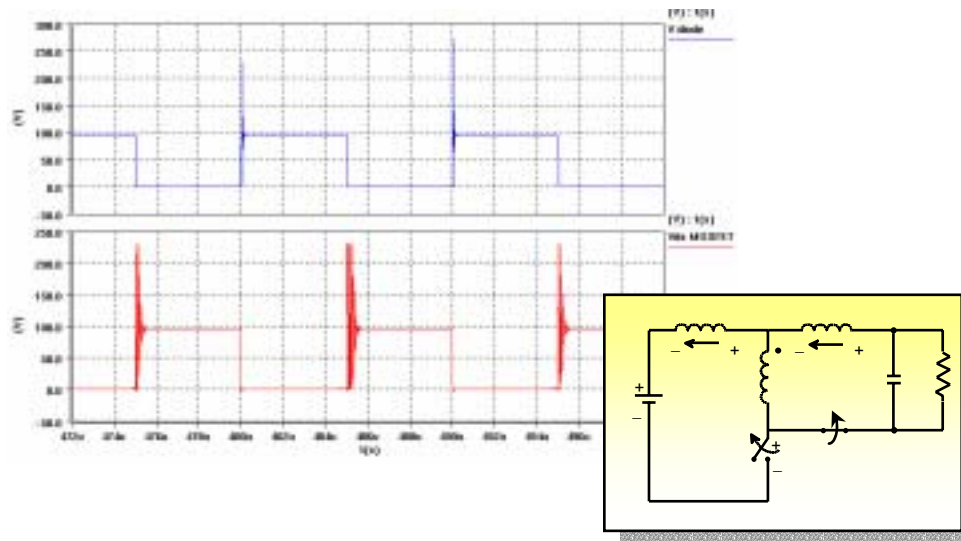
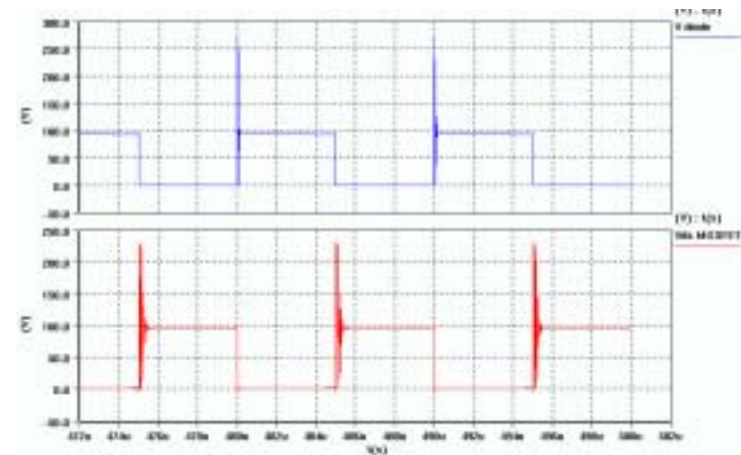
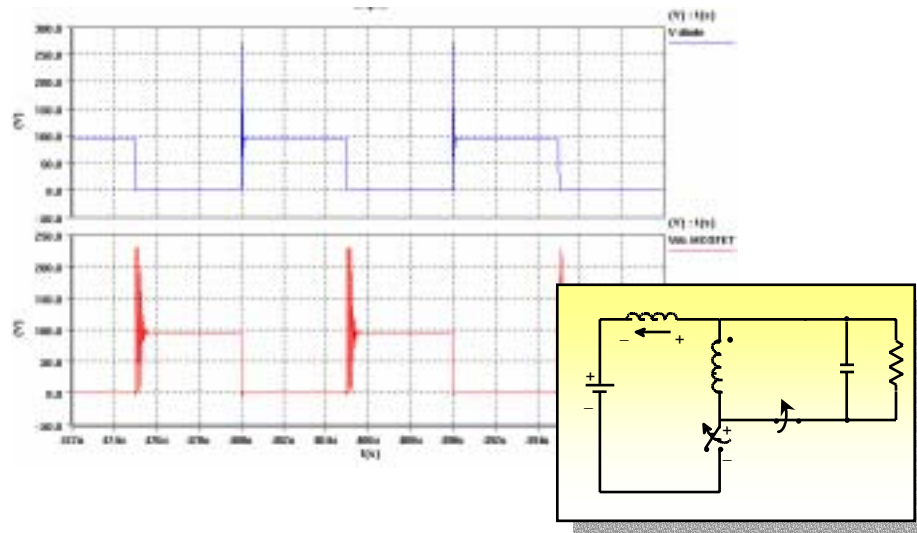


OVERVOLTAGES



The leakage inductance of any winding has influence on MOSFET and diode voltages

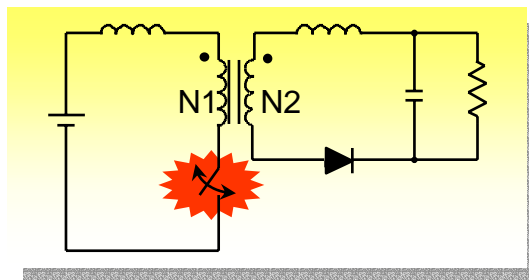
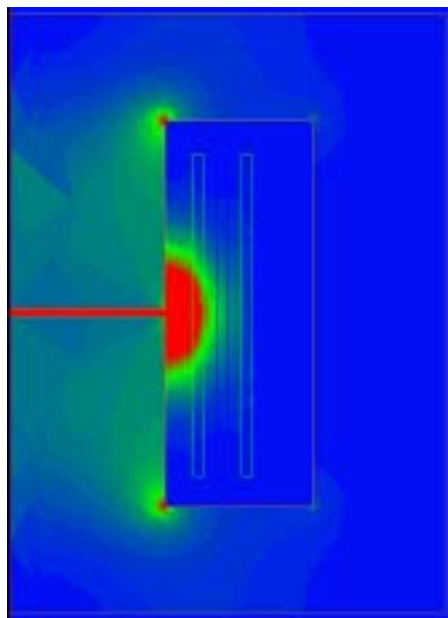
Electrical study of flyback topology



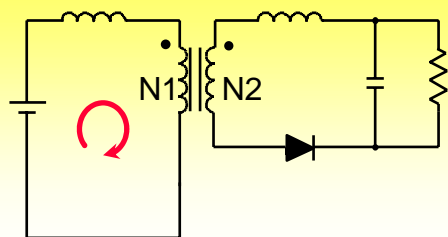
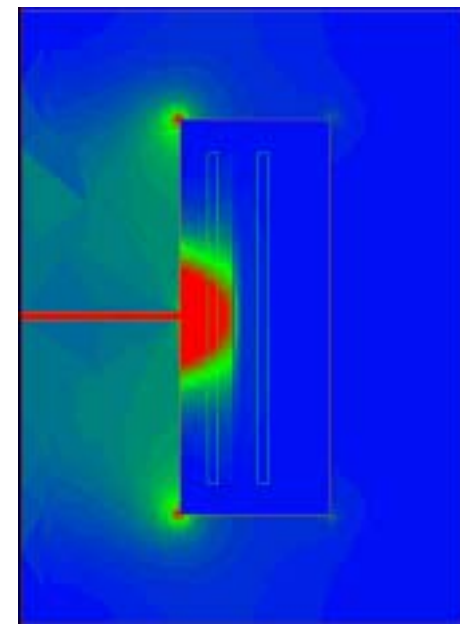
MAIN TARGET
Reduced overall
leakage inductance

Study of the fields: leakage inductance

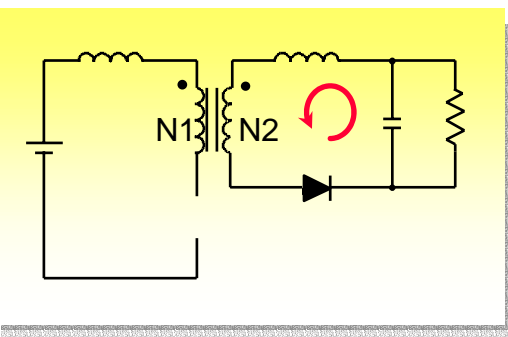
ENERGY 1



ENERGY 2



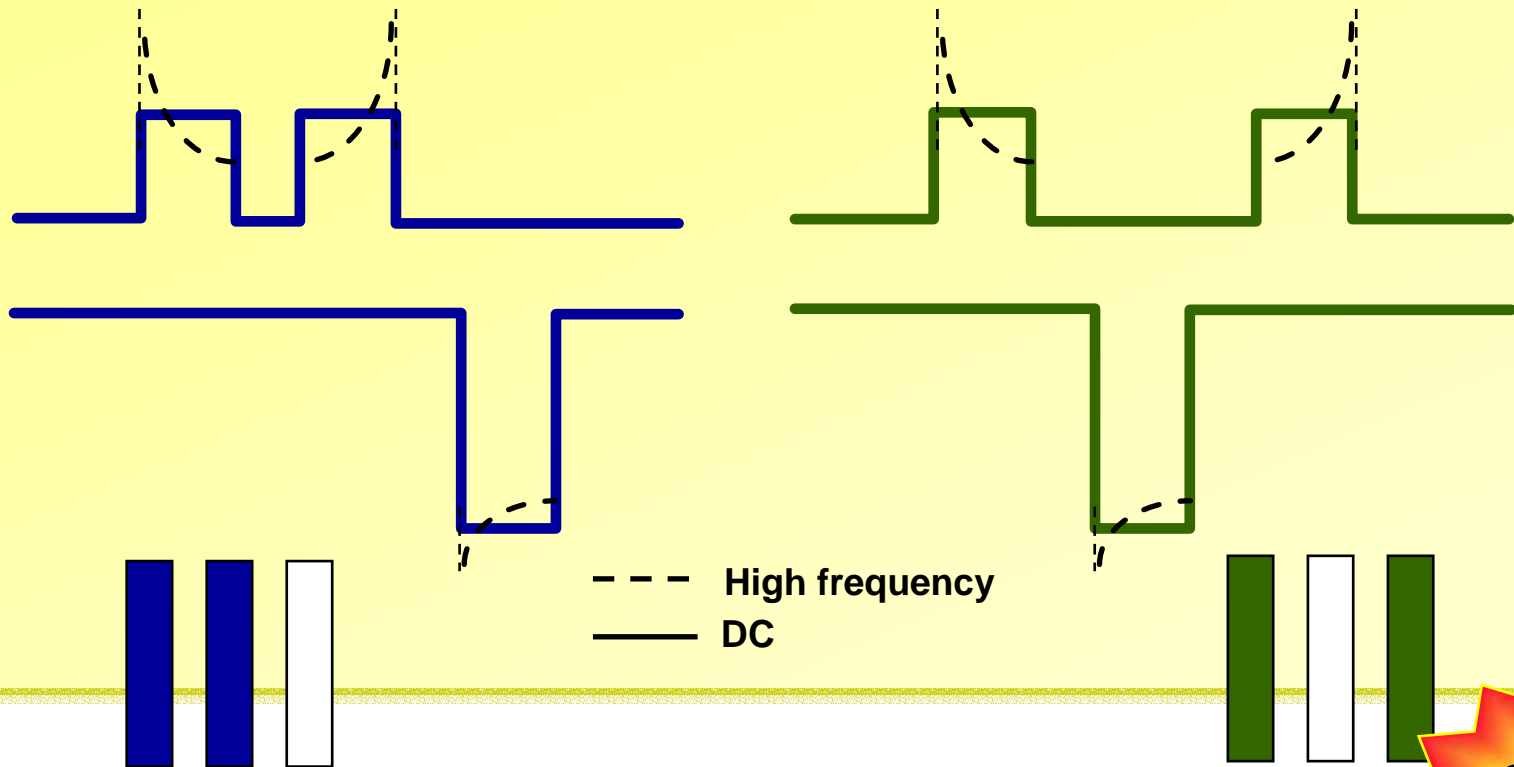
ENERGY 1 - ENERGY 2 =
LEAKAGE ENERGY



Goal: minimization of this energy

Interleaving in flyback type transformers

AC resistance



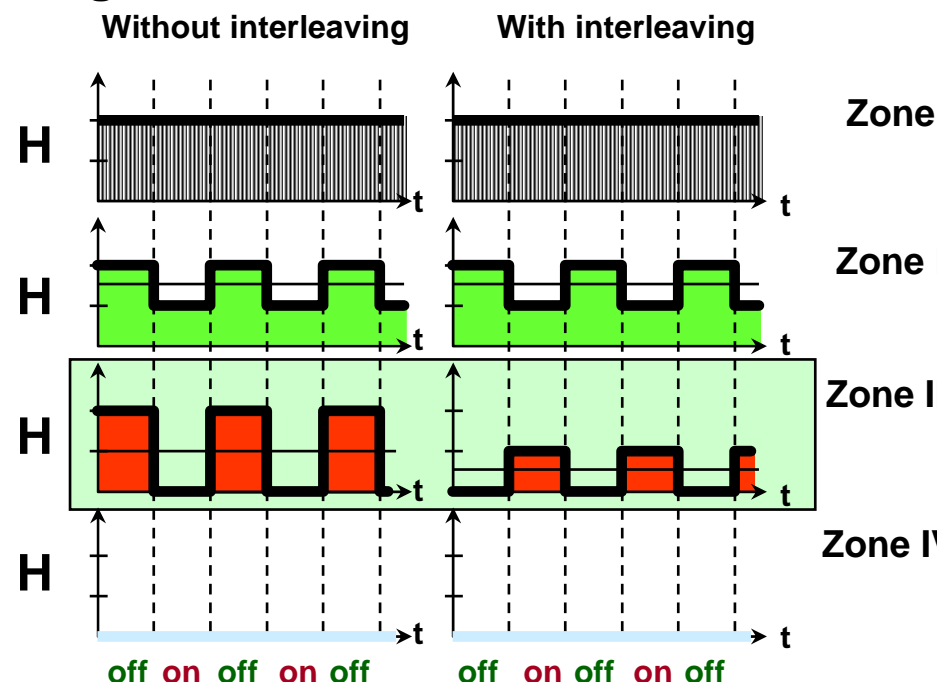
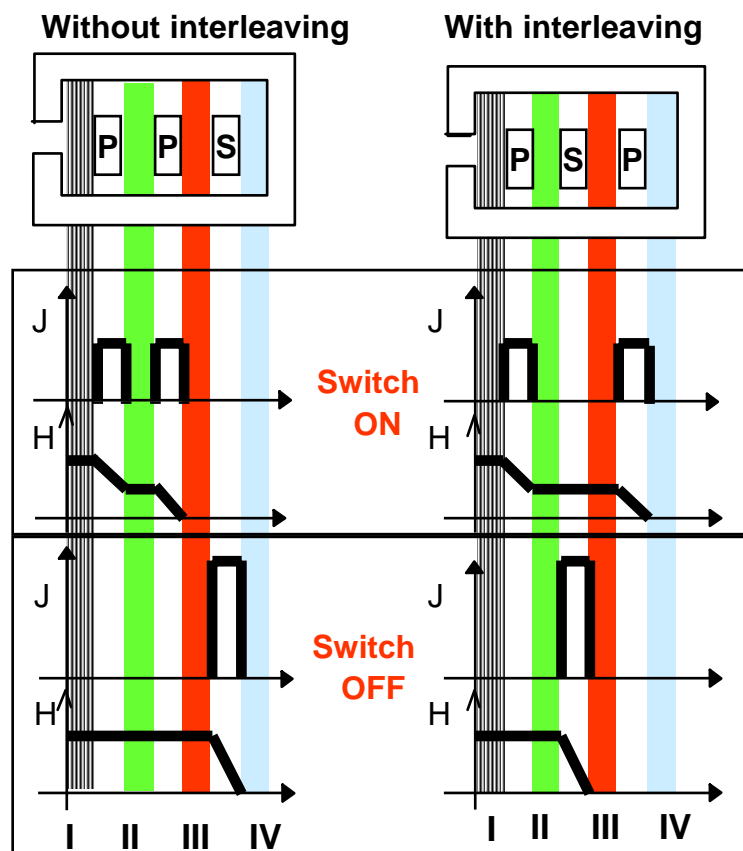
**No AC resist.
reduction**

Interleaving in flyback type transformers

Leakage inductance

➤ Magnetic field distribution

- ✓ Low improvement during on and off states
- ✓ High improvement in the switching times



- × Same current distribution
- × H field distribution very similar (small differences in several parts of the window)

Interleaving in flyback type transformers

Forward type

- Energy transfer
- Interleaving
 - ✓ **Lower R_{AC}**
 - ✓ **Lower Energy in the window**
 - ✓ **Lower L_{LEAK}**

Flyback type

- Energy storage
- Interleaving
 - ✓ **Similar R_{AC}**
 - ✓ **Similar Energy in the window**
 - ✓ **Lower L_{LEAK}**

RECOMMENDED IN BOTH TYPES

- **Increase of cross regulation capabilities**
- **Reduction of size**

4.3

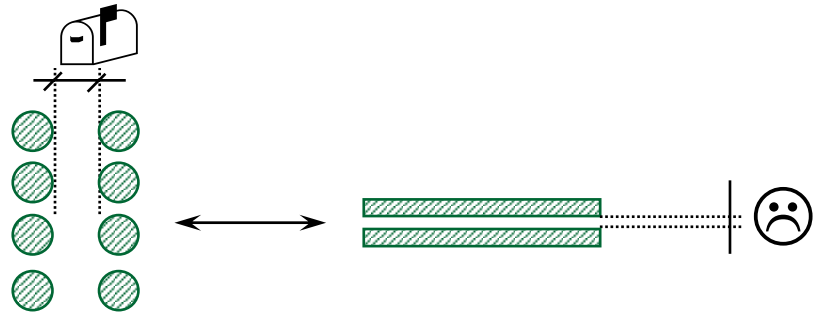
Low profile issues

Low profile

- The use of planar transformers is growing in the last years

WHY?

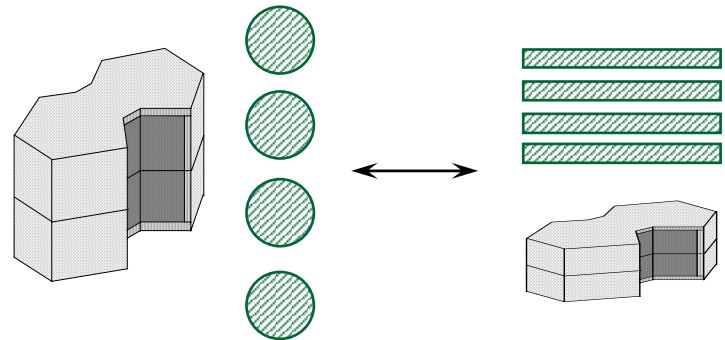
☺ Leakage inductance Reduction



☺ AC Resistance Reduction



☺ Size Reduction



Low profile

WHY NOT?



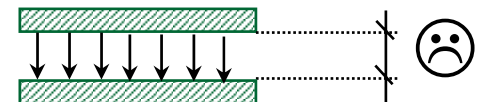
Technological step



Thermal management

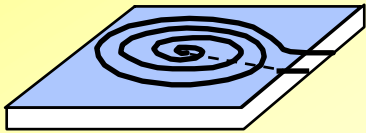


High capacitive effects



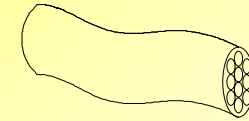
Planar structures vs Traditional structures

Planar transformer

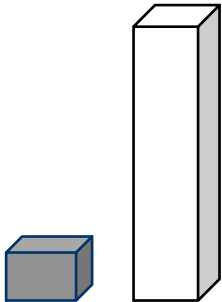


Qualitative comparison
(based on actual measurements)

Litz wire

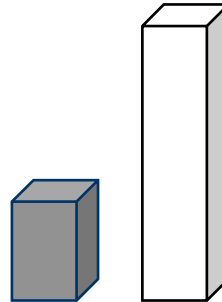


**Lower
leakage inductance**



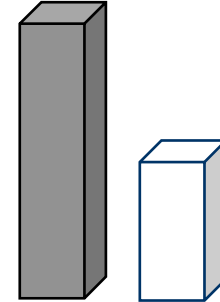
Reduction: 1:5

**Lower
AC Resistance**



Reduction: 1:3

**Higher
capacitance**



Increase: 2:1

Example

Transformer description Core size: RM10

—PRIMARY: 12 turns

—SECONDARY: 2 turns: Center tapped (Half-Bridge)

Comparison criteria: maximum current density (7.5A/mm^2)

LITZ WIRE

Primary: Litz wire (80x0.07 mm)
Secondary: Litz wire (800x0.07 mm)

2380 nH



360 mΩ



19pF



79%

Occupied window area



PLANAR

Primary: 0.276 mm^2
Secondary: 3.08 mm^2

480 nH

119 mΩ

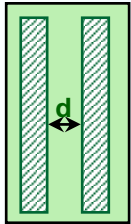
42pF

30%

Layers separation

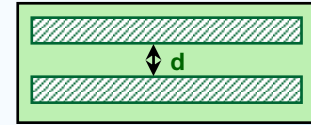
RESISTANCE

CONCENTRIC TRANSFORMERS



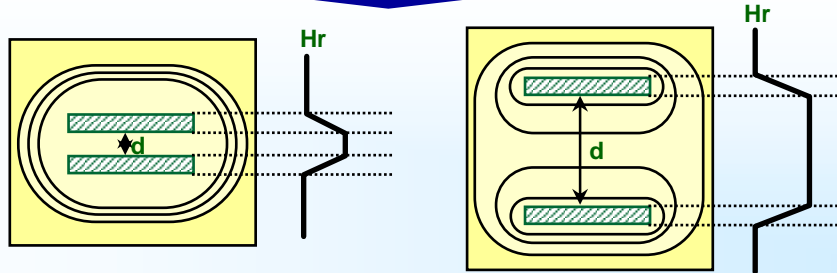
$\uparrow d \Rightarrow$
 $\uparrow R_{DC}$ and $\downarrow R_{AC}$
 $\Rightarrow R = ??$

TOP-DOWN TRANSFORMERS (planar)



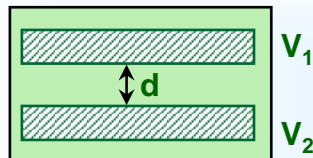
$\uparrow d \Rightarrow \downarrow R_{AC}$ and $R_{DC} \approx \Rightarrow \downarrow R$

LEAKAGE INDUCTANCE



$\uparrow d \Rightarrow \uparrow \text{Energy in the window} \Rightarrow \uparrow \text{Leakage inductance}$

ELECTRIC ENERGY

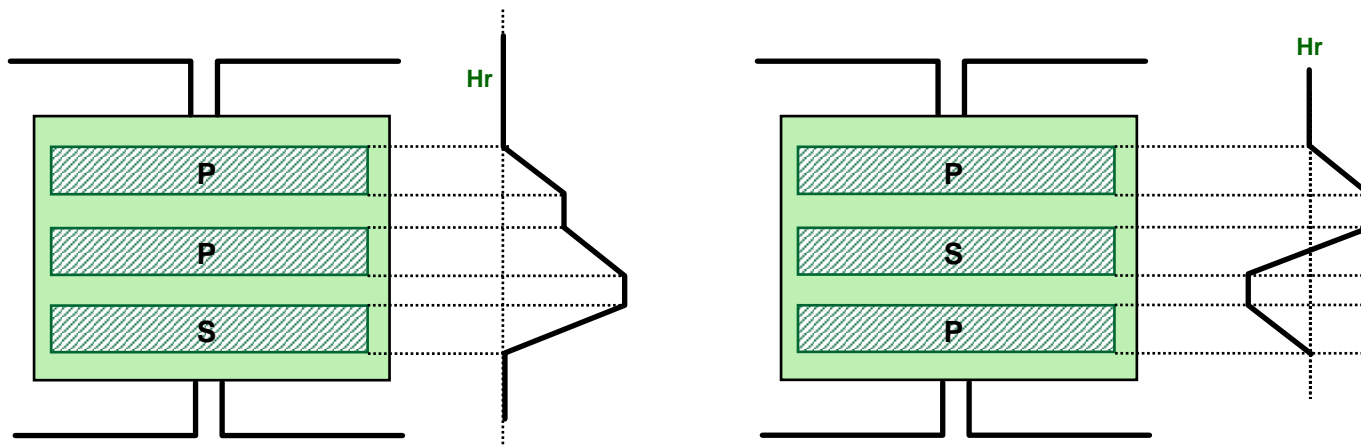


$\uparrow d \Rightarrow \downarrow C$ $C \approx \frac{S}{d}$

Interleaving in low profile transformers

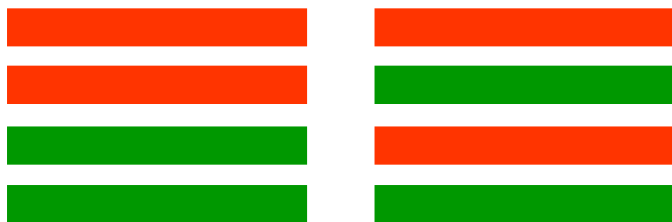
Interleaving improvements

- Reduction of leakage inductance due to:
 - ✓ Lower energy in the window
- Reduction of AC resistance due to:
 - ✓ Optimization of current distribution in the conductors
(NOT IN FLYBACK TYPE TRANSFORMERS!!)



Comparison of different winding strategies

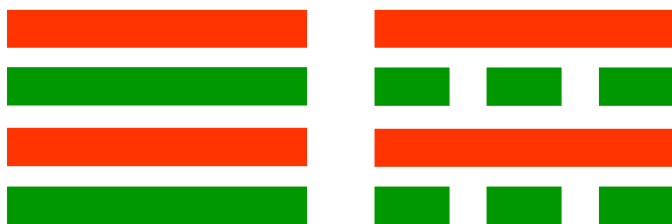
@200kHz



A

B

Do interleaving!!
(but care about insulator thickness)



B

C

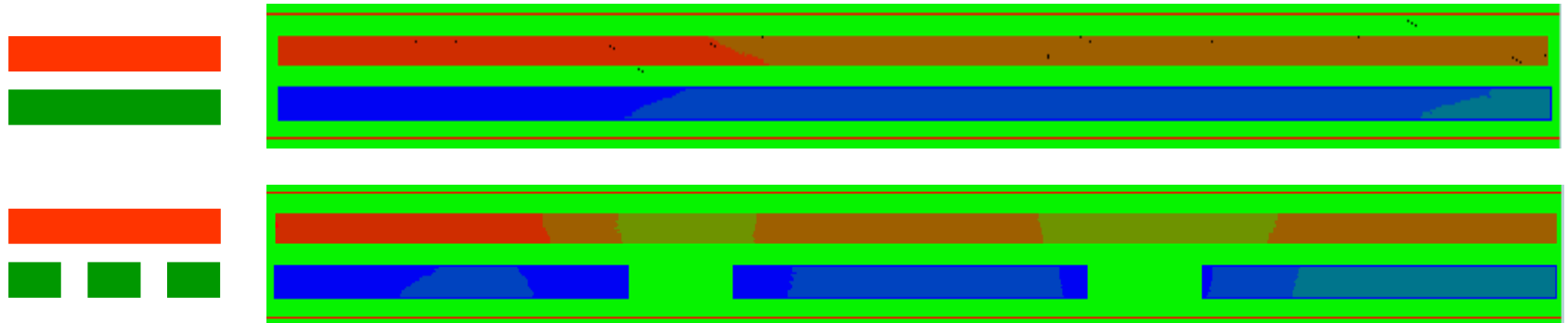
Do not split the track!

	R (mΩ)	Lleak (nH)
A	3.44	2.63
B	3.07	0.59

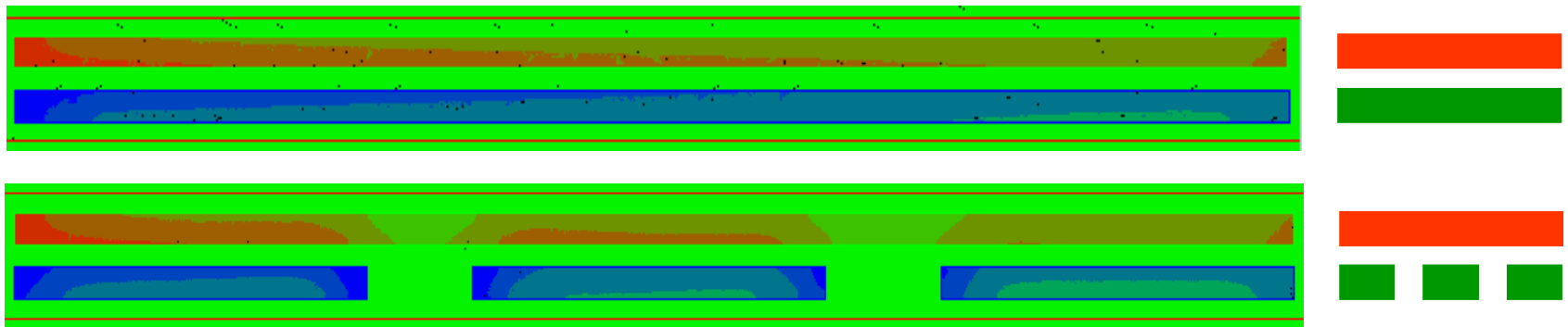
	R (mΩ)	Lleak (nH)
B	3.07	0.59
C	3.43	0.7

Comparison of different winding strategies

Splitting the tracks
Opposite currents tend to come closer

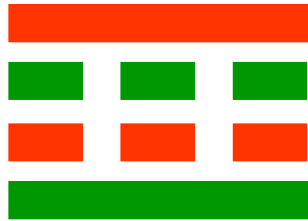


Current density distribution @250kHz



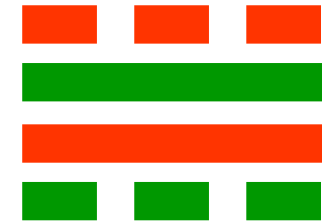
Current density distribution @1MHz

Comparison of different winding strategies



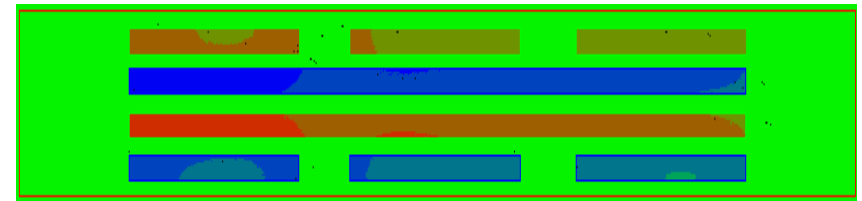
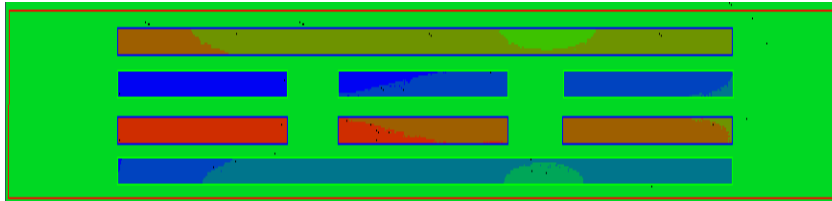
A

	R (mΩ)	Lleak (nH)
A	3.4	0.73
B	3.25	0.58

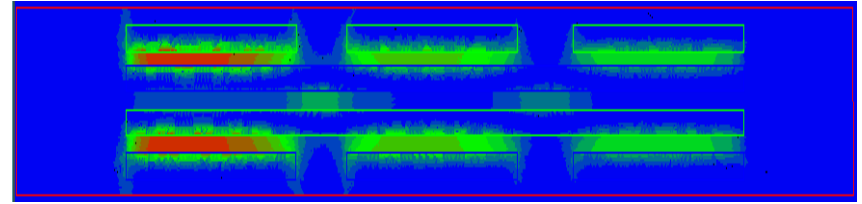
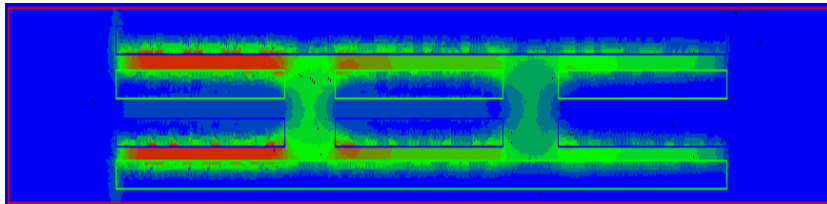


B

Current density Distribution



Magnetic Energy Distribution



@200kHz

Place splitted tracks outside!!

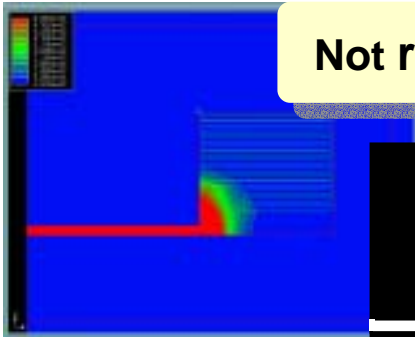
Design guidelines



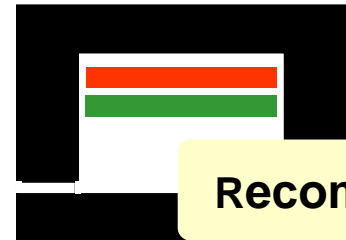
Not recommended



Recommended



Not recommended



Recommended



$<2\delta$ (skin depth)



Lower current density criteria

Application to converters

Charger of capacitors

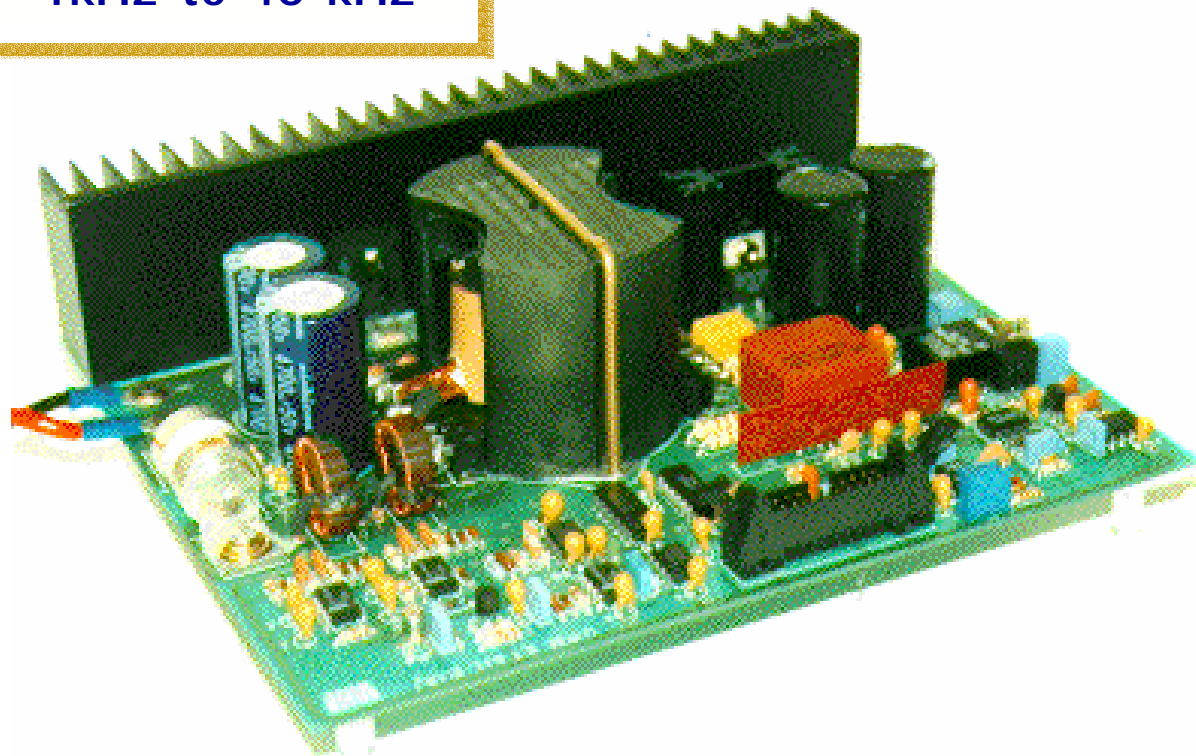
Multiooutput converter

Low profile converter

Flyback converter for capacitor charger

FLYBACK WITH HYSTERETIC CONTROL

Capacitive Load: 0.5 F
Output Voltage: 0 to 340 V
Output Power: up to 1kW
Input Voltage: 16 to 32 V
Switching Frequency: 1kHz to 40 kHz



SCHEMATIC



Flyback converter for capacitor charger

Design of the power transformer

Core: PM62

N27

Windings

Solid wires

Primary 8 x 0.7mm

Secondary 1 x 0.7mm

Turns ratio

Primary: 5

Secondary: 40

Max. Switching frequency: 40 kHz

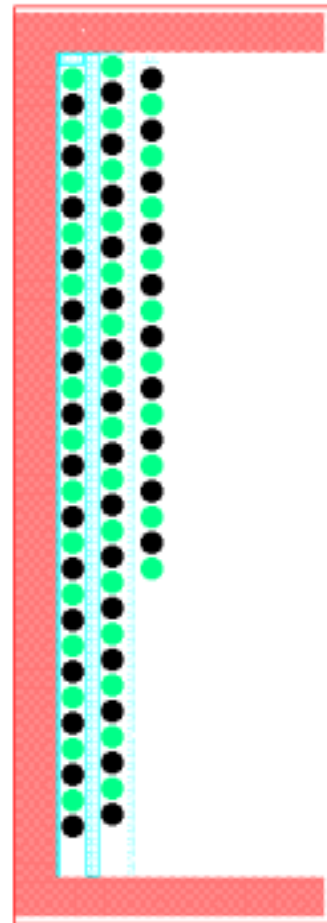
$$L_M = 8\mu\text{H}$$

ΔB

B_{max} 250mT

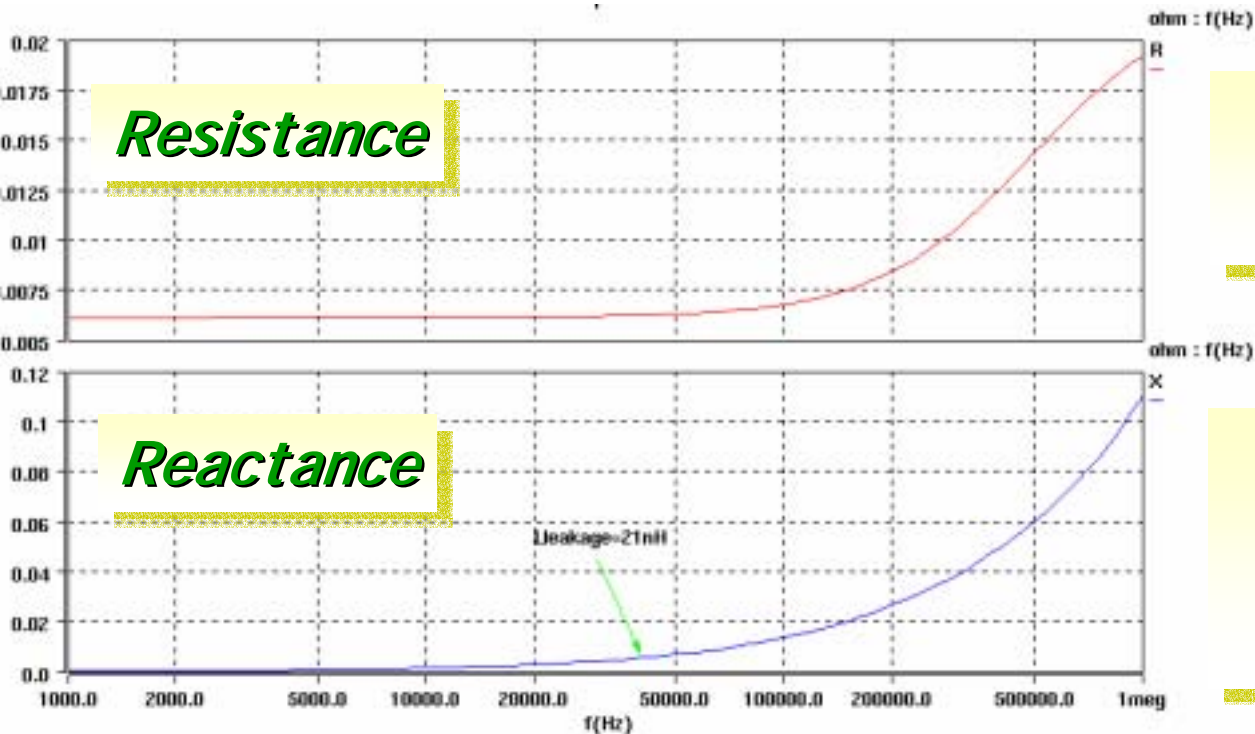
B_{min} 70mT

$I_{\text{rms primary}} = 46\text{A}$



Flyback converter for capacitor charger

Transformer model



Resistance

Reactance

Open circuit test

$$L_m = 8\mu\text{H}$$

Short circuit test

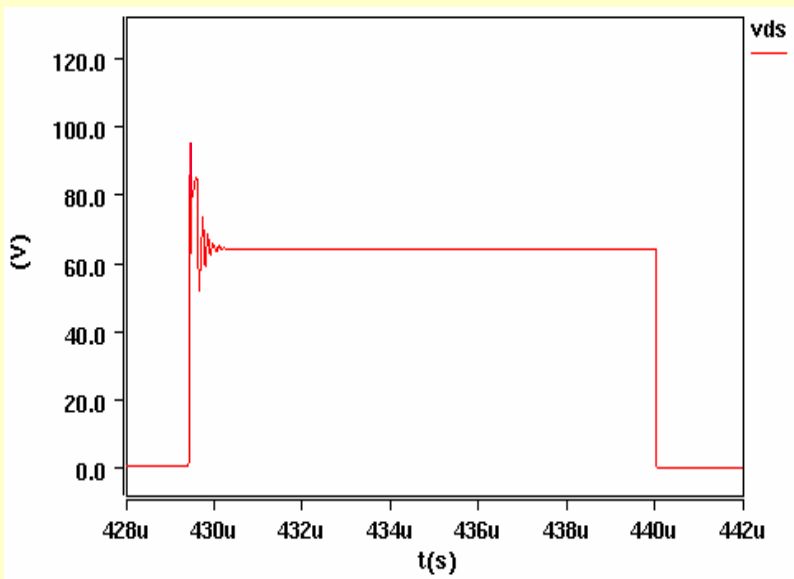
$$L_{\text{leak}} = 21\text{nH} \text{ (40kHz)}$$

$$R_{\text{AC}} = 6\text{m}\Omega \text{ (40kHz)}$$

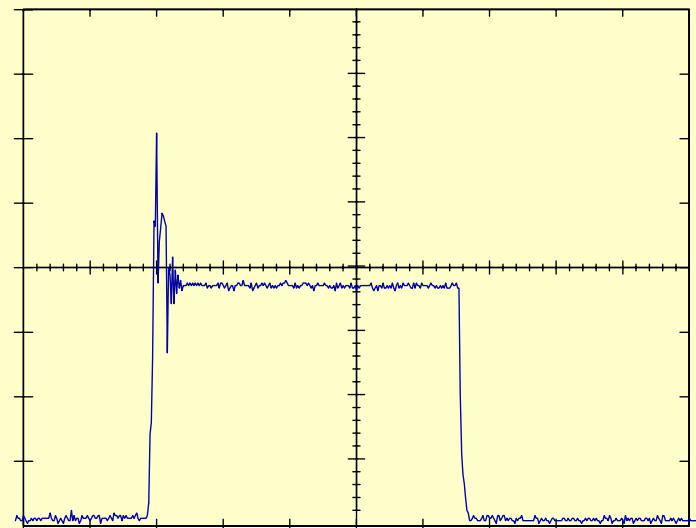
Flyback converter for capacitor charger

Experimental Results

SIMULATION



MEASUREMENT

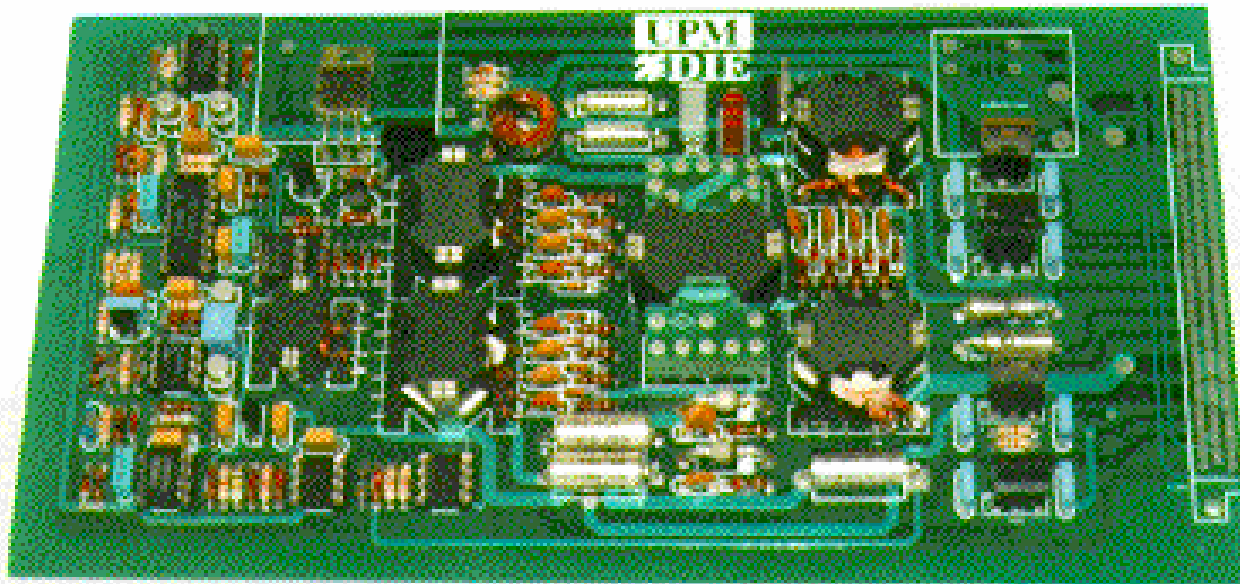
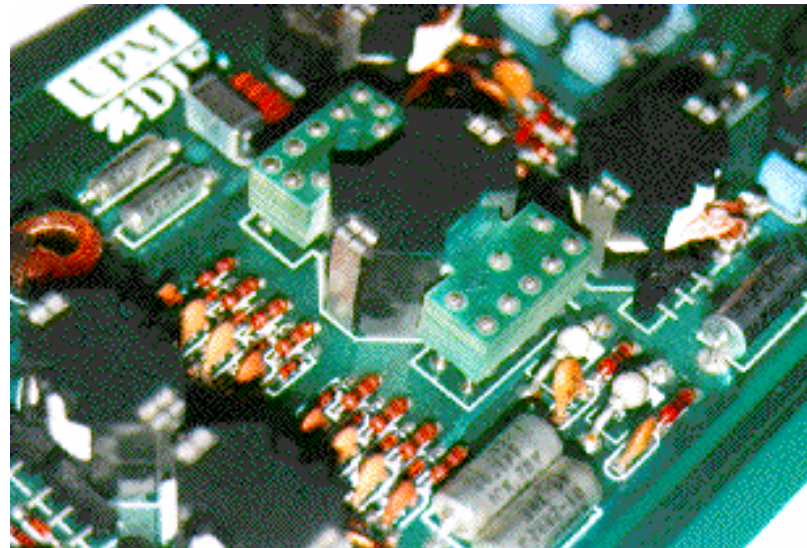


Vds in main switch at nominal conditions ($V_o = 300V$, $I_{ds} = 25-90A$)

Multioutput forward RCD converter

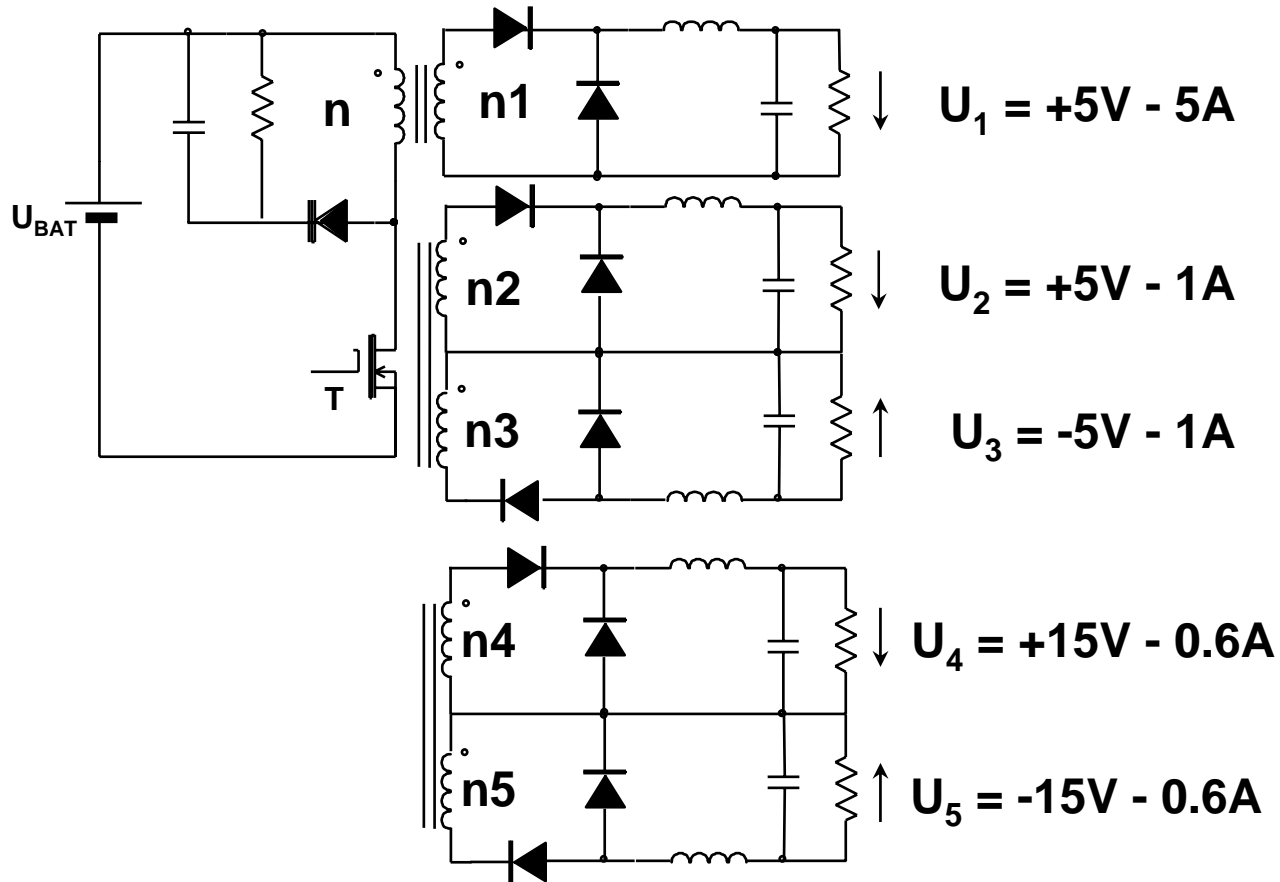
FORWARD RCD

Input voltage: 18 to 32 V
Output Power: 60 W
Switching Frequency: 300 kHz
Output 1: 5 V, 5 A
Outputs 2,3: 5 V, 1 A
Outputs 4,5: 15 V, 0.6 A



Multioutput forward RCD converter

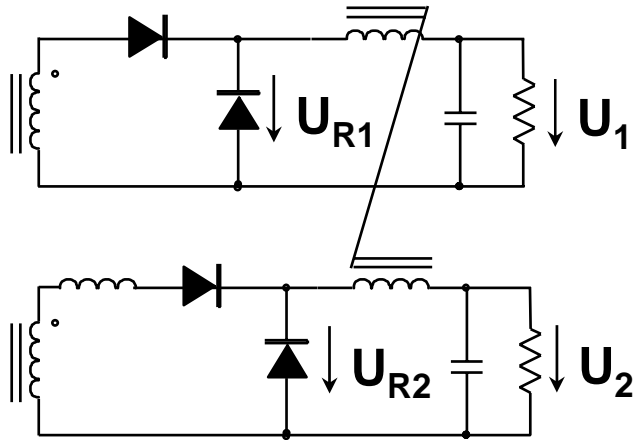
Schematic



WARNING: Transformer is the *heart* of a multi-output converter

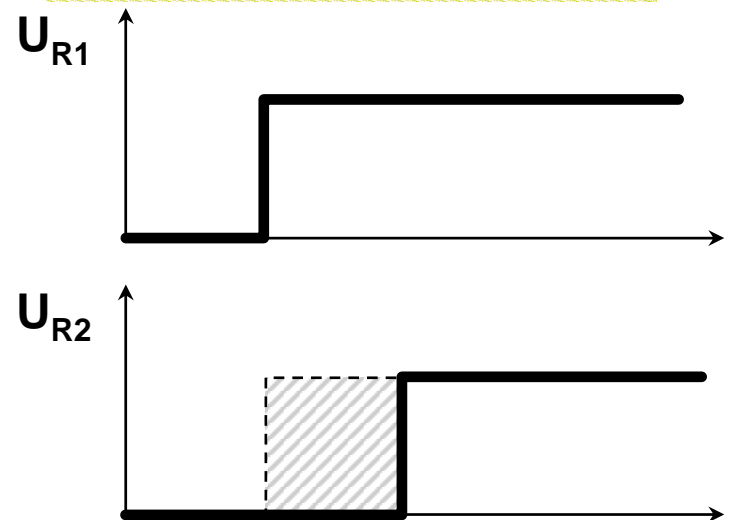
Transformer and output inductors affect to cross regulation

Dynamic cross regulation



Output inductors
(coupled inductors)

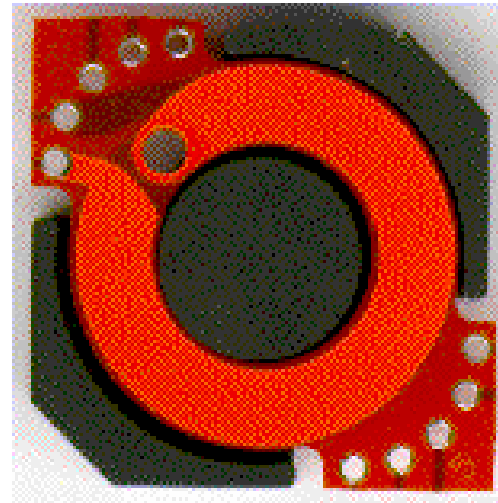
Static cross regulation



Transformer
(leakage between secondaries)
(leakage in primary does not affect to cross regulation)

Technological Characteristics

Copper thickness: 100 μ m
Substrate thickness: 50 μ m
Insulator thickness: 10 μ m



Design of the power transformer

Turns ratio

Primary	3
Secondary 1	2
Secondaries 2, 3	2
Secondaries 4, 5	6

Switching frequency: 300kHz

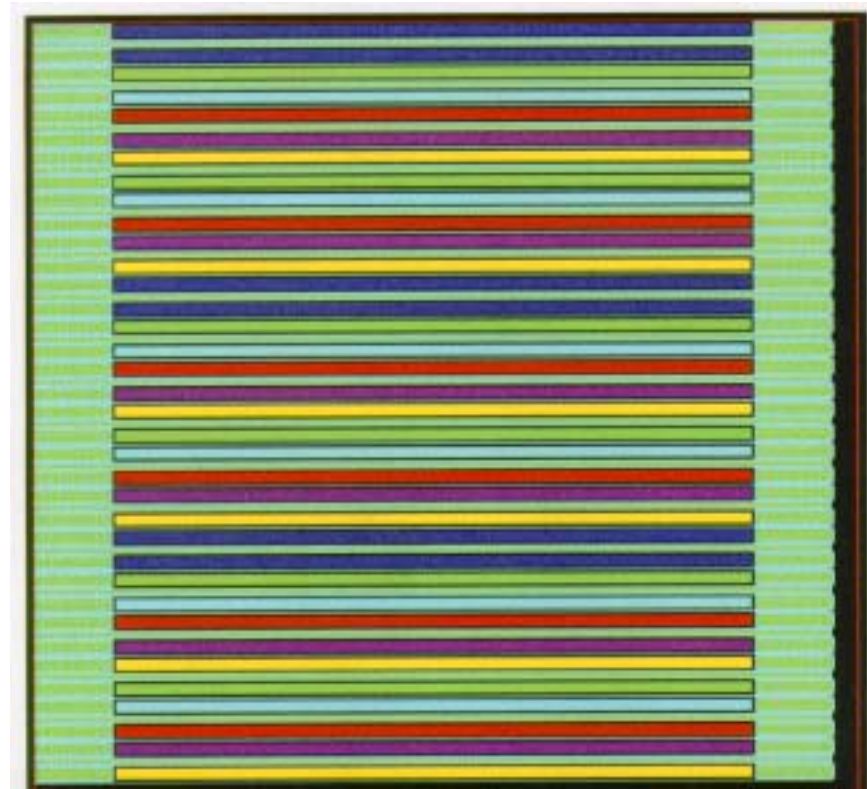


Core: RM10 Low Profile

Material: 3F3

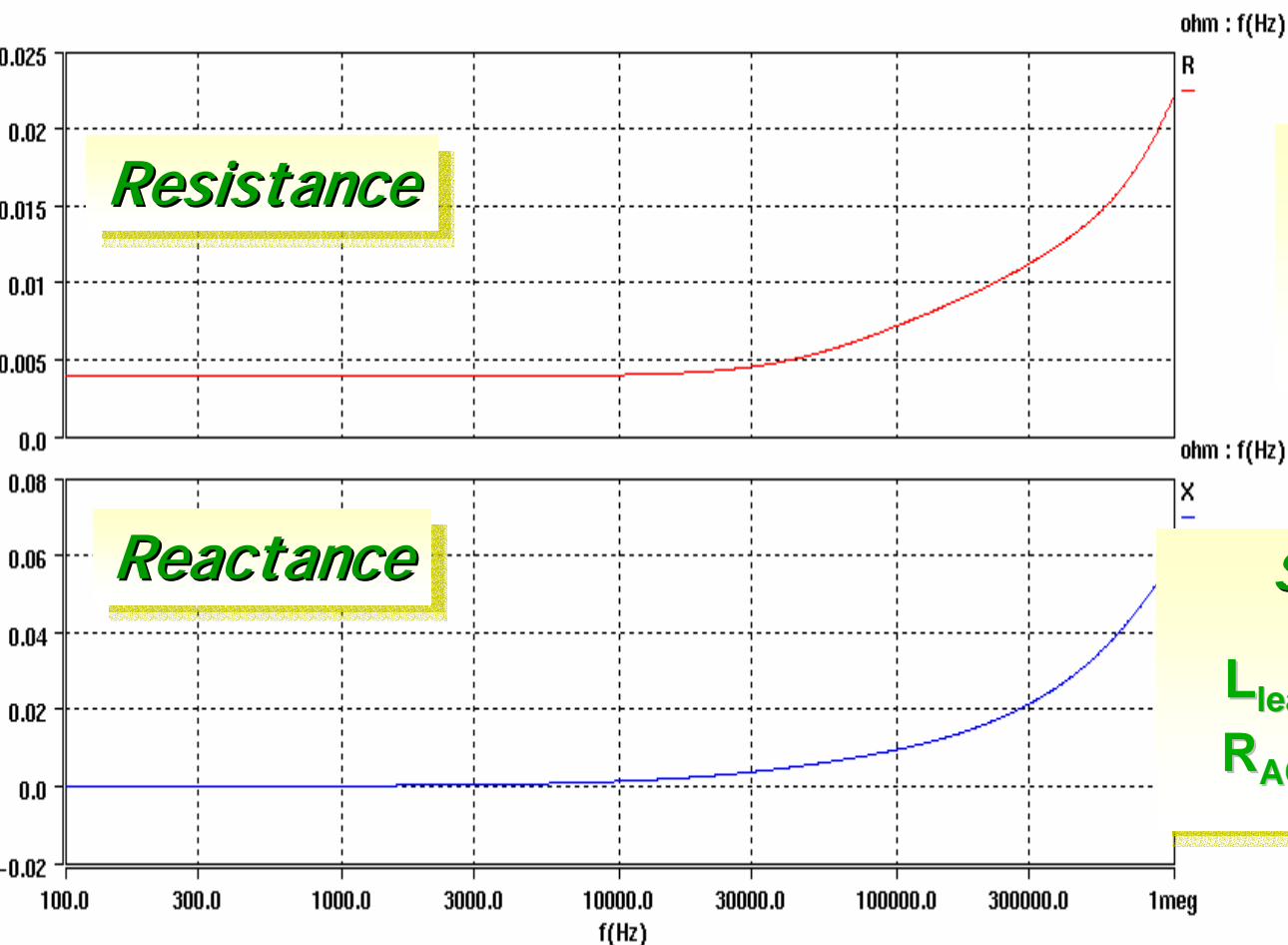
Windings: 36 copper layers

Cross section



Multioutput forward RCD converter

Transformer model



Resistance

Open circuit test

$$L_m = 46 \mu\text{H}$$

Reactance

Short circuit test

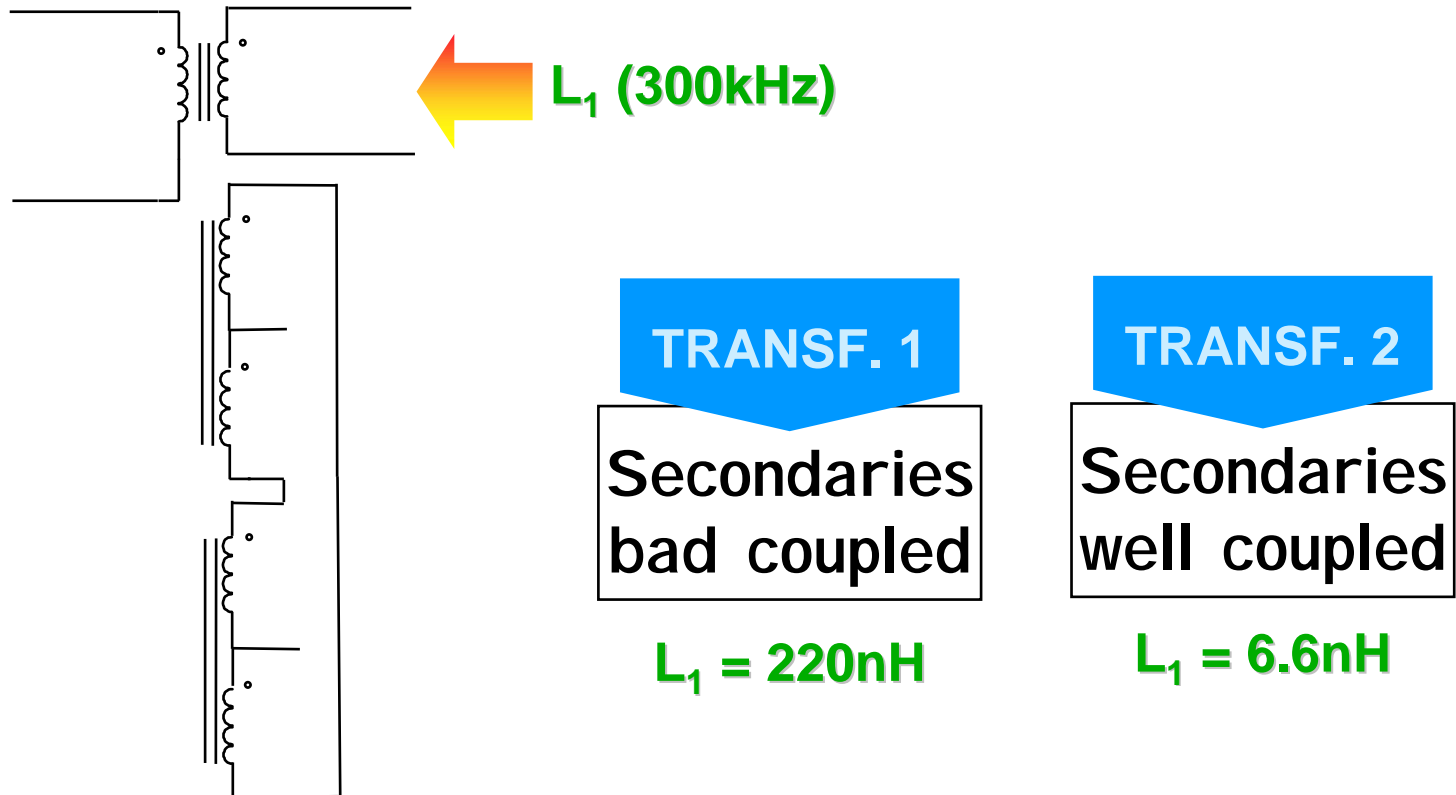
$$L_{\text{leak}} = 11 \text{ nH (300 kHz)}$$

$$R_{\text{AC}} = 11 \text{ m}\Omega \text{ (300 kHz)}$$

Multioutput forward RCD converter

Test of secondaries coupling

2 transformers have been tested



Comparison of the static cross regulation

$\Delta U(\text{mV})$	TRANSFORMER 1	TRANSFORMER 2
U1	0	0
U2	176	106
U3	177	109
U4	673	338
U5	609	291

TEST CONDITION

Output current in main output

$I_1 = 5\text{A}$

$I_1 = 0.5\text{A}$

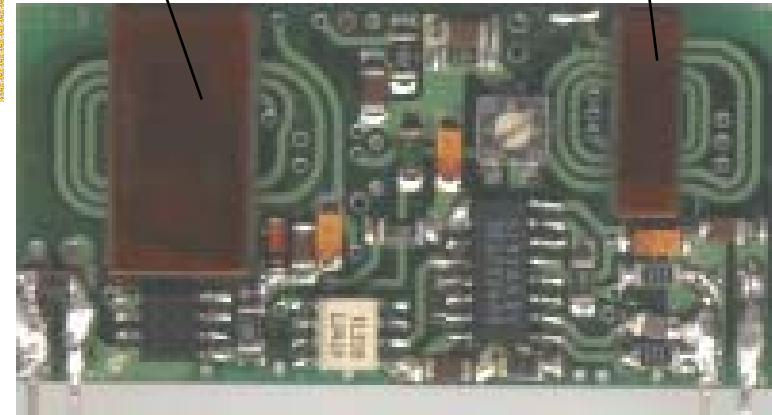
Low profile on board converter (multilayer PCB)

FORWARD WITH RESONANT RESET

Output: 1.5 V / 3 A
Output Power: 5W
Input Voltage: 3 to 6 V
Switching Frequency: 300 kHz
Max. overall efficiency: 85% (82%typ.)

Choke

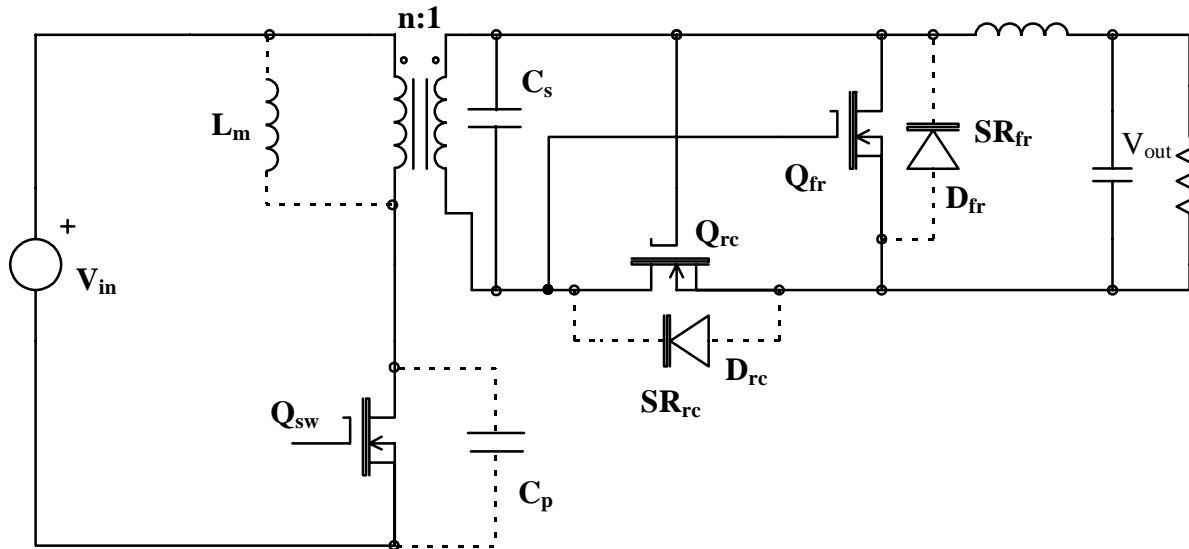
Transformer



GOALS

- ✓ Efficiency and size
- ✓ Magnetic components integrated in a multi-layer PCB

Forward with Resonant Reset



FEATURES

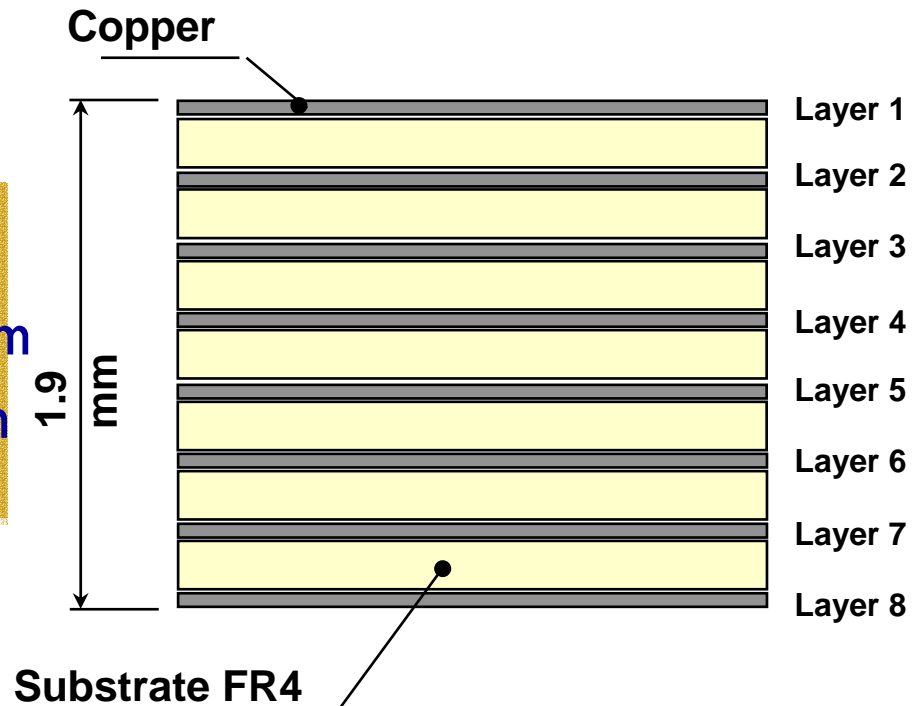
- ✓ Simplicity
- ✓ Self driven synchronous rectification
- ✓ WARNING: Performance depends on parasitics (transformer and semiconductors)

Technological Characteristics

8 layers

Copper thickness: 70 μm

Substrate thickness: 1.9 mm



Overall design is subjected to the PCB characteristics

Design of the power transformer

Turns ratio 4 : 3

Switching frequency: 300 kHz

Resonant freq / Switching freq = 0.85

Parasitic capacitances of the switches



Turns ratio 4 : 3

Core

Planar E core (E 14 / 3.5 / 5)

Plate: PLT 14 / 5 / 1.5 3F3

Windings

1 turn per layer

$n_1 = 4$; $n_2 = 3$

Transformer model

Open circuit analysis



Open circuit test

$$L_m = 19.3 \mu\text{H}$$

Short circuit analysis



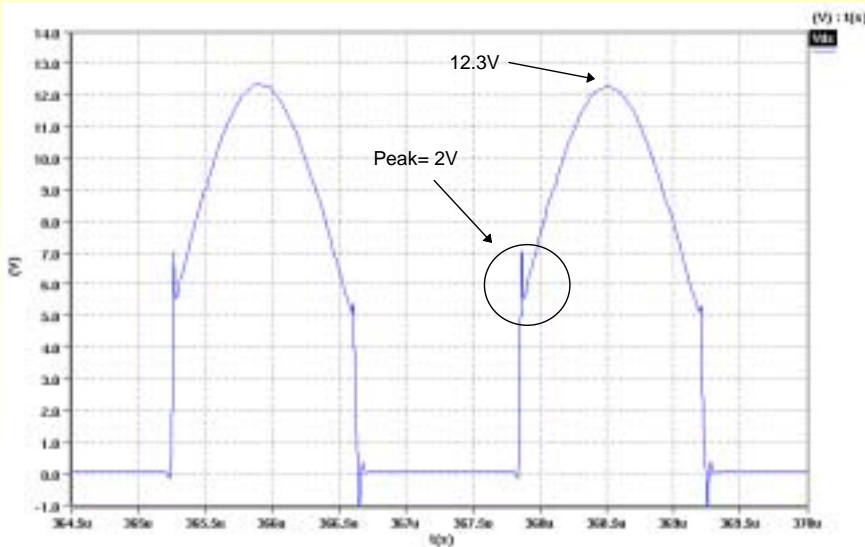
Short circuit test

$$L_{\text{leak}} = 5.2 \text{ nH} \quad (300\text{kHz})$$

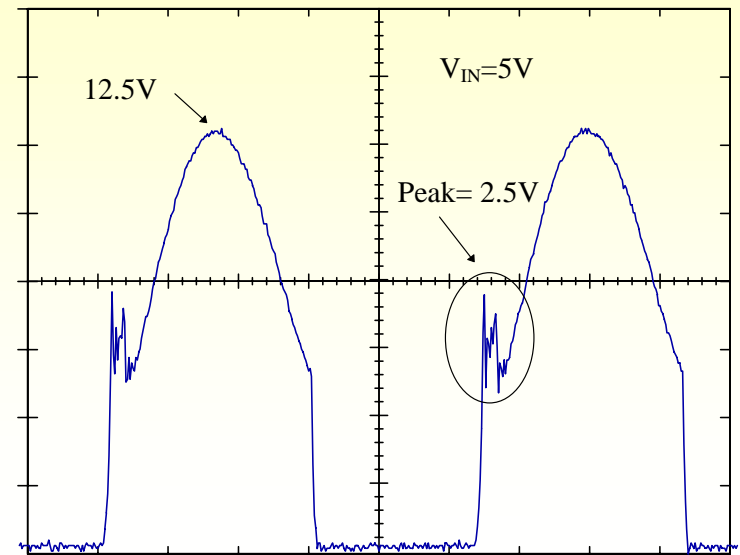
$$R_{\text{AC}} = 15.4 \text{ m}\Omega \quad (300\text{kHz})$$

Experimental Results

SIMULATION



MEASUREMENT



V_{ds} in main switch at nominal conditions ($V_{in}=5V$, $I_o= 3A$)

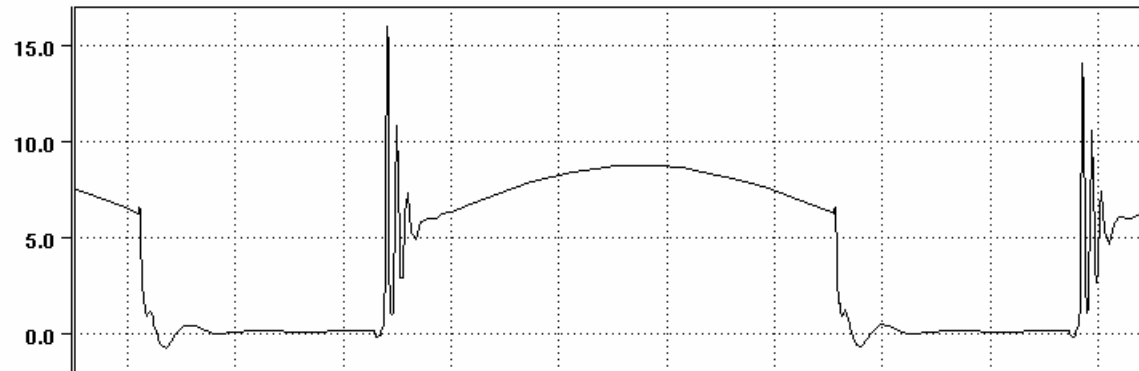
Low profile on board converter (multilayer PCB)

If you just estimate leakage on a thick film transformer

Magic converter. Vds main MOSFET. Vin=5V; Iout=1.5A

(V) : t(s)

Vds classical model



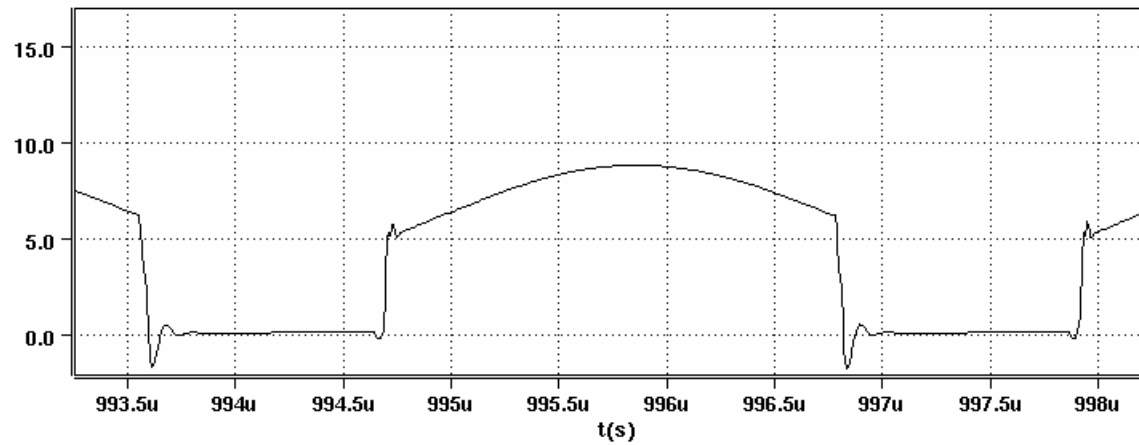
Classical model

$L_m = 30 \mu\text{H}$

$L_{lk} = 30\text{nH}$ (estimated)

(V) : t(s)

Vds UPM-DIE model

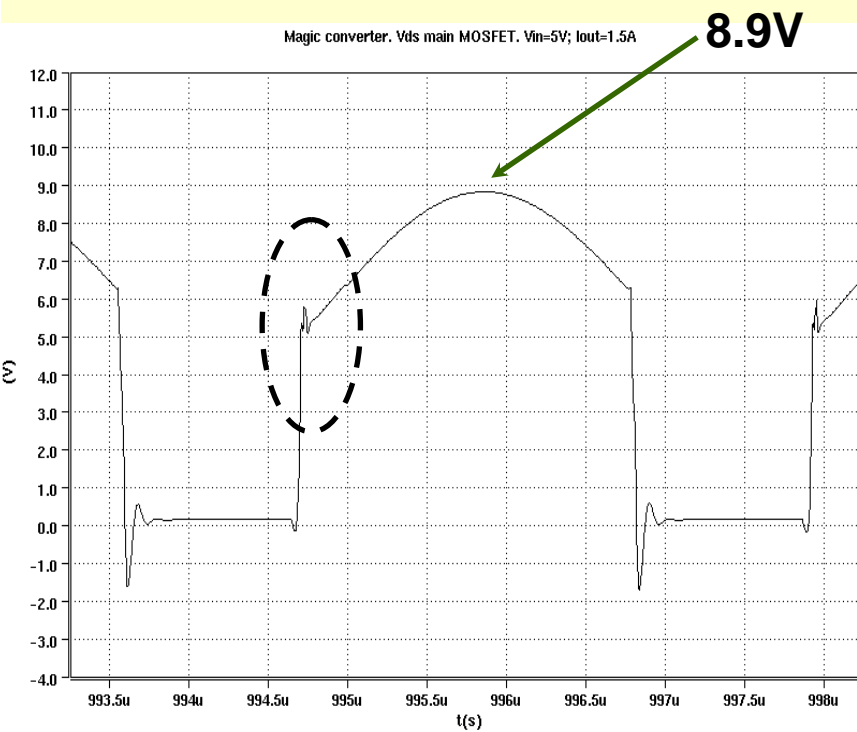


UPM model

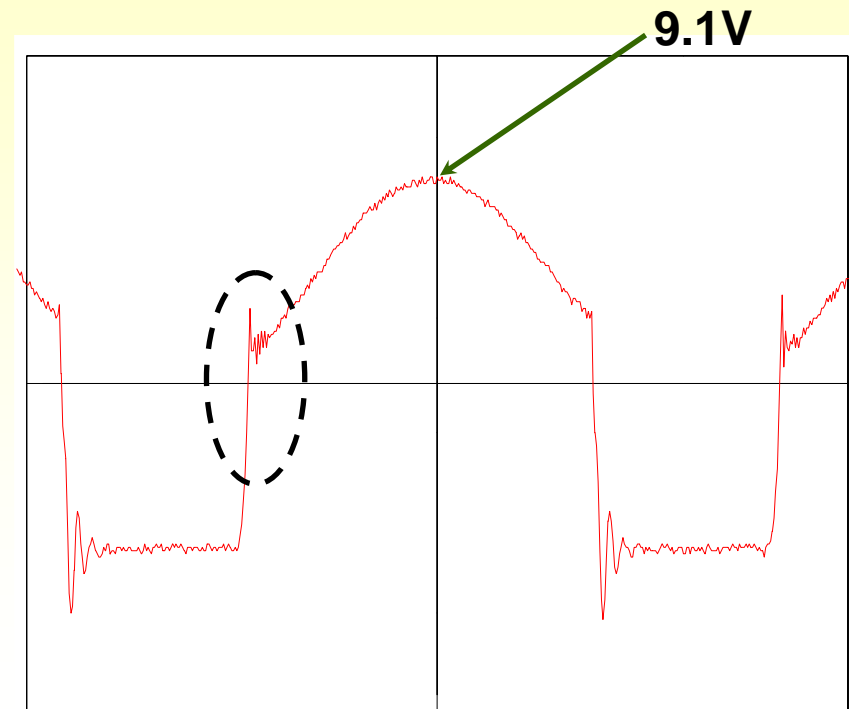
$L_{lk} = 4\text{nH}$

Experimental Results using thick film technology

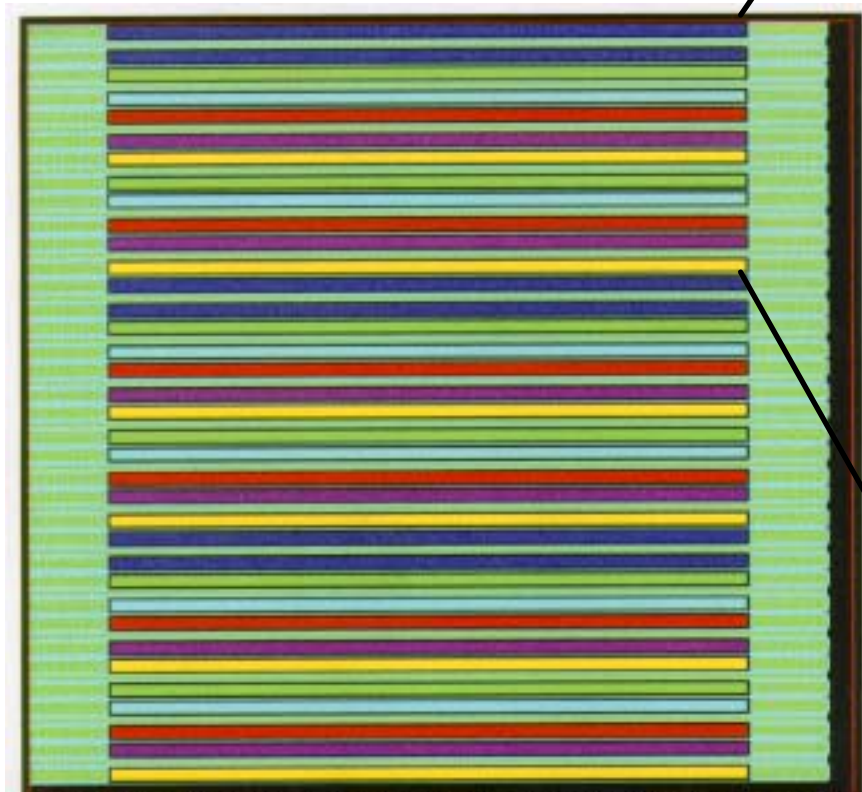
SIMULATION










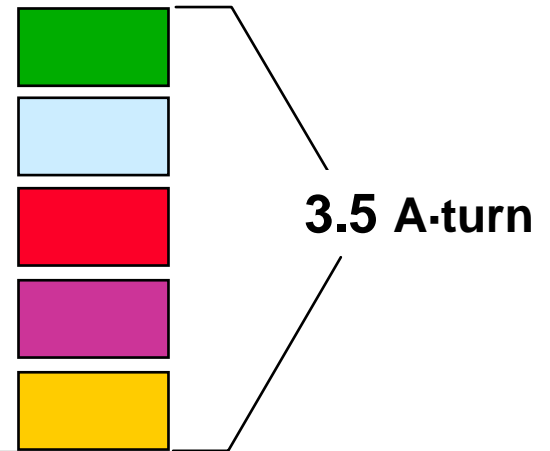
MEASUREMENT



Small value of leakage inductance predicted by the Mod



P		3.5 A-turn
P		3.5 A-turn
Sa		1.7 A-turn
Sb		0.3 A-turn
Sc		0.3 A-turn
Sd		0.6 A-turn
Se		0.6 A-turn

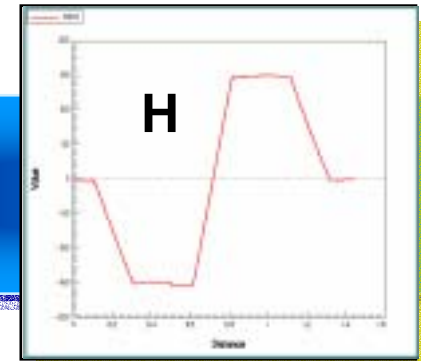


6

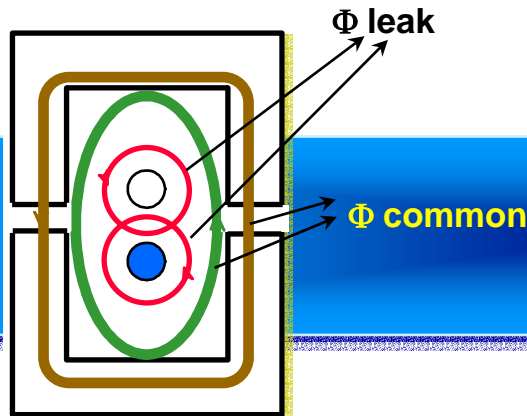
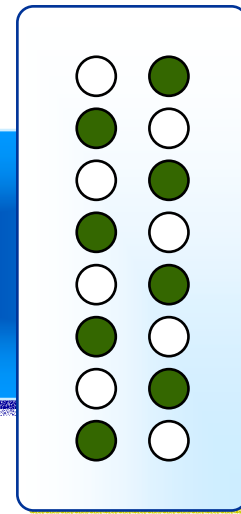
Summary of design guidelines

Interleaving

Reduces	Increases
L_{leak} R_{AC} $C_{\text{intrawinding}}$	$C_{\text{interwinding}}$

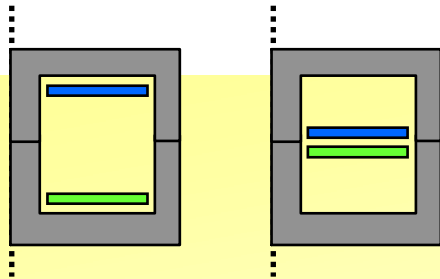


Conductors with opposite current should be placed as close as possible

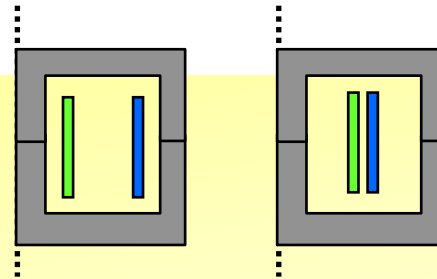


Energy in the air is not necessarily "leakage"

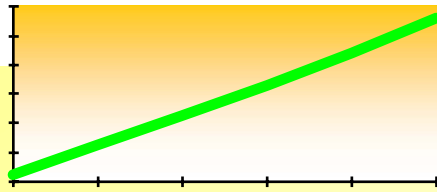
Windings separation



In top-down structures, R_{AC} decreases

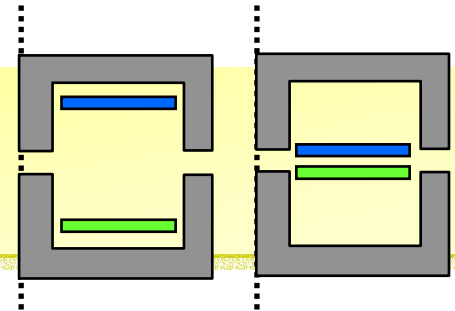


In concentric structures, R_{AC} may increase or decrease



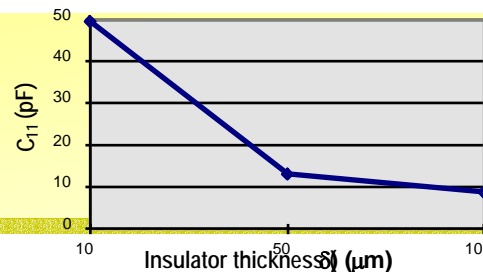
L_{leak} linearly dependent on winding separation

End effect reduced if conductors are far from the core

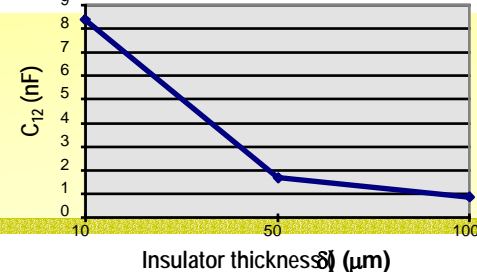


Interwinding and intrawinding capacitance decrease with layer separation

INTRAWINDING CAPACITANCE

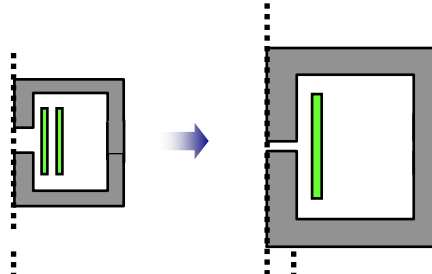


INTERWINDING CAPACITANCE

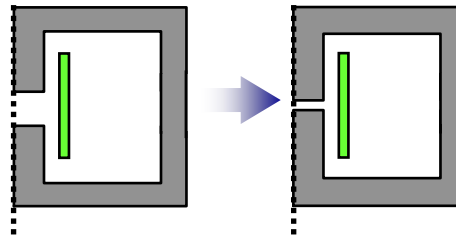


TO REDUCE R_{AC}

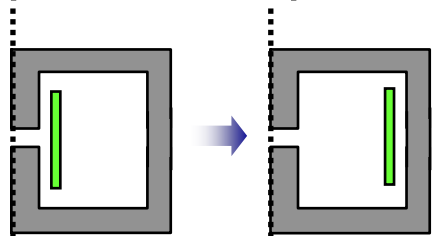
AIR GAP THICKNESS



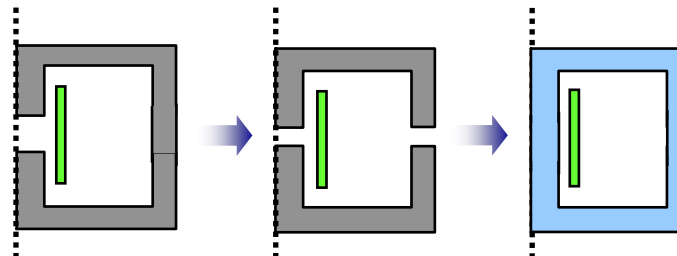
AIR GAP THICKNESS



RELATIVE POSITION
GAP-WINDINGS

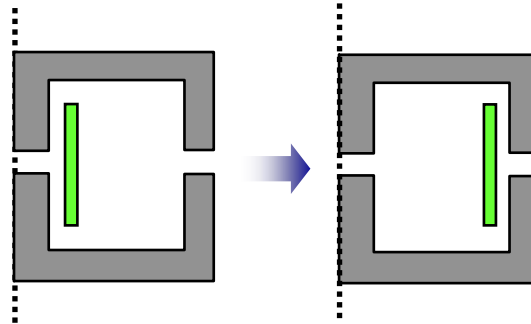


DISTRIBUTED GAP

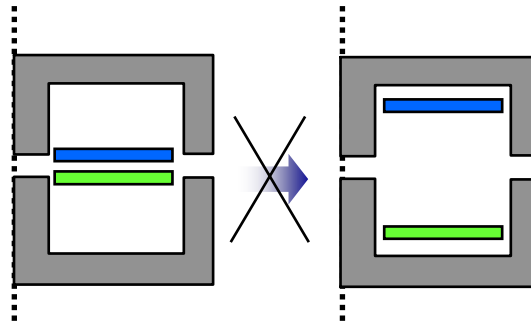


TO REDUCE R_{AC}

CENTER-OUTER LEG



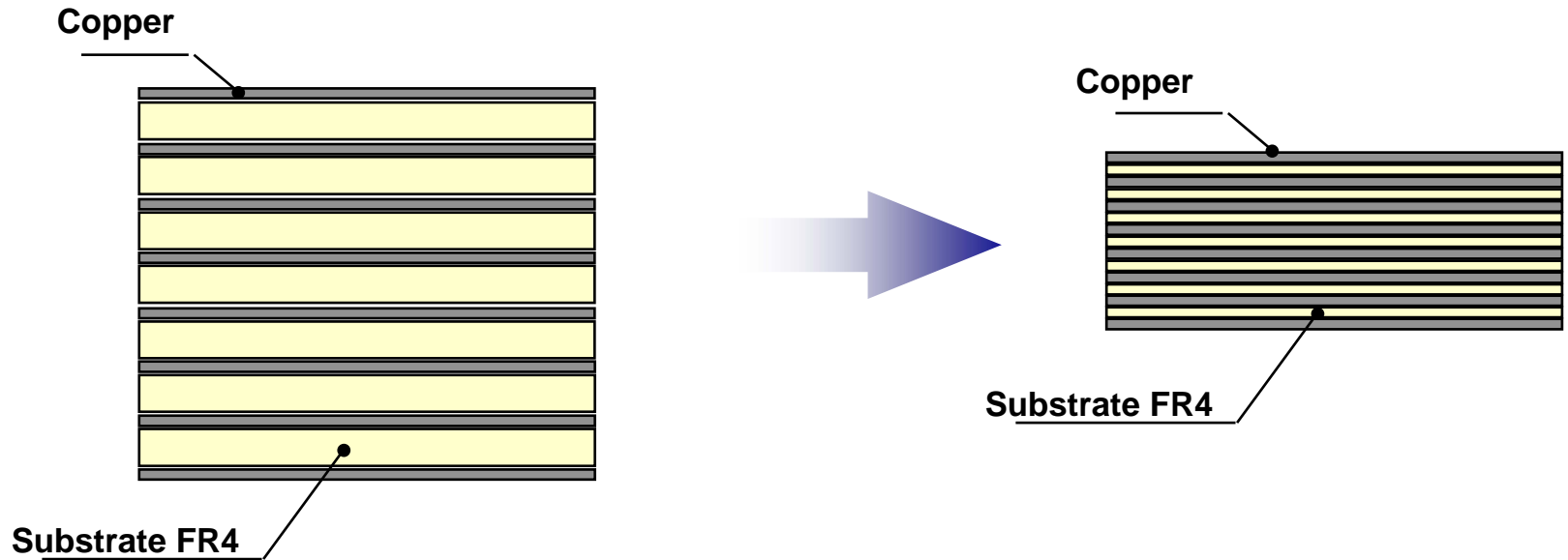
WINDINGS SEPARATION
VS
GAP INFLUENCE



↓ R_{AC}

↑ Leakage inductance

Substrate thickness reduction is limited by technological constraints, but also take into account that...



- ✓ R_{AC} slightly increases, but more blocks can be connected in parallel !!
- ✓ Leakage inductance drastically decreases
- ✓ Capacitance increases
- ✓ Isolation requirements to accomplish regulations

Summary

Modeling:

- It is possible to generate **accurate models** for high frequency magnetic components, based on a **FEA tool** or **analytical expressions**
- All **high frequency and geometry effects** are taken into account
- Valid for **any electrical waveform** (not only sinusoidal)
- Valid for both **multi-winding** transformers and **coupled inductors**
- Valid for **behavioral simulator** and for electrical simulators

Design guidelines:

- **Geometry** equivalent to **performance**
- **Low profile magnetics** and **standard winding construction** techniques are current trends
- Care about **all physical effects** together (Electric energy, Magnetic energy and losses)
- Care about **regulations**